

Lists 04/2005 Edition

sinumerik

SINUMERIK 840D sl/840D/840Di/810D
System Variables

SIEMENS

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SINUMERIK 840D sl /840D/840Di/810D

System Variables

Lists

Gültig für

<i>Control</i>	<i>Software Version</i>
SINUMERIK 840D sl/840DE sl	1.3
SINUMERIK 840D powerline	7.3
SINUMERIK 840DE powerline (Exportvariante)	7.3
SINUMERIK 840Di	2.3
SINUMERIK 840DiE (Exportvariante)	2.3
SINUMERIK 810D powerline	7.3
SINUMERIK 810DE powerline (Exportvariante)	7.3
SINAMIC"	2.3

04.05 Edition

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Printing history

Brief details of this edition and previous editions are listed below.
The status of each edition is shown by the code in the "Remarks" column.

Status code in the "Remarks" column:

- A** New documentation.
- B** Unrevised reprint with new order no.
- C** Revised edition with new status.

Edition	Order No.	Remarks
03.04	6FC5 298 7AE10-0BP0	A
10.04	6FC5 298 7AE10-0BP1	C
04.05	6FC5 298-7AE10-0BP2	C

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Further information is available on the Internet under:
<http://www.siemens.com/motioncontrol>

This publication was produced with FrameMaker V7.0.

Other functions not described in this documentation might be executable in the control. This does not, however, represent an obligation to supply such functions with a new control or when servicing.

We have checked that the contents of this document correspond to the hardware and software described. Nonetheless, differences cannot be ruled out and we cannot therefore guarantee that they are completely identical. The information contained in this manual is reviewed regularly and any necessary changes will be included in the next edition. Suggestions for improvement are welcome at all times.

Preface

Structure of the documentation

The SINUMERIK documentation is organized in three parts:

- General Documentation
- User Documentation
- Manufacturer/Service Documentation

Please contact your local Siemens office for more detailed information about other SINUMERIK 840D sl/840D/840Di/810D publications and publications that apply to all SINUMERIK controls (e.g. universal interface, measuring cycles etc.).

An overview of publications which is updated each month and shows the languages available is provided on the Internet at:

<http://www.siemens.com/motioncontrol>.

Click the menu items in the following order: "Support" à "Technical Documentation" à "Overview of Publications".

The Internet edition of DOConCD - DOConWEB - can be found at:

<http://www.automation.siemens.com/doconweb>

Audience

This documentation is intended for manufacturers of machine tools with SINUMERIK 840D or SINUMERIK 810D with SIMODRIVE 611D or SINAMICS.

Standard Scope

This Programming Guide describes the functionality afforded by standard functions. Extensions or changes made by the machine tool manufacturer are documented by the machine tool manufacturer.

Other functions not described in this documentation might be executable in the control. This does not, however, represent an obligation to supply such functions with a new control or when servicing.

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Objective The List of System Variables manual is intended for programmers of part programs and synchronous actions.

This manual uses the same data source as the relevant software version. A new List of System Variables manual is delivered with the new software versions.

Retrieval aids A table of contents as well as the annex Index have been established.

Safety Guidelines

This manual contains notices you have to observe in order to ensure your personal safety, as well as to prevent damage to property. The notices referring to your personal safety are highlighted in the manual by a safety alert symbol, notices referring to property damage only have no safety alert symbol. These notices shown below are graded according to the degree of danger.

**Danger**

indicates that death or severe personal injury **will** result if proper precautions are not taken.

**Warning**

indicates that death or severe personal injury **may** result if proper precautions are not taken.

**Caution**

with a safety alert symbol, indicates that minor personal injury can result if proper precautions are not taken.

Caution

without a safety alert symbol, indicates that property damage can result if proper precautions are not taken.

Notice

indicates that an unintended result or situation can occur if the corresponding information is not taken into account.

If more than one degree of danger is present, the warning notice representing the highest degree of danger will be used. A notice warning of injury to persons with a safety alert symbol may also include a warning relating to property damage.

Qualified Personnel

The device/system may only be set up and used in conjunction with this documentation. Commissioning and operation of a device/system may only be performed by qualified personnel. Within the context of the safety notes in this documentation qualified persons are defined as persons who are authorized to commission, ground and label devices, systems and circuits in accordance with established safety practices and standards.

Prescribed Usage

Note the following:



Warning

This device may only be used for the applications described in the catalog or the technical description and only in connection with devices or components from other manufacturers which have been approved or recommended by Siemens. Correct, reliable operation of the product requires proper transport, storage, positioning and assembly as well as careful operation and maintenance.



Note

This symbol appears in the documentation whenever the manufacturer can modify the described function. Please note the information provided by the manufacturer.



Ordering data supplement

This symbol appears in this documentation whenever a described function is not contained in the standard scope of supply and has to be ordered as an option.

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1.1 List of system variables

Properties of system variables

The following data are entered in the system variables tables:

1st line: Data type, identifier possibly with array limit 1, array limit 2, short name, References

2nd line: Description

3rd line: Description of the array limits [Index 1, Index 2]

4th line: Axes, NCK version number of the introduction of system variables

5th line: Unit, minimum value, maximum value

6th line: Headers of properties including the following:

- Prep: being updated during preprocessing
- Main run: being updated during main run
- PR-Stop: Stop of preprocessing
- MR-Sync: Main run synchronization
- PP: can be used in the part program
- SA: can be used in synchronized actions
- OPI: can be accessed via operator panel interface
- OEM: can be accessed by OEM compile cycles
- Level: Access rights required to write system variables

7th line: read: Properties for reading; possible if X is set

8th line: write: Properties for writing; possible if X is set

9th line: Headers of properties including the following:

- Attributes
- Global (multi-channel)
- Block search
- Link

10th line: Attribute values

Note: The maximum length for system variables of Type STRING is 400.

1.1 List of system variables

1.1.1 Template of system variables

Type	Identifier[array limit 1,array limit 2]					Short name			Cross. R.:	References
Description: Description lines ...										
Description of array limits: Description of array limit 1 Description of array limit 2										
Axes:	Axis type 1 Axis type 2, ...					NCK Version:		Version		
Unit:	Unit	min:	Minimum value			max:	Maximum value			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X	X		X	X	X	X	Access level
Attributes:	Global	Search run				Link				
	X	Block search condition				Link condition				

1.1.2 R-Parameter

DOUBLE	R[n]					Arithmetic variable of type Real			Cross. R.:	
Description: Array variable Rn or R[n] is an arithmetic variable of type Real and is user-definable. Rn or R[n] is used to program the variable in the part program. \$Rn or \$R[n] is used to program the variable in a synchronized action. The arithmetic variables are stored in SRAM and can be read in and out using the data backup feature.										
Description of array limits: The maximum number of R variables is defined in \$MC_MM_NUM_R_PARAM.										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:	Global	Search run				Link				
		According to part program				No restriction				

1.1.3 Channel-specific synchronized action variables

INT	\$AC_MARKER[n]					User array variable of type Integer			Cross. R.:	
Description: Array variable \$AC_MARKER[n] is used to store application-related integer arithmetic results. The variable is stored in DRAM or in SRAM depending on \$MC_MM_BUFFERED_AC_MARKER. The array elements of the variable in volatile memory (DRAM) are set to 0 on a Reset.										
Description of array limits: The dimension is defined in MD \$MC_MM_NUM_AC_MARKER.										
Axes:					NCK Version:			43.02.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global	Search run			Link				
			not classified			No restriction				

INT	\$AC_SYSTEM_MARKER[n]					System array variable of type Integer			Cross. R.:	
Description: Array variable \$AC_SYSTEM_MARKER[n] is used to store application-related integer arithmetic results. The variable is reserved for SIEMENS applications. The variable is stored in DRAM or in SRAM depending on \$MC_MM_BUFFERED_AC_MARKER. The array elements of the variable in volatile memory (DRAM) are set to 0 on a Reset.										
Description of array limits: The dimension is defined in MD \$MC_MM_NUM_AC_SYSTEM_MARKER.										
Axes:					NCK Version:			46.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global	Search run			Link				
			not classified			No restriction				

DOUBLE	\$AC_PARAM[n]					User array variable of type Real			Cross. R.:	
Description: Array variable \$AC_PARAM[n] is used to store application-related Real arithmetic results. The variable is stored in DRAM or in SRAM depending on \$MC_MM_BUFFERED_AC_PARAM. The array elements of the variable in volatile memory (DRAM) are set to 0 on a Reset.										
Description of array limits: The dimension is defined in MD \$MC_MM_NUM_AC_PARAM.										
Axes:					NCK Version:			43.02.00		
Unit:		-	min:		DBL_MIN			max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global	Search run			Link				
			not classified			No restriction				

1.1 List of system variables

DOUBLE	\$AC_SYSTEM_PARAM[n]					System array variable of type Real			Cross. R.:		
Description:											
Array variable \$AC_SYSTEM_PARAM[n] is used to store application-related Real arithmetic results. The variable is reserved for SIEMENS applications.											
The variable is stored in DRAM or in SRAM depending on \$MC_MM_BUFFERED_AC_PARAM. The array elements of the variable in volatile memory (DRAM) are set to 0 on a Reset.											
Description of array limits:											
The dimension is defined in MD \$MC_MM_NUM_AC_SYSTEM_PARAM.											
Axes:					NCK Version:			46.00.00			
Unit:		-		min:			DBL_MIN		max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X	X			X	X		X	7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

1.1.4 Frames

FRAME	\$P_UIFR[n]					Settable data management frames			Cross. R.:		
Description:											
Array variable \$P_UIFR[n] is used to program settable data management frames. G500, G54 .. G599 can be used to activate the corresponding data management frame. The data management frames are stored in SRAM and can be read in and out using the data backup feature.											
Description of array limits:											
\$MC_MM_NUM_USER_FRAMES is used to program the number of settable frames.											
0: G500											
1: G54											
2: G55											
3: G56											
4: G57											
5: G505											
6: G506											
..											
99: G599											
Axes:					NCK Version:			06.00.00			
Unit:		-		min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

FRAME	\$P_CHBFR[n]					Channel-specific basic frames in the data management system			Cross. R.:	
Description:										
Array variable \$P_CHBFR[n] is used to program channel-specific basic frames in the data management system. G500, G54 .. G599 can be used to activate the data management frames. All active basic frames are chained together to produce the overall basic frame \$P_ACTBFRAME. The data management frames are stored in SRAM and can be read in and out using the data backup feature.										
Description of array limits:										
\$MCM_NUM_BASE_FRAMES is used to program the number of channel basic frames.										
Axes:							NCK Version:		16.00.00	
Unit:		-	min:				max:			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global Search run					Link			
		not classified					No restriction			

FRAME	\$P_SETFR					Data management frame for preset actual value memory			Cross. R.:	
Description:										
Variable \$P_SETFR is used to program the system frame in the data management system for preset actual value memory and scratching. This frame should only be manipulated and activated by the system function. The data management frames are stored in SRAM and can be read in and out using the data backup feature.										
On a Reset, the system frame can be cleared by configuring Bit 0 in \$MCM_CHSFRAME_RESET_CLEAR_MASK.										
Axes:		Geometry axis Channel axis Machine axis Spindle					NCK Version:		41.00.00	
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global Search run					Link			
		not classified					No restriction			

1.1 List of system variables

FRAME	\$P_EXTFR					Data management frame for external frame	Cross. R.:			
Description:										
Variable \$P_EXTFR is used to program the system frame in the data management system for the external work offset. This frame is activated by the PLC. The data management frames are stored in SRAM and can be read in and out using the data backup feature.										
On a Reset, the system frame can be cleared by configuring Bit 1 in \$MC_CHSFRAME_RESET_CLEAR_MASK.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	41.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_PARTFR					Data management frame for TCARR and PAROT	Cross. R.:			
Description:										
Variable \$P_PARTFR is used to program the system frame in the data management system for TCARR and PAROT. This frame should only be manipulated and activated by the system function. The data management frames are stored in SRAM and can be read in and out using the data backup feature.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	41.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_TOOLFR					Data management frame for TOROT and TOFRAME			Cross. R.:	
Description: Variable \$P_TOOLFR is used to program the system frame in the data management system for TOROT and TOFRAME. This frame should only be manipulated and activated by the system function. The data management frames are stored in SRAM and can be read in and out using the data backup feature.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	41.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_WPFR					Data management frame for workpiece			Cross. R.:	
Description: Variable \$P_WPFR is used to program the system frame in the data management system for workpiece reference points. The data management frames are stored in SRAM and can be read in and out using the data backup feature. On a Reset, the system frame can be cleared by configuring Bit 4 in \$MC_CHSFRAME_RESET_CLEAR_MASK.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	44.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_CYCFR					Data management frame for cycles	Cross. R.:			
Description:										
Variable \$P_CYCFR is used to program the system frame in the data management system for cycles. This frame should only be manipulated and activated by cycles. The data management frames are stored in SRAM and can be read in and out using the data backup feature. On a Reset, the system frame can be cleared by configuring Bit 5 in \$MC_CHSFRAME_RESET_CLEAR_MASK.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	44.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_TRAFR					Data management frame for transformations	Cross. R.:			
Description:										
Variable \$P_TRAFR is used to program the system frame in the data management system for transformations. This frame should only be manipulated and activated by the system function. The data management frames are stored in SRAM and can be read in and out using the data backup feature.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	50.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR[n]					Global basic frames in the data management system			Cross. R.:	
Description: Array variable \$P_NCBFR[n] is used to program global basic frames in the data management system. G500, G54 .. G599 can be used to activate the data management frames. All active basic frames are chained together to produce the overall basic frame \$P_ACTBFRAME. The data management frames are stored in SRAM and can be read in and out using the data backup feature.										
Description of array limits: \$MN_MM_NUM_GLOBAL_BASE_FRAMES is used to program the number of NCU basic frames.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00		
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_UBFR					1st basic frame in the data management system			Cross. R.:	
Description: Variable \$P_UBFR is used to program the 1st basic frame in the data management system. G500, G54 .. G599 can be used to activate the corresponding data management frame. The data management frames are stored in SRAM and can be read in and out using the data backup feature. \$P_UBFR is equivalent to \$P_CHBFR[0].										
Application: \$P_UBFR = ctrans(x,10) : crot(z,45) \$P_UBFR[y,tr] = 5										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_SETFRAME					Active system frame for preset actual value memory	Cross. R.:			
Description: Variable \$P_SETFRAME is used to program the active system frame for preset actual value memory and scratching. On a Reset, the activation of the system frame depends on the following machine data: Bit0 in \$MC_RESET_MODE_MASK Bit0 in \$MC_CHSFRAME_RESET_MASK										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:	41.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_EXTFRAME					Active system frame for external frame	Cross. R.:			
Description: Variable \$P_EXTFRAME is used to program the active system frame for the external work offset. On a Reset, the activation of the system frame depends on the following machine data: Bit0 in \$MC_RESET_MODE_MASK Bit1 in \$MC_CHSFRAME_RESET_MASK										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:	41.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_PARTFRAME					Active system frame for toolholder		Cross. R.:		
Description:										
Variable \$P_PARTFRAME determines the active system frame for TCARR and PAROT. On a Reset, the activation of the system frame depends on the following machine data: Bit0 in \$MC_RESET_MODE_MASK \$MC_GCODE_RESET_MODE[51] \$MC_GCODE_RESET_VALUES[51]										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		41.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_TOOLFRAME					Active system frame for TOROT		Cross. R.:		
Description:										
Variable \$P_TOOLFRAME determines the active system frame for TOROT and TOFRAME. On a Reset, the activation of the system frame depends on the following machine data: Bit0 in \$MC_RESET_MODE_MASK \$MC_GCODE_RESET_MODE[52] \$MC_GCODE_RESET_VALUES[52]										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		41.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_WPFRAME					Active system frame for the workpiece			Cross. R.:	
Description:										
Variable \$P_WPFRAME is used to program the active system frame for workpiece reference points. On a Reset, the activation of the system frame depends on the following machine data: Bit0 in \$MC_RESET_MODE_MASK Bit4 in \$MC_CHSFRAME_RESET_MASK										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		44.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CYCFRAME					Active system frame for cycles			Cross. R.:	
Description:										
Variable \$P_CYCFRAME is used to program the active system frame for cycles. On a Reset, the activation of the system frame depends on the following machine data: Bit0 in \$MC_RESET_MODE_MASK Bit5 in \$MC_CHSFRAME_RESET_MASK										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		44.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_TRAFRAME					Active system frame for transformations			Cross. R.:	
Description: Variable \$P_TRAFRAME is used to program the active system frame for transformations. This system frame is configured as follows when a transformation is selected with TRANSMIT or TRACYL: \$MN_FRAME_GEOAX_CHANGE_MODE = 1 oder 2 \$MC_TRANSMIT_ROT_AX_FRAME_1 = 2 \$MC_TRANSMIT_ROT_AX_FRAME_2 = 2 \$MC_TRACYL_ROT_AX_FRAME_1 = 2 \$MC_TRACYL_ROT_AX_FRAME_2 = 2										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		50.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME[n]					Active basic frame in channel			Cross. R.:	
Description: Array variable \$P_CHBFRAME[n] is used to program the nth active basic frame in the channel. On a Reset, the activation of the basic frame depends on the following machine data: Bit0 and Bit14 in \$MC_RESET_MODE_MASK \$MC_CHBFRAME_RESET_MASK										
Description of array limits: The dimension is defined in \$MC_MM_NUM_BASE_FRAMES.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_NCBFRAME[n]					Active global basic frame			Cross. R.:	
Description:										
Array variable \$P_NCBFRAME[n] is used to program the nth active global basic frame. On a Reset, the activation of the basic frame depends on the following machine data: Bit0 and Bit14 in \$MC_RESET_MODE_MASK \$MN_NCBFRAME_RESET_MASK										
Description of array limits:										
The dimension is defined in \$MN_MM_NUM_GLOBAL_BASE_FRAMES.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_ACTBFRAME					Active overall basic frame			Cross. R.:	
Description:										
Variable \$P_ACTBFRAME determines the active chained overall basic frame. This frame is produced by chaining together all valid (see \$P_NCBFRMASK) global basic frames and all valid (see \$P_CHBFRMASK) basic frames in the channel. The overall basic frame is always recalculated when a basic frame is activated. On a Reset, the activation of the basic frames depend on the following machine data: Bit0 and Bit14 in \$MC_RESET_MODE_MASK \$MN_NCBFRAME_RESET_MASK \$MC_CHBFRAME_RESET_MASK										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_BFRAME					1. active basic frame in channel			Cross. R.:	
Description: Variable \$P_BFRAME is used to program the 1st active basic frame in the channel. The variable is equivalent to \$P_CHBFRAME[0]. On a Reset, the activation of the basic frame depends on the following machine data: Bit0 and Bit14 in \$MC_RESET_MODE_MASK \$MC_CHBFRAME_RESET_MASK										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_IFFRAME					Active settable frame			Cross. R.:	
Description: Variable \$P_IFFRAME is used to program the active settable frame. A settable data management frame \$P_UIFR[n] becomes the active settable frame on execution of G500, G54 to G599. On a Reset, the activation of the settable frame depends on the following machine data: Bit0 in \$MC_RESET_MODE_MASK \$MC_GCODE_RESET_MODE[7] \$MC_GCODE_RESET_VALUES[7]										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_PFRAME					Programmable frame			Cross. R.:	
Description:										
Variable \$P_PFRAME is used to program the active programmable frame.										
The programmable frame is retained on a Reset when the following setting is configured:										
\$MC_PFRAME_RESET_MODE = 1										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_ACTFRAME					Active overall frame			Cross. R.:	
Description:										
Variable \$P_ACTFRAME determines the active chained overall frame. The active overall frame is calculated using the following formula:										
$\$P_ACTFRAME = \$P_PARTFRAME : \$P_SETFRAME : \$P_EXTFRAME : \$P_ACTBFRAME :$										
$\$P_IFRAME : \$P_TOOLFRAME : \$P_WPFRAME : \$P_TRAFRAME : \$P_PFRAME : \$P_CYCFRAME$										
The overall frame is recalculated each time a frame belonging to the frame chain is activated and on a Reset.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		06.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_UIFRNUM					Number of active settable frames		Cross. R.:			
Description:											
Variable \$P_UIFRNUM is used to determine the number of the active settable frame. A settable data management frame \$P_UIFR[n] becomes the active settable frame on execution of G500, G54 to G599.											
G500: \$P_UIFRNUM = 0											
G54: \$P_UIFRNUM = 1											
G599: \$P_UIFRNUM = 99											
On a Reset, the activation of the settable frame depends on the following machine data:											
Bit0 in \$MC_RESET_MODE_MASK											
\$MC_GCODE_RESET_MODE[7]											
\$MC_GCODE_RESET_VALUES[7]											
Axes:							NCK Version:		06.00.00		
Unit:		-		min:		0		max:		99	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:		Global					Search run		Link		
							not classified		No restriction		

INT	\$P_NCBFRMASK					Global basic frame mask		Cross. R.:			
Description:											
Variable \$P_NCBFRMASK is used to define the NCU-global basic frame included in the calculation of the overall basic frame \$P_ACTBFRAME. The variable is implemented in the form of a bit mask in which the global basic frames can be selected. On a Reset, the mask is initialized by											
\$MN_NCBFRAME_RESET_MASK.											
Axes:							NCK Version:		16.00.00		
Unit:		-		min:		0		max:		0xFFFF	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global					Search run		Link		
							not classified		No restriction		

INT	\$P_CHBFRMASK					Basic frame mask in the channel		Cross. R.:			
Description:											
Variable \$P_CHBFRMASK is used to define the channel-specific basic frame included in the calculation of the overall basic frame \$P_ACTBFRAME. The variable is implemented in the form of a bit mask in which the basic frames can be selected. On a Reset, the mask is initialized by											
\$MC_CHBFRAME_RESET_MASK.											
Axes:							NCK Version:		16.00.00		
Unit:		-		min:		0		max:		0xFFFF	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global					Search run		Link		
							not classified		No restriction		

1.1 List of system variables

INT	\$P_CHSFRMASK					System frame mask			Cross. R.:	
Description: Variable \$P_CHSFRMASK is used to define the channel-specific system frame included in the calculation of the overall frame \$P_ACTFRAME. The variable is implemented in the form of a bit mask in which the system frames can be selected. On a Reset, the mask is initialized by \$MC_CHSFRAME_RESET_MASK.										
Axes:					NCK Version:			51.03.00		
Unit:		min:		0			max:		0x7F	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run			Link		
		not classified			No restriction					

DOUBLE	\$P_AD[34]					Still to be defined			Cross. R.:	
Description: \$P_AD[n] Active tool offsets n: Parameter numbers 1 - 31 n = 1-25 \$TC_DP1 to \$TC_DP25 n = 26 \$TC_DPCE n = 27 \$TC_DPH n = 28 \$TC_DPV n = 29 \$TC_DPV3 n = 30 \$TC_DPV4 n = 31 \$TC_DPV5										
Description of array limits: n: Parameter numbers 1 - 31 n = 1-25 \$TC_DP1 to \$TC_DP25 n = 26 \$TC_DPCE n = 27 \$TC_DPH n = 28 \$TC_DPV n = 29 \$TC_DPV3 n = 30 \$TC_DPV4 n = 31 \$TC_DPV5										
Axes:					NCK Version:			06.00.00		
Unit:		min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run			Link		
		According to part program			No restriction					

DOUBLE	\$P_ADT[34]				Still to be defined	Cross. R.:				
Description: \$P_AD[n] Active tool offsets transformed n: Parameter numbers 1 - 31 n = 1-25 \$TC_DP1 to \$TC_DP25 n = 26 \$TC_DPCE n = 27 \$TC_DPH n = 28 \$TC_DPV n = 29 \$TC_DPV3 n = 30 \$TC_DPV4 n = 31 \$TC_DPV5										
Description of array limits: n: Parameter numbers 1 - 31 n = 1-25 \$TC_DP1 to \$TC_DP25 n = 26 \$TC_DPCE n = 27 \$TC_DPH n = 28 \$TC_DPV n = 29 \$TC_DPV3 n = 30 \$TC_DPV4 n = 31 \$TC_DPV5										
Axes:						NCK Version:		43.00.00		
Unit:		-	min: DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
		According to part program				No restriction				

INT	\$P_DLNO				Still to be defined	Cross. R.:				
Description: \$P_DLNO Active additive offset number DL=0 - DL='max.'; 'max' = value of \$MN_MM_MAX_SUMCORR_PER_CUTTEDGE										
Axes:						NCK Version:		20.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global				Search run		Link		
		not classified				No restriction				

1.1 List of system variables

INT	\$P_TOOL					Still to be defined			Cross. R.:	
Description:										
\$P_TOOL										
Active tool cutting edge D0 - D'max.'; 'max'= value of \$MN_MM_MAX_CUTTING_EDGE_NO										
Axes:						NCK Version:	06.00.00			
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_TOOLNO					Still to be defined			Cross. R.:	
Description:										
\$P_TOOLNO										
Active tool number T0 - T32000; T can be an 8-digit number when 'flat D number' function is active										
This command should not generally be used when magazine management is active.										
When magazine management is active, GETEXET should be used instead.										
(T number programming always works reliably when \$MC_CUTTING_EDGE_DEFAULT=-1, or > 0.										
In cases where \$MC_CUTTING_EDGE_DEFAULT=0, or =-2, T number read errors can occur.										
The T number mechanism is also reliable if it is programmed after D > 0.										
Notice: Particularly with a setting of \$MC_CUTTING_EDGE_DEFAULT=-2, \$P_TOOLNO (the T no. of the active tool with which the currently										
active D offset has been calculated) and GETEXET (the changed tool) can return different T numbers.										
->see also \$P_MTHSDC and the documentation relating to the subject of multiple toolholders/spindles.										
Axes:						NCK Version:	06.00.00			
Unit:	-	min:				max:	32000			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_TOOLP					Still to be defined			Cross. R.:	
Description:										
\$P_TOOLP										
Last programmed tool number T0 - T32000 (in operation without magazine management).										
This command cannot be used when magazine management is active.										
When magazine management is active, GETSELT must be used instead.										
If the function 'T alarm delay after M06' is active, the result T number = -1 if the preceding T address has been programmed incorrectly.										
Axes:						NCK Version:	20.00.00			
Unit:	-	min:				max:	32000			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		According to part program				No restriction				

DOUBLE	\$P_TOOLL[3]					Still to be defined			Cross. R.:		
Description: \$P_TOOLL[n] Active tool total length											
Description of array limits: n: Length 1 - 3											
Axes:					NCK Version:			06.00.00			
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$P_TOOLO[3]					Still to be defined			Cross. R.:		
Description: \$P_TOOLO[n] Active tool orientation											
Description of array limits: n: Components 1 - 3											
Axes:					NCK Version:			44.00.00			
Unit:	-	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$AC_TOOLO_ACT[3]					Still to be defined			Cross. R.:		
Description: \$AC_TOOLO_ACT[n] Active command orientation											
Description of array limits: n: Components 1 - 3											
Axes:					NCK Version:			51.00.00			
Unit:	-	min:	-1.0				max:	1.0			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$AC_TOOLO_END[3]					Still to be defined			Cross. R.:	
Description: \$AC_TOOLO_END[n] End orientation of active block										
Description of array limits: n: Components 1 - 3										
Axes:					NCK Version:			51.00.00		
Unit:		-	min:		-1.0			max:		1.0
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global	Search run			Link				
			not classified			No restriction				

DOUBLE	\$AC_TOOLO_DIFF					Still to be defined			Cross. R.:	
Description: \$AC_TOOLO_DIFF Remaining angle of tool orientation in active block										
Description of array limits: n: Components 1 - 3										
Axes:					NCK Version:			51.00.00		
Unit:		Degrees	min:		0.0			max:		360.0
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global	Search run			Link				
			not classified			No restriction				

DOUBLE	\$VC_TOOLO[3]					Still to be defined			Cross. R.:	
Description: \$VC_TOOLO[n] Actual orientation										
Description of array limits: n: Components 1 - 3										
Axes:					NCK Version:			51.00.00		
Unit:		-	min:		-1.0			max:		1.0
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global	Search run			Link				
			not classified			No restriction				

DOUBLE	\$VC_TOOLO_DIFF				Still to be defined				Cross. R.:	
Description: \$VC_TOOLO_DIFF Angle between command and actual orientation										
Axes:				NCK Version:				51.00.00		
Unit:	Degrees	min:	0.0			max:	180.0			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$VC_TOOLO_STAT				Still to be defined				Cross. R.:	
Description: \$VC_TOOLO_STAT Status of calculation of actual orientation										
Axes:				NCK Version:				51.00.00		
Unit:	-	min:	-1			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_TC				Active toolholder				Cross. R.:	
Description: \$P_TC Active toolholder										
Axes:				NCK Version:				20.00.00		
Unit:	-	min:				max:	99999999			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$AC_TC				Still to be defined				Cross. R.:	
Description: \$AC_TC Active toolholder										
Axes:				NCK Version:				49.00.00		
Unit:	-	min:				max:	99999999			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$P_TCNUM					Still to be defined			Cross. R.:	
Description: \$P_TCNUM Number of available toolholders in the channel										
Axes:							NCK Version:		52.00.00	
Unit:	-	min:					max:		99999999	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$P_TCANG[2]					Still to be defined			Cross. R.:	
Description: \$P_TCANG[n] Active angle of a toolholder axis Description of array limits: n: Angle 1 - 2										
Axes:							NCK Version:		16.00.00	
Unit:	-	min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$P_TCDIFF[2]					Still to be defined			Cross. R.:	
Description: \$P_TCDIFF[n] Difference between calculated and used angle of a toolholder axis with angle incrementation (Hirth tooth system) Description of array limits: n: Angle 1 - 2										
Axes:							NCK Version:		20.00.00	
Unit:	-	min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_TCSOL					Still to be defined	Cross. R.:			
Description: \$P_TCSOL Number of solutions when angle of axis of rotation of an orientatable toolholder is defined from a frame In the case of 0 to 2 solutions, the relevant value is returned. The return value is 3 when the number of solutions is infinite. If the angles are specified (TCOABS), the number of solutions is always 1.										
Axes:						NCK Version:	43.00.00			
Unit:	-	min:				max:	3			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_TCSTAT					Still to be defined	Cross. R.:			
Description: \$P_TCSTAT Specifies the status of an orientatable toolholder. The variable is bit-coded with the following bit meanings: 0x1 The first axis of rotation exists 0x2 The second axis of rotation exists 0x4 The angles used in the calculation are acquired from an orientation in the frame direction 0x8 The angles used in the calculation have been specified absolutely 0x10 The polar axis angle is uncertain with the toolholder orientated in the frame direction 0x1000 Only the tool is rotatable (kinematic type T) 0x2000 Only the workpiece is rotatable (kinematic type P) 0x4000 Tool and workpiece are rotatable (kinematic type M) The bits specified here are not currently assigned.										
Axes:						NCK Version:	49.00.00			
Unit:	-	min:				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$P_TOOLR					Still to be defined			Cross. R.:	
Description: \$P_TOOLR Active tool radius (total)										
Axes:					NCK Version:			06.00.00		
Unit:	inch	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$P_TOOLND[32000]					Still to be defined			Cross. R.:	
Description: \$P_TOOLND[t] Number of tool edges of tool t Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run			Link					
		not classified			No restriction					

BOOL	\$P_TOOLEXIST[32000]					Still to be defined			Cross. R.:	
Description: \$P_TOOLEXIST[t] Does the tool with T no. t exist Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	FALSE			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run			Link					
		According to part program			No restriction					

1.1 List of system variables

INT	\$P_D					Programmed D number (ISO2 mode)			Cross. R.:	
Description: \$P_D Programmed D number in ISO_2 language mode The D number is the tool offset number in ISO mode 2 (milling). If no tool offset is active, the value 0 is output. The tool offset can be selected with D or H. However, this variable only ever contains the D value.										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global				Search run			Link	
						According to part program			No restriction	

INT	\$P_H					Programmed H number (ISO2 milling)			Cross. R.:	
Description: \$P_H Programmed H number in ISO_2 language mode The H number is the tool offset number in ISO mode 2 (milling). If no tool offset is active, the value 0 is output. The tool offset can be selected with D or H. However, this variable only ever contains the H value.										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global				Search run			Link	
						According to part program			No restriction	

INT	\$A_TOOLMN[32000]					Still to be defined			Cross. R.:	
Description: \$A_TOOLMN[t] Magazine number of tool t Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			13.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:										
Attributes:		Global				Search run			Link	
						not classified			No restriction	

1.1 List of system variables

INT	\$A_TOOLMLN[32000]					Still to be defined			Cross. R.:	
Description: \$A_TOOLMLN[t] Magazine location number of tool t										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			13.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$A_MYMN[32000]					Still to be defined			Cross. R.:	
Description: \$A_MYMN[t] Number of home magazine of tool with T no. t. (A magazine becomes the home magazine of the tool if the tool is being loaded onto a magazine location of kind 1 (\$TC_MPP1=1).) Resulting value = 0 = tool is not loaded (if \$A_TOOLMN > 0, then manual tool). Resulting value = -1 = tool management is not active Resulting value = -2 = tool with T no. t does not exist.										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			41.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$A_MYMLN[32000]					Still to be defined	Cross. R.:			
Description:										
\$A_MYMLN[t]										
Number of the home magazine location of the tool with T no. t. (A magazine location becomes the home magazine location of a tool if the tool is being loaded onto a magazine location of kind 1 (\$TC_MPP1=1).) Resulting value = 0 = tool is not loaded (if \$A_TOOLMLN > 0, then manual tool). Resulting value = -1 = tool management is not active Resulting value = -2 = tool with T no. t does not exist.										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
Axes:						NCK Version:	41.00.00			
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$A_MONIFACT					Still to be defined	Cross. R.:			
Description:										
\$A_MONIFACT										
Factor for tool life monitoring										
Axes:						NCK Version:	13.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_TOOLNG					Still to be defined	Cross. R.:			
Description:										
\$P_TOOLNG										
Number of defined tool groups assigned to the channel OPI block type= TM										
Axes:						NCK Version:	42.00.00			
Unit:	-	min:	INT_MIN			max:	INT_MAX]			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$P_TOOLNT					Still to be defined			Cross. R.:	
Description: \$P_TOOLNT Number of defined tools assigned to the channel OPI block type= TV										
Axes:					NCK Version:			42.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX]		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_TOOLT[600]					Still to be defined			Cross. R.:	
Description: \$P_TOOLT[i] ith tool number T OPI block type= TV										
Description of array limits: i= 1,..., \$P_TOOLNT										
Axes:					NCK Version:			42.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX]		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_TOOLD[32000,12]					Still to be defined			Cross. R.:	
Description: \$P_TOOLD[t,i] ith D no. of tool with T no. t; i=1,2... If t is the value of an undefined tool, -2 is returned If i is a value outside the permissible range, 0 is returned OPI block type= TO										
Description of array limits: t = 1, ..., SLMAXTOOLNUMBER i = 1,....., \$P_TOOLND										
Axes:					NCK Version:			42.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX]		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_USEKT					Still to be defined			Cross. R.:	
Description: \$P_USEKT (= USE Kind of Tool) Is a bit-coded value All tools whose parameter \$TC_TP11 has set one of the bits of \$P_USEKT are available for the following tool changes. The value 'zero' has the equivalent content of 'all bits are set' OPI block= C/S										
Axes:					NCK Version:			43.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X				7
Attributes:		Global Search run			Link					
		not classified			No restriction					

INT	\$P_TOOLNDL[32000,32000]					Still to be defined			Cross. R.:	
Description: \$P_TOOLNDL[t,d] Number of DL offsets of D offset specified by T no. t and D no. d >0 Number of DL offsets 0 No DL offset for this D offset -1 Additive offset function not active -2 t is the value of an undefined tool -3 d is the value of an undefined D offset OPI block type= TOS; TOE										
Description of array limits: t = 1, ..., SLMAXTOOLNUMBER d = 1, ..., SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			43.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX]		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global Search run			Link					
		not classified			No restriction					

1.1 List of system variables

INT	\$P_MAGN					Still to be defined			Cross. R.:	
Description: \$P_MAGN Number of defined magazines assigned to the channel. > 0 Successful read access 0 No magazine defined -1 WZMG is not active OPI block= TM										
Axes:					NCK Version:			43.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global Search run			Link					
		not classified			No restriction					

INT	\$P_MAG[32]					Still to be defined			Cross. R.:	
Description: \$P_MAG[i] ith magazine number > 0 Successful read access 0 i is outside the permissible range -1 WZMG is not active OPI block= TM										
Description of array limits: i= 1, ..., \$P_MAGN										
Axes:					NCK Version:			43.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global Search run			Link					
		not classified			No restriction					

INT	\$P_MAGNDIS[32000,32000]					Still to be defined					Cross. R.:
Description:											
P_MAGNDIS[n, m]											
Number of magazines connected to location m of internal magazine n.											
> 0 Successful read access											
0 No magazine is connected to the buffer location											
-1 WZMG is not active											
-2 n is not the number of an internal magazine											
-3 m is not the number of an internal magazine location											
OPI block TPM											
Description of array limits:											
n = must be the number of the buffer magazine or load magazine											
m = 1, ..., max. number of a location in the specified internal magazine											
Axes:						NCK Version:	43.00.00				
Unit:	-	min:	INT_MIN			max:	INT_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$P_MAGDISS[32000,32]					Still to be defined					Cross. R.:
Description:											
P_MAGDISS[l, i]											
Number of ith magazine connected to location l of the buffer magazine.											
> 0 Successful read access											
0 i is outside the permissible range											
-1 WZMG is not active											
-2 m is not the number of a buffer magazine location											
-3 no buffer magazine defined											
OPI block TPM											
Description of array limits:											
l = 1, ..., max. number of a location in the buffer magazine											
i = 1, ..., \$P_MAGNDIS[no. of buffer magazine, refLoc]											
Axes:						NCK Version:	43.00.00				
Unit:	-	min:	INT_MIN			max:	INT_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

INT	\$P_MAGDISL[32000,32]					Still to be defined			Cross. R.:	
Description: P_MAGDISL[I, i] Number of ith magazine connected to location I of the load magazine. > 0 Successful read access 0 i is outside the permissible range -1 WZMG is not active -2 m is not the number of a load magazine location -3 no load magazine defined OPI block TPM										
Description of array limits: I = 1, ..., max. number of a location in the load magazine i = 1, ..., \$P_MAGNDIS[no. of load magazine, refLoc]										
Axes:					NCK Version:			43.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_MAGNS					Still to be defined			Cross. R.:	
Description: \$P_MAGNS Number of spindle locations / toolholder locations in the buffer assigned to the channel. > 0 Successful read access 0 No spindle locations defined -1 WZMG is not active -3 No buffer magazine defined										
Axes:					NCK Version:			43.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_MAGS[20]					Still to be defined	Cross. R.:			
Description: \$P_MAGS[n] nth number of spindle / of toolholder in buffer > 0Successful read access 0n is outside the permissible range -1WZMG is not active -3No buffer magazine defined										
Description of array limits: n= 1,...., max. toolholder number										
Axes:					NCK Version:		43.00.00			
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes: Global		Search run				Link				
		not classified				No restriction				

INT	\$P_MAGNREL[20]					Still to be defined	Cross. R.:			
Description: \$P_MAGNREL[n] Number of buffers assigned to the spindle number / toolholder number n > 0Successful read access 0No buffer location assigned to spindle location -1WZMG is not active -2n is not the number of a spindle location -3No buffer magazine defined										
Description of array limits: n= 1,...., max. toolholder number										
Axes:					NCK Version:		43.00.00			
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes: Global		Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$P_MAGREL[20,600]					Still to be defined			Cross. R.:	
Description:										
P_MAGREL[n, m]										
mth buffer number of nth spindle number / toolholder number										
> 0Successful read access										
0m is outside the permissible range										
-1WZMG is not active										
-2n is not the number of a spindle location										
-3No buffer magazine defined										
Description of array limits:										
n= 1,..., max. toolholder number										
m= 1,..., \$P_MAGNREL										
Axes:							NCK Version:		43.00.00	
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global			Search run			Link		
		not classified			No restriction					

INT	\$P_MAGNH					Still to be defined			Cross. R.:	
Description:										
\$P_MAGNH										
Number of defined magazine location type hierarchies assigned to the channel.										
> 0Successful read access										
0No location type hierarchies are defined										
-1WZMG is not active										
OPI block= TT										
Axes:							NCK Version:		43.00.00	
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global			Search run			Link		
		not classified			No restriction					

INT	\$P_MAGNHLT[8]				Still to be defined	Cross. R.:				
Description: \$P_MAGNHLT[n] Number of defined location types in the nth defined hierarchy > 0 Successful read access 0n is outside the defined range -1WZMG is not active OPI block= TT										
Description of array limits: n= 1,..., \$P_MAGNH										
Axes:				NCK Version:			43.00.00			
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$P_MAGHLT[8,8]				Still to be defined	Cross. R.:				
Description: P_MAGHLT[n, m] mth location type of hierarchy n; n= 1,..., \$P_MAGNH; m= 1,..., \$P_MAGNHLT > 0 Successful read access 0m is outside the defined range -1WZMG is not active -2Hierarchy n has no defined location types OPI block= TT										
Description of array limits: n= 1,..., \$P_MAGNH m= 1,..., \$P_MAGNHLT										
Axes:				NCK Version:			43.00.00			
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

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INT	\$P_MAGNA					Still to be defined			Cross. R.:	
Description: \$P_MAGNA Number of defined adapters assigned to the channel. > 0 Successful read access 0 No adapters defined -1 'Adapter' function or TMMG is not active OPI block= AD										
Axes:					NCK Version:			43.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global Search run			Link					
		not classified			No restriction					

INT	\$P_MAGA[600]					Still to be defined			Cross. R.:	
Description: \$P_MAGA[i] ith adapter number > 0 Successful read access 0i is outside the permissible range -1 'Adapter' function or TMMG is not active OPI block= AD										
Description of array limits: i= 1, ..., \$P_MAGNA										
Axes:					NCK Version:			43.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global Search run			Link					
		not classified			No restriction					

INT	\$P_MTHSDC					Master spindle/toolholder for tool offset			Cross. R.:		
Description: \$P_MTHSDC Master toolholder no. or master spindle no. with reference to which the active tool is determined for the next D offset selection. >0Successful read access 0No master toolholder or master spindle available. The next D offset works with T0. -1TMMG not available.											
If read as an OPI variable, this is valid for the status in the current main run block											
Axes:					NCK Version:			48.00.00			
Unit:	-	min:	-1				max:	20			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$AC_MONMIN					Still to be defined			Cross. R.:		
Description: \$AC_MONMIN Relation between tool monitoring actual value and setpoint. Threshold for tool search strategy "Load only tools with an actual value higher than threshold"											
Axes:					NCK Version:			18.00.00			
Unit:	-	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X				X	X		X		
write:	X	X	X			X	X		X	7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$P_VDITCP[3]					Still to be defined			Cross. R.:		
Description: \$P_VDITCP[n] Free parameters for tool management in VDI interface Description of array limits: n: Index 1 - 3											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$P_ATPG[9]					Still to be defined					Cross. R.:
Description: \$P_ATPG[n] Current tool-related grinding data											
Description of array limits: n: Parameter numbers 1 -9											
Axes:						NCK Version:	13.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

STRING	\$P_TOOLENV					Still to be defined					Cross. R.:
Description: \$P_TOOLENV[i] Supplies the name of the tool environment stored under the (internal) index i. If i does not refer to a defined data block, a zero string is returned. If index i is invalid, i.e. less than 1 or greater than the maximum number of data blocks for tool environments (\$MN_MM_NUM_TOOLENV), an alarm is generated.											
Description of array limits: A maximum number of tool environments can be configured via MD \$MN_MM_NUM_TOOLENV. max. string length											
Axes:						NCK Version:	45.00.00				
Unit:	-	min:				max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$P_TOOLENVN					Still to be defined					Cross. R.:
Description: \$P_TOOLENVN Specifies the number of defined data blocks for defining tool environments.											
Axes:						NCK Version:	45.00.00				
Unit:	-	min:				max:	INT_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$P_AP				Angle with polar coordinates				Cross. R.:	
Description: \$P_AP Programmed angle with polar coordinates in degrees										
Axes:					NCK Version:		43.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

AXIS	\$P_AXN1				Axis identifier for the abscissa				Cross. R.:	
Description: Variable \$P_AXN1 supplies the current address of the geometry axis for the abscissa.										
Axes:					NCK Version:		06.00.00			
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

AXIS	\$P_AXN2				Axis identifier for the ordinate				Cross. R.:	
Description: Variable \$P_AXN2 supplies the current address of the geometry axis for the ordinate.										
Axes:					NCK Version:		06.00.00			
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

AXIS	\$P_AXN3				Axis identifier for the applicate				Cross. R.:	
Description: Variable \$P_AXN3 supplies the current address of the geometry axis for the applicate.										
Axes:					NCK Version:		06.00.00			
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

AXIS	\$P_ACTGEOAX[3]					Current geometry axis identifier		Cross. R.:		
Description:										
Variable \$P_ACTGEOAX[n] supplies the current geometry axis identifier depending on the plane. The geometry axis assignment corresponds to the programmed GEOAX(1,X,2,Y,3,Z) values. The assignment can also change on a Reset and on selection and deselection of transformations.										
Description of array limits:										
Array index 1-3 for 1st - 3rd geometry axis										
Axes:					NCK Version:			13.00.00		
Unit:		min:					max:			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global				Search run		Link		
						not classified		not classified		

INT	\$P_GG[MAX_GGROUP]					Active G function		Cross. R.:		
Description:										
\$P_GG[n]										
Read active G function of G function group n The index of the G function is supplied as described in the Programming Guide Fundamentals, Section "List of G functions/preparatory functions". (This also matches the index output at the PLC interface when configured accordingly)										
Example:										
;Check for G55										
IF \$P_GG[8] == 3 GOTOF LABEL_G55										
Description of array limits:										
n: Number of G function group										
Axes:					NCK Version:			06.00.00		
Unit:		min:		0			max:		INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global				Search run		Link		
						not classified		not classified		

INT	\$P_EXTGG[MAX_EXT_GGROUP]					Active G function with external language			Cross. R.:	
Description: \$P_EXTGG[n] Read active G function of G function group n of external language. The index of the G function is supplied as described in the Function Description "ISO Dialects" Section "G commands". (This also matches the index output at the PLC interface when configured accordingly) Example: ;Check for G55 in ISO Dialect T IF \$P_EXTGG[14] == 2 GOTOF LABEL_G55										
Description of array limits:										
n: Number of G function group										
Axes:							NCK Version:		16.00.00	
Unit:	-	min:	0			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$A_GG[MAX_GGROUP]					Active G function in synchronized action			Cross. R.:	
Description: \$A_GG[n] Read active G function of G function group n in synchronized action The index of the G function is supplied as described in the Programming Guide Fundamentals, Section "List of G functions/preparatory functions". (This also matches the index output at the PLC interface when configured accordingly) Example: ;Check for G55 in synchronized action WHEN \$A_GG[8] == 3 DO ...										
Description of array limits:										
n: Number of G function group										
Axes:							NCK Version:		16.00.00	
Unit:	-	min:	0			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

BOOL	\$P_SEARCH					Search run active					Cross. R.:
Description:											
\$P_SEARCH											
Returns TRUE (1) if block search is active											
Axes:						NCK Version:	06.00.00				
Unit:	-	min:	FALSE			max:	TRUE				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

BOOL	\$P_SEARCH1					Search with calculation active					Cross. R.:
Description:											
\$P_SEARCH1											
Returns TRUE (1) if block search with calculation is active.											
Axes:						NCK Version:	06.00.00				
Unit:	-	min:	FALSE			max:	TRUE				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

BOOL	\$P_SEARCH2					Block search without calculation was active					Cross. R.:
Description:											
\$P_SEARCH2											
Returns TRUE (1) if last selected search type was "block search without calculation".											
Axes:						NCK Version:	06.00.00				
Unit:	-	min:	FALSE			max:	TRUE				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$P_SEARCHL					Last active search type			Cross. R.:		
Description: \$P_SEARCHL supplies the last selected search type: (coding analogous to PI service _N_FINDBL) 0 : No search 1 : Search without calculation 2 : Search with calculation on contour 3 : Reserved 4 : Search with calculation at end of block 5 : Search in extended program test											
Axes:					NCK Version:			16.00.00			
Unit:		-	min:		0			max:		5	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:											
Attributes:		Global	Search run				Link				
			not classified				not classified				

BOOL	\$P_SUBPAR[n]					Parameter programmed			Cross. R.:		
Description: \$P_SUBPAR[n] Interrogate whether parameter n was actually programmed (TRUE) on subroutine call with parameter transfer, or whether the system has applied a default parameter (FALSE).											
Description of array limits: n: Parameter numbers 1 to n according to definition in PROC instruction											
Axes:					NCK Version:			14.00.00			
Unit:		-	min:		FALSE			max:		TRUE	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:											
Attributes:		Global	Search run				Link				
			not classified				not classified				

BOOL	\$P_CTABDEF					Curve table is defined			Cross. R.:		
Description: Variable \$P_CTABDEF determines whether a curve table definition is active.											
Axes:					NCK Version:			13.00.00			
Unit:		-	min:		FALSE			max:		TRUE	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:											
Attributes:		Global	Search run				Link				
			not classified				not classified				

1.1 List of system variables

BOOL	\$P_IPTRLOCK					Still to be defined			Cross. R.:	
Description: \$P_IPTRLOCK Status of disable for updating the interruption pointer (OPI block InterruptionSearch) due to part program command IPTRLOCK/IPTRUNLOCK or machine data \$MC_AUTO_IPTR_LOCK: FALSE (0) -> interruption pointer is updated when interruption occurs TRUE (1) -> the halt block is stored in the interruption pointer										
Axes:					NCK Version:			52.00.00		
Unit:		-	min:					max:		1
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

BOOL	\$P_DELAYFST					Still to be defined			Cross. R.:	
Description: \$P_DELAYFST Interrogation whether delay stop area is active or not depending on part program command DELAYFSTON/DELAYFSTOF. Note: Delay stop areas defined by G331/G332 can be interrogated only by a synchronized action due to the restriction to motion blocks and dwell times (see \$AC_DELAYFST). FALSE (0) -> Delay stop area is not active TRUE (1) -> Delay stop area is active										
Axes:					NCK Version:			54.00.00		
Unit:		-	min:		FALSE			max:		TRUE
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

BOOL	\$AC_DELAYFST					Still to be defined			Cross. R.:	
Description: \$AC_DELAYFST Interrogation in synchronized actions whether delay stop area is active or not due to part program command DELAYFSTON/DELAYFSTOF or G331/G332. Note: If \$AC_DELAYFST is used outside synchronized actions in the part program, then, analogous to \$P_DELAYFST, the delay stop areas defined with G331/G332 cannot be interrogated owing to the restriction to motion blocks and dwell times (see \$P_DELAYFST). FALSE (0) -> Delay stop area is not active TRUE (1) -> Delay stop area is active										
Axes:					NCK Version:			54.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$P_MC					Modal subroutine call active			Cross. R.:	
Description: \$P_MC Status of modal subroutine call FALSE (0) -> no modal subroutine call TRUE (1) -> modal subroutine call active										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$P_REPINF					Repositioning possible			Cross. R.:	
Description: \$P_REPINF Status info for repositioning with REPOS command FALSE (0) -> Axis cannot be repositioned with REPOS command for following reasons - Call is not issued in an Asub - Call is issued by an Asub that has been started in the Reset state - Call is issued by an Asub that has been started in JOG mode TRUE (1) -> Axis can be repositioned with REPOS										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

BOOL	\$P_SIM					HMI simulation active			Cross. R.:	
Description: \$P_SIM Returns TRUE (1) if HMI simulation is running										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run			Link					
		not classified			not classified					

BOOL	\$P_DRYRUN					Dry run feed selected			Cross. R.:	
Description: \$P_DRYRUN Returns TRUE (1) if dry run feed is selected, or else FALSE (0).										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run			Link					
		not classified			not classified					

DOUBLE	\$P_OFFN					Still to be defined			Cross. R.:	
Description: \$P_OFFN Programmed offset contour normal:										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run			Link					
		not classified			not classified					

DOUBLE	\$PI					Circle constant			Cross. R.:	
Description: Variable \$PI determines the circle constant $PI = 3.1415927$.										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	3.1415927			max:	3.1415927			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run			Link					
		Independent			No restriction					

INT	\$P_PROG_EVENT					Event-driven program call active			Cross. R.:	
Description:										
System variable \$P_PROG_EVENT can be used to query whether the program has been activated implicitly by an event configured with \$MC_PROG_EVENT_MASK or \$MN_SEARCH_RUN_MODE.										
\$P_PROG_EVENT supplies an integer value between 0 and 5 with the following meaning:										
0:Explicit activation by NC Start or Asub Start via VDI or Asub interface										
1: Implicit activation by "Part program start" event										
2:Implicit activation by "Part program end" event										
3:Implicit activation by "Operator panel reset" event										
4:Implicit activation by "Boot" event										
5:Implicit activation after output of last action block after a block search										
Axes:						NCK Version:		42.00.00		
Unit:	-	min:	0			max:	5			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

STRING	\$P_PROGPATH					Path of the current program			Cross. R.:	
Description:										
\$P_PROGPATH										
Supplies the path where the program currently being processed is stored in the file system.										
Example:										
Subprogram "/_N_WKS_DIR/_N_SHAFT_DIR/_N_MYSUB_SPF" is running.										
\$P_PROGPATH returns the string "/_N_WKS_DIR/_N_SHAFT_DIR/".										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

STRING	\$P_PROG				Program name of a program level				Cross. R.:		
Description: \$P_PROG[n] Supplies the name of the program on program level n.											
Example: \$P_PROG[0] Supplies the name of the program on program level 0 = main program name.											
Description of array limits: n: Defines the program level from which the program name is to be read. Numerical value: 0 to 11 max. string length											
Axes:					NCK Version:	17.00.00					
Unit:	-	min:					max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$P_STACK				Current program level				Cross. R.:		
Description: \$P_STACK Supplies the program level on which the current part program is running.											
Axes:					NCK Version:	17.00.00					
Unit:	-	min:	0				max:	11			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$P_ISO_STACK					Current program level in ISO mode			Cross. R.:		
Description: \$P_ISO_STACK The variable supplies the current program level in ISO mode. Unlike Siemens mode, not every subprogram or macro call changes the program level in ISO mode. Subprogram/macro calls and their effect on \$P_ISO_STACK: M98 Pxx ,subprogram call\$P_ISO_STACK remains the same G65 Pxx ,non-modal macro\$P_ISO_STACK is incremented G66 Pxx ,modal macro\$P_ISO_STACK is incremented M macro substitution\$P_ISO_STACK is incremented M subprogram substitution\$P_ISO_STACK remains the same T substitution\$P_ISO_STACK remains the same G substitution\$P_ISO_STACK is incremented 802S/C:Value range = [0,5]											
Axes:							NCK Version:		52.00.00		
Unit:	-	min:						max:		11	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

STRING	\$P_PATH					Path of a program level			Cross. R.:		
Description: \$P_PATH[n] Supplies the path where the program being processed on program level n is stored in the file system. Examples: \$P_PATH[0] supplies the directory of the main program, e.g. "/_N_WKS_DIR/_N_SHAFT_WPD/". \$P_PATH[\$P_STACK - 1] supplies the path of the calling program. Description of array limits: n: Defines the program level from which the program path is to be read. Numerical value: 0 to 11 max. string length											
Axes:							NCK Version:		17.00.00		
Unit:	-	min:						max:			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

BOOL	\$P_ACTID[16]					Modal synchronized action is programmed			Cross. R.:	
Description: Variable \$P_ACTID[n] determines whether the first 16 modal synchronized actions with ID n are programmed.										
Description of array limits: Index 1 - 16 corresponds to the nth modal synchronized action.										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	FALSE				max:	TRUE	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global				Search run			Link	
						not classified			not classified	

INT	\$AC_STAT					Still to be defined			Cross. R.:	
Description: \$AC_STAT -1: Invalid 0: Channel in Reset state 1: Channel interrupted 2: Channel active										
Axes:					NCK Version:			13.00.00		
Unit:		-	min:	-1				max:	2	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:		Global				Search run			Link	
						not classified			not classified	

INT	\$AC_PROG					Still to be defined			Cross. R.:	
Description: \$AC_PROG -1: Invalid 0: Program in Reset state 1: Program stopped 2: Program active 3: Program waiting 4: Program interrupted										
Axes:					NCK Version:			13.00.00		
Unit:		-	min:	-1				max:	4	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X		X	
write:										
Attributes:		Global				Search run			Link	
						not classified			not classified	

INT	\$AC_SYNA_MEM					Free synchronized action elements		Cross. R.:		
Description: Variable \$AC_SYNA_MEM determines the number of free synchronized action elements. The maximum number of elements is configured by \$MC_MM_NUM_SYNC_ELEMENTS. The value is read from the part program without a preprocessing stop.										
Axes:					NCK Version:		13.00.00			
Unit:		min:		0		max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$AC_IPO_BUF					Fill level Ipo buffer		Cross. R.:		
Description: Variable \$AC_IPO_BUF determines the current fill level of the interpolator buffer. The value is read from the part program without a preprocessing stop.										
Axes:					NCK Version:		13.00.00			
Unit:		min:		0		max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$AC_BLOCKTYPE					Block type		Cross. R.:		
Description: Variable \$AC_BLOCKTYPE determines the type of the current main run block. The following values are possible: 0: Block is programmed block (main block). 1: Block was generated by the system as an intermediate block. 2: Block was generated by chamfers/rounding 3: Smooth approach and retraction (SAR) 4: Block was generated by tool offset 5: Block was generated by smoothing 6: Block was generated by TLIFT (tangential follow-up) 7: Block was generated by path segmentation 8: Block was generated by compile cycles 9: Block was generated due to orientation changes on path-relative interpolation of tool orientation (ORIPATH/ORIROTC) 10: Block was generated by pole treatment of orientation transformations which is activated by the the machine data \$MC_POLE_ORI_MODE										
Axes:					NCK Version:		51.00.00			
Unit:		min:		0		max:		9		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X			
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$AC_BLOCKTYPEINFO				Block type info			Cross. R.:			
Description:											
System variable \$AC_BLOCKTYPEINFO can be used to interrogate more detailed information about variable \$AC_BLOCKTYPE.											
Depending on the value of system variable \$AC_BLOCKTYPE, various values can be returned:											
1. General, internally generated block: \$AC_BLOCKTYPE = 1											
\$AC_BLOCKTYPEINFO = 1000 and contains no further information.											
2. Chamfer/rounding: \$AC_BLOCKTYPE = 2											
2001: Straight											
2002: Circle											
3. SAR: \$AC_BLOCKTYPE = 3											
3001: Approach with straight line											
3002: Approach with quadrant											
3003: Approach with semicircle											
4. Tool compensation: \$AC_BLOCKTYPE = 4											
4001: Approach block after STOPRE											
4002: Connection blocks if intersection point not found											
4003: Point-type circle on inner corners (with TRACYL only)											
4004: Bypass circle (or conical cut) at outer corners											
4005: Approach blocks with offset suppression											
4006: Approach blocks on repeated WRC activation											
4007: Block split due to excessive curvature											
4008: Compensation blocks with 3D face milling (tool vector area vector)											
5. Smoothing: \$AC_BLOCKTYPE = 5											
5001: Smoothing contour by means of G641											
5002: Smoothing contour by means of G642											
5003: Smoothing contour by means of G643											
5004: Smoothing contour by means of G644											
6. TLIFT: \$AC_BLOCKTYPE = 6											
6001: TLIFT block with linear movement of tangential axis and without lift motion.											
6002: TLIFT block with nonlinear movement of tangential axis (polynomial) and without lift movement.											
6003: TLIFT block with lift motion, tangential axis motion and lift motion start simultaneously.											
6004: TLIFT block with lift motion, tangential axis starts first if specific lift position is reached.											
7. Path segmentation: \$AC_BLOCKTYPE = 7											
7001: Programmed path segmentation without active punching/nibbling											
7002: Programmed path segmentation with active punching/nibbling											
7003: Automatic, internally generated path segmentation											
8. Compile cycles: \$AC_BLOCKTYPE = 8											
In this case, system variable \$AC_BLOCKTYPEINFO contains the ID of the compile cycles Application which created the block											
9. Path-relative interpolation of tool orientation (ORIPATH/ORIROTC)											
9000: interpolation of tool orientation (ORIPATH)											
9001: interpolation of rotation of tool (ORIROTC)											
10: Pole treatment for orientation transformations											
10000: Look ahead of position of pole axis for orientation transformations											
10001 Inserted block for traversing the pole cone at orientation transformations:											
Axes:						NCK Version:		54.00.00			
Unit:		-		min: 0		max:		INT_MAX			
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X						X	X		
write:											
Attributes:		Global				Search run		Link			

1.1 List of system variables

		not classified	not classified	
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INT	\$AC_SPLITBLOCK				Still to be defined	Cross. R.:			
Description:									
System variable \$AC_SPLITBLOCK is capable of detecting all blocks generated internally and programmed blocks which were truncated as a result.									
It can return the following values:									
= 0 : It is an unchanged programmed block (a block generated by the compressor is viewed here as a programmed block).									
<> 0: Block has been truncated or is an internally generated block, the variable can assume the following values (variable is bit-coded):									
= 1: It is an internally generated block or a truncated original block									
= 3: It is the last block in a chain of internally generated blocks or truncated original blocks									
Axes:					NCK Version:	54.00.00			
Unit:	-	min:	0			max:	3		
	Prep	Main run	PR-Stop	MR-Sync	PP	SA	OPI	OEM	Acc. R.
read:		X				X	X		
write:									
Attributes:	Global	Search run			Link				
		not classified			not classified				

DOUBLE	\$AC_TANEB				Tangent angle at block end point	Cross. R.:			
Description:									
\$AC_TANEB determines the angle between the path tangent at the end of the current block and the path tangent at the start of the next block. This variable should only be applied to programmed main blocks.									
\$AC_BLOCKTYPE can be used to determine whether the current block is a main block.									
Axes:					NCK Version:	51.00.00			
Unit:	-	min:	-180.0			max:	180.0		
	Prep	Main run	PR-Stop	MR-Sync	PP	SA	OPI	OEM	Acc. R.
read:		X				X		X	
write:									
Attributes:	Global	Search run			Link				
		not classified			not classified				

DOUBLE	\$AC_SYNC_ACT_LOAD				Current runtime for synchronized actions	Cross. R.:			
Description:									
Variable \$AC_SYNC_ACT_LOAD supplies the current runtime for synchronized actions of the last interpolator cycle in the channel.									
Axes:					NCK Version:	54.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync	PP	SA	OPI	OEM	Acc. R.
read:		X				X		X	
write:									
Attributes:	Global	Search run			Link				
		not classified			not classified				

1.1 List of system variables

DOUBLE	\$AC_SYNC_MAX_LOAD					Longest runtime for synchronized actions			Cross. R.:	
Description: Variable \$AC_SYNC_MAX_LOAD supplies the longest runtime for synchronized actions of an interpolator cycle in the channel.										
Axes:					NCK Version:			54.00.00		
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:	X	X				X	X		X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$AC_SYNC_AVERAGE_LOAD					Average runtime for synchronized actions			Cross. R.:	
Description: Variable \$AC_SYNC_AVERAGE_LOAD supplies the average runtime per interpolator cycle for synchronized actions in the channel.										
Axes:					NCK Version:			54.00.00		
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:	X	X				X	X		X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_IW_STAT					Position information for PTP			Cross. R.:	
Description: Variable \$AC_IW_STAT describes the position information of the articulated joints (transformation-specific) for cartesian PTP travel. The variable is relevant only for transformations which support PTP.										
Axes:					NCK Version:			19.00.00		
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

1.1 List of system variables

INT	\$AC_IW_TU					Position information of axes for PTP			Cross. R.:	
Description: Variable \$AC_IW_TU describes the position information of the axes (MCS) for cartesian PTP travel. The variable is relevant only for transformations which support PTP.										
Axes:					NCK Version:			19.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TRANS_SYS					Reference system for cart. manual trav. (trans.)			Cross. R.:	
Description: \$AC_TRANS_SYS Reference system for translation with cartesian manual travel 0: Axis-spec. manual trav. active 1: Cart. manual trav. in BCS 2: Cart. manual trav. in WCS 3: Cart. manual trav. in TCS Only appropriate in connection with transformations which support cart. manual travel.										
Axes:					NCK Version:			46.00.00		
Unit:		-	min:		0			max:		3
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_JOG_COORD					Coordinate system for manual travel			Cross. R.:	
Description: Variable \$AC_JOG_COORD is used to set the coordinate system frame for manual travel. The following values are possible: 0: Manual travel in WCS 1: Manual travel in SZS										
Axes:					NCK Version:			50.00.00		
Unit:		-	min:		0			max:		1
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_ROT_SYS					Reference system for cart. manual trav. (ori.)			Cross. R.:		
Description: \$AC_ROT_SYS Reference system for orientation with cartesian manual travel 0: Axis-spec. manual trav. active 1: Cart. manual trav. in BCS 2: Cart. manual trav. in PCS 3: Cart. manual trav. in TCS Only appropriate in connection with transformations which support cart. manual travel.											
Axes:							NCK Version:		47.00.00		
Unit:		-	min:	0			max:	3			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:		Global	Search run			Link					
			not classified			not classified					

INT	\$AC_MEA[2]					Probe has switched			Cross. R.:		
Description: \$AC_MEA[n] Probe with number [n] has switched if TRUE (1) Description of array limits: n: Number of probe 1 - MAXNUM_PROBE											
Axes:							NCK Version:		13.00.00		
Unit:		-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X	X				X	X	X		
write:											
Attributes:		Global	Search run			Link					
			not classified			not classified					

1.1 List of system variables

INT	\$AC_TRAFO				Active transformation				Cross. R.:	
Description: \$AC_TRAFO Code number of active transformation according to machine data \$MC_TRAFO_TYPE_n . Note special meaning in the case of parameterized persistent transformation (bit 1 of \$MC_TRAFO_MODE_MASK set to 1): The parameters of the first chained transformation are returned in the case of TRACON. 0 is returned if only the persistent transformation is active.										
Axes:						NCK Version:		06.00.00		
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global				Search run		Link		
						not classified		not classified		

INT	\$P_TRAFO				Programmed transformation				Cross. R.:	
Description: \$P_TRAFO Code number of programmed transformation according to machine data \$MC_TRAFO_TYPE_n . Note special meaning in the case of parameterized persistent transformation (bit 1 of \$MC_TRAFO_MODE_MASK set to 1): The first chained transformation is returned in the case of TRACON. 0 is returned if only the persistent transformation is active.										
Axes:						NCK Version:		43.00.00		
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global				Search run		Link		
						not classified		not classified		

DOUBLE	\$AC_TRAFO_PAR[n]					Transformation selection parameters				Cross. R.:	
Description: \$AC_TRAFO_PAR[n] Selection parameters of active transformation Please note special meaning when persistent transformation is configured (Bit 1 of \$MC_TRAFO_MODE_MASK is set to 1): The parameters of the first chained transformation are returned in the case of TRACON. 0 is returned if only the persistent transformation is active.											
Description of array limits: n: Number of parameter											
Axes:					NCK Version:			43.00.00			
Unit:	-	min:	DOUBLE_MIN				max:	DOUBLE_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$P_TRAFO_PAR[n]					Progr. transformation selection parameters				Cross. R.:	
Description: \$P_TRAFO_PAR[n] Selection parameters of programmed transformation Please note special meaning when persistent transformation is configured (Bit 1 of \$MC_TRAFO_MODE_MASK is set to 1): The parameters of the first chained transformation are returned in the case of TRACON. 0 is returned if only the persistent transformation is active.											
Description of array limits: n: Number of parameter											
Axes:					NCK Version:			43.00.00			
Unit:	-	min:	DOUBLE_MIN				max:	DOUBLE_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

INT	\$AC_TRAFO_PARSET				Transformation data set number				Cross. R.:	
Description:										
\$AC_TRAFO_PARSET										
Number of active transformation data block										
Variable is '0' is no transformation is active										
.										
Please note special meaning when persistent transformation is configured (Bit 1 of \$MC_TRAFO_MODE_MASK is set to 1):										
The number of the data set of the first chained transformation is returned in the case of TRACON. is returned.										
0 is returned if only the persistent transformation is active.										
Axes:						NCK Version:		44.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$P_TRAFO_PARSET				Transformation data set number				Cross. R.:	
Description:										
\$P_TRAFO_PARSET										
Number of programmed transformation data block										
Variable is '0' is no transformation is active										
.										
Please note special meaning when persistent transformation is configured (Bit 1 of \$MC_TRAFO_MODE_MASK is set to 1):										
The number of the data set of the first chained transformation is returned in the case of TRACON. is returned.										
0 is returned if only the persistent transformation is active.										
Axes:						NCK Version:		44.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$AC_LIFTFAST					Still to be defined			Cross. R.:	
Description: \$AC_LIFTFAST Information about execution of rapid lift. 0: Initial state. 1: Rapid lift has been executed. The variable is set internally to "1" by the NC at the beginning of the rapid lift process. The variable must be reset to its initial state (\$AC_LIFTFAST=0) by the evaluating program (if one is configured) so that any subsequent rapid lift process can be detected again.										
Axes:						NCK Version:		13.00.00		
Unit:		-	min:				max:	1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$P_LIFTFAST					Still to be defined			Cross. R.:	
Description: \$P_LIFTFAST Information about execution of rapid lift. 0: Initial state. 1: Rapid lift has been executed. The variable is set internally to "1" by the NC at the beginning of the rapid lift process. The variable must be reset to its initial state (\$AC_LIFTFAST=0) by the evaluating program (if one is configured) so that any subsequent rapid lift process can be detected again. The variable is reset by writing \$AC_LIFTFAST!										
Axes:						NCK Version:		44.00.00		
Unit:		-	min:				max:	1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$AC_ASUP	Still to be defined	Cross. R.:	
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1.1 List of system variables

Description:

\$AC_ASUP

Code number for the reason for activating an Asub. The reasons are bit-coded and have the following meaning:

BIT0: Activation due to: user interrupt "ASUB with Blsync"

Activation by: VDI signal, digital-analog interface

Continued by: Freely selectable Reorg or Ret

BIT1: Activation due to: User interrupt "ASUB"

To continue the program with Repos, the position immediately prior to the interrupt is stored.

Activation by: VDI signal, digital-analog interface

Continued by: Freely selectable

BIT2: Activation due to: user interrupt "ASUB from channel state Ready"

Activation by: VDI signal, digital-analog interface

Continued by: Freely selectable

BIT3: Activation due to: user interrupt "ASUB in a manual mode and channel state not READY"

Activation by: VDI signal, digital-analog interface

Continued by: Freely selectable

BIT4: Activation due to: Activation due to: User interrupt "ASUB".

To continue the program with Repos, the current position at the moment of interrupt is stored.

Activation by: VDI signal, digital-analog interface

Continued by: Freely selectable

BIT5: Activation due to: Cancellation of subroutine repeat

Activation by: VDI signal

Continued by: Execution of system Asub REPOS

BIT6: Activation due to: Activation of decoding single block

Activation by: VDI signal (+OPI)

Continued by: Execution of system Asub REPOS

BIT7: Activation due to: Activation of delete distance to go

Activation by: VDI signal

Continued by: Execution of system Asub Ret

BIT8: Activation due to: Activation of axis synchronization

Activation by: VDI signal

Continued by: Execution of system Asub REPOS

BIT9: Activation due to: Mode change

Activation by: VDI signal

Continued by: Execution of system Asub REPOS or RET (see MD.)

BIT10: Activation due to: Program continuation under TeachIn or after TeachIn deactivation

Activation by: VDI signal

Continued by: Execution of system Asub Ret

BIT11: Activation due to: Overstore selection

Activation by: Pi selection

Continued by: Execution of system Asub REPOS

BIT12: Activation due to: Alarm with reaction 'offset block with Repos' (COMPBLOCKWITHREORG)

Activation by: Internal

Continued by: Execution of system Asub REPOS

BIT13: Activation due to: Retraction with G33 and Stop

Activation by: Internal

Continued by: Execution of system Asub Ret

BIT14: Activation due to: Activation of dry run feedrate

Activation by: Vdi

Continued by: Execution of system Asub REPOS

BIT15: Activation due to: Deactivation of dry run feedrate

Activation by: Vdi

Continued by: Execution of system Asub REPOS

BIT16: Activation due to: Activation of block suppression

Activation by: Vdi

Continued by: Execution of system Asub REPOS

BIT17: Activation due to: Deactivation of block suppression

Activation by: Vdi

Continued by: Execution of system Asub REPOS

BIT18: Activation due to: Activate machine data

Activation by: Pi

Continued by: Execution of system Asub REPOS

BIT19: Activation due to: Activate tool offset

Activation by: Pi "N_SETUDT"

Continued by: Execution of system Asub REPOS

Axes:							NCK Version:	13.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$P_ISTEST						Program test active			Cross. R.:
Description: \$P_ISTEST Returns TRUE (1) if program test is active.										
Axes:							NCK Version:	13.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

STRING	\$P_MMCA						Task acknowledgement for MMC command			Cross. R.:
Description: \$P_MMCA Task acknowledgement for MMC command										
Axes:							NCK Version:	13.00.00		
Unit:	-	min:					max:			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$A_PROTO						Activate logging function for 1st user			Cross. R.:
Description: \$A_PROTO Activate / deactivate logging function for the first user. Corresponds to \$A_PROTOC[0].										
Axes:							NCK Version:	13.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
	X	not classified				not classified				

1.1 List of system variables

BOOL	\$A_PROTOC[10]					Activate logging function for user			Cross. R.:	
Description: \$A_PROTOC Activate / deactivate logging function for a user. Corresponds to OPI variable protocUserActive.										
Description of array limits: Index of the user of the logging function.										
Axes:					NCK Version:			42.00.00		
Unit:		-	min:		FALSE			max:		TRUE
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:		Global				Search run			Link	
	X	not classified				not classified				

BOOL	\$A_PROT_LOCK[10]					Still to be defined			Cross. R.:	
Description: \$A_PROT_LOCK Disable / enable logging function temporarily for a user										
Description of array limits: 0 - EX_MAX_NUM_PROT_USER-1, USER										
Axes:					NCK Version:			51.04.00		
Unit:		-	min:		FALSE			max:		TRUE
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:		Global				Search run			Link	
		not classified				not classified				

DOUBLE	\$AC_FIFO1[n]				1st FIFO stack			Cross. R.:		
Description:										
Variable \$AC_FIFO1[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.										
\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10.										
The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.										
\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.										
R variables assigned to FIFO areas should not be written elsewhere.										
The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:										
$\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$										
The FIFO variable is an array variable.										
Indices 0 - 5 have special meanings:										
n = 0: When written with index 0, a new value is stored in the FIFO.										
When read with index 0, the oldest element is read and removed from the FIFO.										
n=1: Access to the first element read										
n=2: Access to the second element read										
n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set.										
n=4: Number of elements available in the FIFO										
n=5: Current write index relative to the start of the FIFO										
n=6: Oldest element										
n=7: Second oldest etc.										
Description of array limits:										
The dimension is defined in \$MC_LEN_AC_FIFO.										
Axes:						NCK Version:		13.00.00		
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AC_FIFO2[n]				2. FIFO stack			Cross. R.:		
Description:										
Variable \$AC_FIFO2[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.										
\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10.										
The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.										
\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.										
R variables assigned to FIFO areas should not be written elsewhere.										
The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:										
$\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$										
The FIFO variable is an array variable.										
Indices 0 - 5 have special meanings:										
n = 0: When written with index 0, a new value is stored in the FIFO.										
When read with index 0, the oldest element is read and removed from the FIFO.										
n=1: Access to the first element read										
n=2: Access to the second element read										
n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set.										
n=4: Number of elements available in the FIFO										
n=5: Current write index relative to the start of the FIFO										
n=6: Oldest element										
n=7: Second oldest etc.										
Description of array limits:										
The dimension is defined in \$MC_LEN_AC_FIFO.										
Axes:						NCK Version:		13.00.00		
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_FIFO3[n]				3. FIFO stack			Cross. R.:		
Description:										
Variable \$AC_FIFO3[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.										
\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10.										
The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.										
\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.										
R variables assigned to FIFO areas should not be written elsewhere.										
The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:										
$\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$										
The FIFO variable is an array variable.										
Indices 0 - 5 have special meanings:										
n = 0: When written with index 0, a new value is stored in the FIFO.										
When read with index 0, the oldest element is read and removed from the FIFO.										
n=1: Access to the first element read										
n=2: Access to the second element read										
n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set.										
n=4: Number of elements available in the FIFO										
n=5: Current write index relative to the start of the FIFO										
n=6: Oldest element										
n=7: Second oldest etc.										
Description of array limits:										
The dimension is defined in \$MC_LEN_AC_FIFO.										
Axes:						NCK Version:		13.00.00		
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AC_FIFO4[n]				4. FIFO stack				Cross. R.:	
Description:										
Variable \$AC_FIFO4[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.										
\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10.										
The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.										
\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.										
R variables assigned to FIFO areas should not be written elsewhere.										
The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:										
$\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$										
The FIFO variable is an array variable.										
Indices 0 - 5 have special meanings:										
n = 0: When written with index 0, a new value is stored in the FIFO.										
When read with index 0, the oldest element is read and removed from the FIFO.										
n=1: Access to the first element read										
n=2: Access to the second element read										
n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set.										
n=4: Number of elements available in the FIFO										
n=5: Current write index relative to the start of the FIFO										
n=6: Oldest element										
n=7: Second oldest etc.										
Description of array limits:										
The dimension is defined in \$MC_LEN_AC_FIFO.										
Axes:						NCK Version:		13.00.00		
Unit:		-		min: DBL_MIN		max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X		X	7
Attributes:		Global				Search run		Link		
		not classified				not classified				

DOUBLE	\$AC_FIFO5[n]				5. FIFO stack				Cross. R.:		
Description:											
Variable \$AC_FIFO5[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.											
\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10.											
The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.											
\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.											
R variables assigned to FIFO areas should not be written elsewhere.											
The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:											
$\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$											
The FIFO variable is an array variable.											
Indices 0 - 5 have special meanings:											
n = 0: When written with index 0, a new value is stored in the FIFO.											
When read with index 0, the oldest element is read and removed from the FIFO.											
n=1: Access to the first element read											
n=2: Access to the second element read											
n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set.											
n=4: Number of elements available in the FIFO											
n=5: Current write index relative to the start of the FIFO											
n=6: Oldest element											
n=7: Second oldest etc.											
Description of array limits:											
The dimension is defined in \$MC_LEN_AC_FIFO.											
Axes:						NCK Version:		13.00.00			
Unit:		-		min: DBL_MIN		max:		DBL_MAX			
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X	X			X	X	X	X	
write:		X	X				X	X		X	7
Attributes:		Global				Search run		Link			
		not classified				not classified					

1.1 List of system variables

DOUBLE	\$AC_FIFO6[n]				6. FIFO stack			Cross. R.:		
<p>Description:</p> <p>Variable \$AC_FIFO6[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.</p> <p>\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10. The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.</p> <p>\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.</p> <p>R variables assigned to FIFO areas should not be written elsewhere.</p> <p>The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:</p> $\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$ <p>The FIFO variable is an array variable.</p> <p>Indices 0 - 5 have special meanings:</p> <p>n = 0: When written with index 0, a new value is stored in the FIFO. When read with index 0, the oldest element is read and removed from the FIFO.</p> <p>n=1: Access to the first element read n=2: Access to the second element read n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set. n=4: Number of elements available in the FIFO n=5: Current write index relative to the start of the FIFO n=6: Oldest element n=7: Second oldest etc.</p> <p>Description of array limits:</p> <p>The dimension is defined in \$MC_LEN_AC_FIFO.</p>										
Axes:						NCK Version:		13.00.00		
Unit:		-	min: DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X		X	7
Attributes:		Global Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_FIFO7[n]				7. FIFO stack	Cross. R.:					
Description:											
Variable \$AC_FIFO7[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.											
\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10.											
The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.											
\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.											
R variables assigned to FIFO areas should not be written elsewhere.											
The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:											
$\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$											
The FIFO variable is an array variable.											
Indices 0 - 5 have special meanings:											
n = 0: When written with index 0, a new value is stored in the FIFO.											
When read with index 0, the oldest element is read and removed from the FIFO.											
n=1: Access to the first element read											
n=2: Access to the second element read											
n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set.											
n=4: Number of elements available in the FIFO											
n=5: Current write index relative to the start of the FIFO											
n=6: Oldest element											
n=7: Second oldest etc.											
Description of array limits:											
The dimension is defined in \$MC_LEN_AC_FIFO.											
Axes:						NCK Version:	13.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X				X	X		X	7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

DOUBLE	\$AC_FIFO8[n]				8. FIFO stack			Cross. R.:		
Description:										
Variable \$AC_FIFO8[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.										
\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10.										
The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.										
\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.										
R variables assigned to FIFO areas should not be written elsewhere.										
The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:										
$\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$										
The FIFO variable is an array variable.										
Indices 0 - 5 have special meanings:										
n = 0: When written with index 0, a new value is stored in the FIFO.										
When read with index 0, the oldest element is read and removed from the FIFO.										
n=1: Access to the first element read										
n=2: Access to the second element read										
n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set.										
n=4: Number of elements available in the FIFO										
n=5: Current write index relative to the start of the FIFO										
n=6: Oldest element										
n=7: Second oldest etc.										
Description of array limits:										
The dimension is defined in \$MC_LEN_AC_FIFO.										
Axes:						NCK Version:		13.00.00		
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_FIFO9[n]				9. FIFO stack				Cross. R.:		
Description:											
Variable \$AC_FIFO9[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.											
\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10.											
The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.											
\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.											
R variables assigned to FIFO areas should not be written elsewhere.											
The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:											
$\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$											
The FIFO variable is an array variable.											
Indices 0 - 5 have special meanings:											
n = 0: When written with index 0, a new value is stored in the FIFO.											
When read with index 0, the oldest element is read and removed from the FIFO.											
n=1: Access to the first element read											
n=2: Access to the second element read											
n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set.											
n=4: Number of elements available in the FIFO											
n=5: Current write index relative to the start of the FIFO											
n=6: Oldest element											
n=7: Second oldest etc.											
Description of array limits:											
The dimension is defined in \$MC_LEN_AC_FIFO.											
Axes:						NCK Version:		13.00.00			
Unit:		-		min: DBL_MIN		max:		DBL_MAX			
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X	X			X	X	X	X	
write:		X	X				X	X		X	7
Attributes:		Global		Search run			Link				
		not classified			not classified						

1.1 List of system variables

DOUBLE	\$AC_FIFO10[n]				10. FIFO stack				Cross. R.:	
Description:										
Variable \$AC_FIFO10[n] is a stack with first in first out characteristics. This stack memory can be used for cyclic measuring operations.										
\$MC_NUM_AC_FIFO is used to define the number of FIFO variables \$AC_FIFO1 - \$AC_FIFO10.										
The elements of the stack memory are saved in R variables. The length of all FIFO variables is configured with \$MC_LEN_AC_FIFO.										
\$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored.										
R variables assigned to FIFO areas should not be written elsewhere.										
The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be accommodated:										
$\$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6)$										
The FIFO variable is an array variable.										
Indices 0 - 5 have special meanings:										
n = 0: When written with index 0, a new value is stored in the FIFO.										
When read with index 0, the oldest element is read and removed from the FIFO.										
n=1: Access to the first element read										
n=2: Access to the second element read										
n=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set.										
n=4: Number of elements available in the FIFO										
n=5: Current write index relative to the start of the FIFO										
n=6: Oldest element										
n=7: Second oldest etc.										
Description of array limits:										
The dimension is defined in \$MC_LEN_AC_FIFO.										
Axes:						NCK Version:		13.00.00		
Unit:		-		min: DBL_MIN		max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X		X	7
Attributes:		Global				Search run		Link		
		not classified				not classified				

BOOL	\$A_IN[n]				Digital input				Cross. R.:	
Description:										
Variable \$A_IN[n] is used to interrogate digital inputs.										
Description of array limits:										
The dimension is defined in \$MN_FASTIO_DIG_NUM_INPUTS.										
Axes:						NCK Version:		06.00.00		
Unit:		-		min: FALSE		max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

BOOL	\$A_OUT[n]					Digital output			Cross. R.:	
Description:										
Variable \$A_OUT[n] is used to interrogate digital outputs.										
Description of array limits:										
The dimension is defined in \$MN_FASTIO_DIG_NUM_OUTPUTS.										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		FALSE			max:		TRUE
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$A_INA[n]					Analog input			Cross. R.:	
Description:										
Variable \$A_INA[n] is used to access the analog inputs.										
Description of array limits:										
The dimension is defined in \$MN_FASTIO_ANA_NUM_INPUTS.										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		DBL_MIN			max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$A_OUTA[n]					Analog output			Cross. R.:	
Description:										
Variable \$A_OUTA[n] is used to access the analog outputs. When written the value does not become operative until the next interpolator cycle and can then be read back.										
Description of array limits:										
The dimension is defined in \$MN_FASTIO_ANA_NUM_OUTPUTS.										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		DBL_MIN			max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

1.1 List of system variables

BOOL	\$A_INCO[2]					Comparator input			Cross. R.:	
Description: Variable \$A_INCO[n] is used to access the comparator inputs.										
Description of array limits: nth comparator input.										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		FALSE			max:		TRUE
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$A_DBB[1024]					PLC data byte (unsigned)			Cross. R.:	
Description: Array variable \$A_DBB[n] is used to read and write a data byte (8 bits) from PLC. The byte is unsigned and can be read in the range from 0 to 255 and written in the range from -128 to 255. A memory area is reserved in the communications buffer of these modules (DPR) for high-speed data exchange between PLC and NC. The PLC uses function calls (FC) and the NCK uses \$ variables to access this memory. See also \$A_DBSB[n].										
Description of array limits: n: Position offset within I/O area 0 - ...										
Axes:					NCK Version:			13.00.00		
Unit:		-	min:		-128			max:		255
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X		X		X	X		X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$A_DBW[1024]					PLC data word (unsigned)			Cross. R.:	
Description: Array variable \$A_DBW[n] is used to read and write a data word (16 bits) from PLC. The byte is unsigned and can be read in the range from 0 to 65535 and written in the range from -32768 to 65535. A memory area is reserved in the communications buffer of these modules (DPR) for high-speed data exchange between PLC and NC. The PLC uses function calls (FC) and the NCK uses \$ variables to access this memory. See also \$A_DBSW[n].										
Description of array limits: n: Position offset within I/O area 0 - ...										
Axes:					NCK Version:			13.00.00		
Unit:		-	min:		-32768			max:		65535
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X		X		X	X		X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$A_DBD[1024]					PLC data doubleword		Cross. R.:			
Description: Array variable \$A_DBD[n] is used to read and write a data doubleword (32 bits) from PLC. A memory area is reserved in the communications buffer of these modules (DPR) for high-speed data exchange between PLC and NC. The PLC uses function calls (FC) and the NCK uses \$ variables to access this memory.											
Description of array limits: n: Position offset within I/O area 0 - ...											
Axes:					NCK Version:		13.00.00				
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X		X		X	X		X	7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$A_DBR[1024]					PLC Real data (32 bits)		Cross. R.:			
Description: Array variable \$A_DBR[n] is used to read and write Real data (32 bits) from PLC. A memory area is reserved in the communications buffer of these modules (DPR) for high-speed data exchange between PLC and NC. The PLC uses function calls (FC) and the NCK uses \$ variables to access this memory.											
Description of array limits: n: Position offset within I/O area 0 - ...											
Axes:					NCK Version:		13.00.00				
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X		X		X	X		X	7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$A_DLB[n]					Link variable byte		Cross. R.:			
Description: Variable \$A_DLB[n] enables reading and writing of a data byte (8 bits) which can be transmitted to other channels or NCUs across the NCU link. \$MC_MM_NUM_LINKVAR_ELEMENTS is used to define the number of elements available to the user for programming link variables (\$A_DLx). The negative value range of this variable applies to write operations only. The variable can thus store negative values. Only the corresponding positive value can be read back.											
Description of array limits: The dimension is defined in \$MC_MM_SIZEOF_LINKVAR_DATA.											
Axes:					NCK Version:		14.00.00				
Unit:		-	min:	-128				max:	255		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X		X		X	X	X	X	7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

INT	\$A_DLW[n]					Link variable word			Cross. R.:		
Description: Variable \$A_DLW[n] enables reading and writing of a data word (16 bits) which can be transmitted to other channels or NCUs across the NCU link. \$MC_MM_NUM_LINKVAR_ELEMENTS is used to define the number of elements available to the user for programming link variables (\$A_DLx). The negative value range of this variable applies to write operations only. The variable can thus store negative values. Only the corresponding positive value can be read back.											
Description of array limits: The dimension is defined in \$MC_MM_SIZEOF_LINKVAR_DATA.											
Axes:							NCK Version:		14.00.00		
Unit:		-	min: -32768			max:		65535			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X		X		X	X	X	X	7	
Attributes:		Global Search run					Link				
		not classified					not classified				

INT	\$A_DLD[n]					Integer link variable			Cross. R.:		
Description: Variable \$A_DLD[n] enables reading and writing of a data doubleword (32 bits) which can be transmitted to other channels or NCUs across the NCU link. \$MC_MM_NUM_LINKVAR_ELEMENTS is used to define the number of elements available to the user for programming link variables (\$A_DLx).											
Description of array limits: The dimension is defined in \$MC_MM_SIZEOF_LINKVAR_DATA.											
Axes:							NCK Version:		14.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X		X		X	X	X	X	7	
Attributes:		Global Search run					Link				
		not classified					not classified				

DOUBLE	\$A_DLR[n]					Real link variable			Cross. R.:		
Description: Variable \$A_DLR[n] enables reading and writing of a Real value which can be transmitted to other channels or NCUs across the NCU link. \$MC_MM_NUM_LINKVAR_ELEMENTS is used to define the number of elements available to the user for programming link variables (\$A_DLx).											
Description of array limits: The dimension is defined in \$MC_MM_SIZEOF_LINKVAR_DATA.											
Axes:							NCK Version:		14.00.00		
Unit:		-	min: DBL_MIN			max:		DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X		X		X	X	X	X	7	
Attributes:		Global Search run					Link				
		not classified					not classified				

1.1 List of system variables

INT	\$A_LINK_TRANS_RATE				Link data transfer rate				Cross. R.:	
Description: Variable \$A_LINK_TRANS_RATE determines the number of bytes which can still be transferred by NCU link in the current interpolation cycle.										
Axes:				NCK Version:				15.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$A_PBB_IN[16]				PLC input byte				Cross. R.:	
Description: Array variable \$A_PBB_IN[n] is used to read and write a data byte (8 bits) from the PLC I/O.										
Description of array limits: The dimension is defined in \$MN_PLCIO_NUM_BYTES_IN.										
Axes:				NCK Version:				16.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$A_PBW_IN[16]				PLC input word				Cross. R.:	
Description: Array variable \$A_PBW_IN[n] is used to read and write a data word (16 bits) from the PLC I/O.										
Description of array limits: The dimension is defined in \$MN_PLCIO_NUM_BYTES_IN.										
Axes:				NCK Version:				16.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$A_PBD_IN[16]				PLC input doubleword				Cross. R.:	
Description:										
Array variable \$A_PBD_IN[n] is used to read a data doubleword (32 bits) from the PLC I/O.										
Description of array limits:										
The dimension is defined in \$MN_PLCIO_NUM_BYTES_IN.										
Axes:				NCK Version:				16.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global				Search run				Link
						not classified				not classified

DOUBLE	\$A_PBR_IN[16]				Real PLC input				Cross. R.:	
Description:										
Array variable \$A_PBR_IN[n] is used to read Real data (32 bits) from the PLC I/O.										
Description of array limits:										
The dimension is defined in \$MN_PLCIO_NUM_BYTES_IN.										
Axes:				NCK Version:				16.00.00		
Unit:		-	min:	DBL_MIN				max:	DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global				Search run				Link
						not classified				not classified

INT	\$A_PBB_OUT[16]				PLC output byte				Cross. R.:	
Description:										
Array variable \$A_PBB_OUT[n] is used to write a data byte (8 bits) to the PLC I/O.										
Description of array limits:										
The dimension is defined in \$MN_PLCIO_NUM_BYTES_OUT.										
Axes:				NCK Version:				16.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X		X		X	X		X	7
Attributes:		Global				Search run				Link
						not classified				not classified

1.1 List of system variables

INT	\$A_PBW_OUT[16]					PLC output word			Cross. R.:	
Description:										
Array variable \$A_PBW_OUT[n] is used to write a data word (16 bits) to the PLC I/O.										
Description of array limits:										
The dimension is defined in \$MN_PLCIO_NUM_BYTES_OUT.										
Axes:						NCK Version:		16.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X		X		X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$A_PBD_OUT[16]					PLC output doubleword			Cross. R.:	
Description:										
Array variable \$A_PBD_OUT[n] is used to write a data doubleword (32 bits) to the PLC I/O.										
Description of array limits:										
The dimension is defined in \$MN_PLCIO_NUM_BYTES_OUT.										
Axes:						NCK Version:		16.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X		X		X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$A_PBR_OUT[16]					Real PLC output			Cross. R.:	
Description:										
Array variable \$A_PBR_OUT[n] is used to write Real data (32 bits) to the PLC I/O.										
Description of array limits:										
The dimension is defined in \$MN_PLCIO_NUM_BYTES_OUT.										
Axes:						NCK Version:		16.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X		X		X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

BOOL	\$C_IN[16]					Signal from PLC to cycle			Cross. R.:	
Description: \$C_IN[n] Signal from the PLC to cycle Reserved for SIEMENS applications! 16 input signals (i.e. 2 bytes) are available. Data transfer is cyclic.										
Description of array limits: n: Number of input 1 - ...										
Axes:					NCK Version:			41.00.00		
Unit:		min:		FALSE				max:		TRUE
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

BOOL	\$C_OUT[16]					Signal from cycle to the PLC			Cross. R.:	
Description: \$C_OUT[n] Signal from cycle to the PLC Reserved for SIEMENS applications! 16 output signals (i.e. 2 bytes) are available. Data transfer is cyclic.										
Description of array limits: n: Number of output 1 - ...										
Axes:					NCK Version:			41.00.00		
Unit:		min:		FALSE				max:		TRUE
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global Search run				Link				
		not classified				not classified				

INT	\$AC_TC_CMDT					Still to be defined			Cross. R.:	
Description: \$AC_TC_CMDT Trigger variable: \$AC_TC_CMDT (CoMmadTrigger) assumes the value '1' for an interpolation cycle whenever a new command from the magazine management is output to the PLC.										
Axes:					NCK Version:			44.00.00		
Unit:		min:		INT_MIN				max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X		X	
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AC_TC_ACKT					Still to be defined			Cross. R.:	
Description: \$AC_TC_ACKT Trigger variable: \$AC_TC_ACKT (ACKnowledgeTrigger) assumes the value '1' for an interpolation cycle whenever the PLC acknowledges a TM command.										
Axes:					NCK Version:			44.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X		X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_CMDC					Still to be defined			Cross. R.:	
Description: \$AC_TC_CMDC Counter variable: \$AC_TC_CMDC (CoMmandCounter) is incremented by 1 every time the TM sends a command to the PLC.										
Axes:					NCK Version:			44.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X	X		X	X	X	X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_ACKC					Still to be defined			Cross. R.:	
Description: \$AC_TC_ACKC Counter variable: \$AC_TC_CMDC (ACKnowledgeCounter) is incremented by 1 every time the PLC acknowledges a command from the TM.										
Axes:					NCK Version:			44.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X	X		X	X	X	X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

1.1 List of system variables

INT	\$AC_TC_FCT					Still to be defined			Cross. R.:	
Description:										
\$AC_TC_FCT										
Command number. This specifies the requested operation.										
-1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			15.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
					not classified			not classified		

INT	\$AC_TC_STATUS					Still to be defined			Cross. R.:	
Description:										
\$AC_TC_STATUS										
Current status of the command - to be read via \$AC_TC_FCT.										
-1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			15.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
					not classified			not classified		

INT	\$AC_TC_THNO					Still to be defined			Cross. R.:	
Description:										
\$AC_TC_THNO										
Number of the toolholder (specifically the spindle no.) to which the new tool is to be loaded.										
-1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			15.00.00		
Unit:		-	min:					max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
					not classified			not classified		

INT	\$AC_TC_TNO					Still to be defined			Cross. R.:	
Description: \$AC_TC_TNO NCK internal T number of the new (to be loaded) tool. 0: There is no new tool. -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			15.00.00		
Unit:		-	min:		max:			INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_MMYN					Still to be defined			Cross. R.:	
Description: \$AC_TC_MMYN Home magazine number of the new (to be loaded) tool. 0: There is no new tool, or the new tool (if \$AC_TC_TNO > 0) is not loaded (manual tool). -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			49.00.00		
Unit:		-	min:		max:			INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_LMYN					Still to be defined			Cross. R.:	
Description: \$AC_TC_LMYN Home location number of the new (to be loaded) tool. 0: There is no new tool, or the new tool (if \$AC_TC_TNO > 0) is not loaded (manual tool). -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			49.00.00		
Unit:		-	min:		max:			INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

1.1 List of system variables

INT	\$AC_TC_MFN					Still to be defined			Cross. R.:	
Description: \$AC_TC_MFN Source magazine number of the new tool. 0: There is no new tool. -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			16.00.00		
Unit:		-	min:		max:			INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_LFN					Still to be defined			Cross. R.:	
Description: \$AC_TC_LFN Source location number of the new tool. 0: There is no new tool. -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			16.00.00		
Unit:		-	min:		max:			INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X		
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_MTN					Still to be defined			Cross. R.:	
Description: \$AC_TC_MTN Target magazine number of the new tool. 0: There is no new tool. -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			16.00.00		
Unit:		-	min:		max:			INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X		
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_LTN					Still to be defined			Cross. R.:	
Description: \$AC_TC_LTN Target location number of the new tool. 0: There is no new tool. -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			16.00.00		
Unit:		-	min:		max:			INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_MFO					Still to be defined			Cross. R.:	
Description: \$AC_TC_MFO Source magazine number of the old (to be replaced) tool. 0: There is no old tool. -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			16.00.00		
Unit:		-	min:		max:			INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_LFO					Still to be defined			Cross. R.:	
Description: \$AC_TC_LFO Source location number of the old (to be replaced) tool. 0: There is no old tool. -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			16.00.00		
Unit:		-	min:		max:			INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

1.1 List of system variables

INT	\$AC_TC_MTO					Still to be defined			Cross. R.:	
Description: \$AC_TC_MTO Target magazine number of the old (to be replaced) tool. 0: There is no old tool. -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			16.00.00		
Unit:		-		min:				max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_TC_LTO					Still to be defined			Cross. R.:	
Description: \$AC_TC_LTO Target location number of the old (to be replaced) tool. 0: There is no old tool. -1: No TM command is active at the instant the variable is read.										
Axes:					NCK Version:			16.00.00		
Unit:		-		min:				max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$A_YEAR					System time: year			Cross. R.:	
Description: \$A_YEAR System time year										
Axes:					NCK Version:			00.00.00		
Unit:		-		min:				max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$A_MONTH					System time: month		Cross. R.:		
Description: \$A_MONTH System time month										
Axes:					NCK Version:		06.00.00			
Unit:		-		min:		max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$A_DAY					System time: day		Cross. R.:		
Description: \$A_DAY System time day										
Axes:					NCK Version:		06.00.00			
Unit:		-		min:		max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$A_HOUR					System time: hour		Cross. R.:		
Description: \$A_HOUR System time hour										
Axes:					NCK Version:		06.00.00			
Unit:		-		min:		max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$A_MINUTE					System time: minute		Cross. R.:		
Description: \$A_MINUTE System time minute										
Axes:					NCK Version:		06.00.00			
Unit:		-		min:		max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

1.1 List of system variables

INT	\$A_SECOND					System time: second			Cross. R.:	
Description: \$A_SECOND System time second										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:			max:			INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$A_MSECOND					System time: millisecc.			Cross. R.:	
Description: \$A_MSECOND System time millisecond										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:			max:			INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$AC_TIME					Time from block start			Cross. R.:	
Description: Variable \$AC_TIME determines the time from the block start in seconds.										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:			max:			DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$AC_TIMES					Still to be defined					Cross. R.:
Description:											
\$AC_TIMES											
Time from block start (REAL) in seconds (excluding times for internally generated intermediate blocks). Each programmed block can be divided into a sequence of sub-blocks for sequential processing. \$AC_TIMES is set to zero o_n_l_y during the 1st cycle of the 1st block in the sequence. It is then incremented in seconds. The variable therefore allows time measurements to be taken over the whole block sequence.											
The variable can be accessed only from synchronized actions.											
Axes:						NCK Version:	54.00.00				
Unit:	-	min:	0			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X	X				X	X			
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AC_TIMEC					Interpolation cycles since block start					Cross. R.:
Description:											
Variable \$AC_TIMEC determines the number of interpolation cycles which have elapsed since the block start.											
Axes:						NCK Version:	06.00.00				
Unit:	-	min:	0			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X	X				X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AC_TIMESC					Still to be defined					Cross. R.:
Description:											
\$AC_TIMESC											
Time from block start (Real) in IPO cycles (excluding cycles for internally generated intermediate blocks). Each programmed block can be divided into a sequence of sub-blocks for sequential processing. \$AC_TIMESC is set to zero o_n_l_y during the 1st cycle of the 1st block in the sequence. It is then incremented in IPO cycles. The variable therefore allows time measurements to be taken over the whole block sequence.											
The variable can be accessed only from synchronized actions											
Axes:						NCK Version:	54.00.00				
Unit:	-	min:				max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X	X				X	X			
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

DOUBLE	\$AC_TIMER[1]					User timer	Cross. R.:			
Description:										
Array variable \$AC_TIMER[n] is an application-related timer. The time in seconds is counted in multiples of an interpolation cycle.										
The timer is started by assigning a value: \$AC_TIMER[n]=<start value>										
The timers can be stopped by assigning a negative value: \$AC_TIMER[n]=-1										
The current timer count can be read while the time variable is running or stopped. When the time variable is stopped by assigning -1, the last count value remains stored in the variable and can continue to be read.										
Description of array limits:										
The dimension is defined in \$MC_MM_NUM_AC_TIMER.										
Axes:						NCK Version:	13.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_PRTIME_M					Set ProgramRunTIME-Main	Cross. R.:			
Description:										
\$AC_PRTIME_M "ProgramRunTIME-Main"										
Setting (initialization) of the calculated program run time (main time)										
During a block search, the anticipated processing time of the skipped blocks in the part program can be calculated by the NCK and stored in OPI variable 'acPRTIME_M'. This value is cleared by writing a value to the variable.										
Axes:						NCK Version:	13.00.00			
Unit:	-	min:				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:										
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_PRTIME_A					Set ProgramRunTIME-Auxiliary	Cross. R.:			
Description:										
\$AC_PRTIME_A "ProgramRunTIME-Auxiliary"										
Setting (initialization) of the calculated program run time (auxiliary time)										
During a block search, the anticipated processing time (auxiliary time) of the skipped blocks in the part program can be calculated by the NCK and stored in OPI variable 'acPRTIME_A'. This value is cleared by writing a value to the variable.										
Axes:						NCK Version:	13.00.00			
Unit:	-	min:				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:										
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_PRTIME_M_INC					Increment ProgramRunTIME-Main			Cross. R.:		
Description:											
<p>\$AC_PRTIME_M_INC "ProgramRunTIME-Main-INCrement"</p> <p>Incrementation of the calculated program run time (main time)</p> <p>During a block search, the anticipated processing time of the skipped blocks in the part program can be calculated by the NCK and stored in OPI variable 'acPRTIME_M'. Since certain times (e.g. PLC times) are not considered, the calculated program runtime can be corrected by setting this variable explicitly.</p>											
Axes:							NCK Version:		13.00.00		
Unit:		-	min:					max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:											
write:		X				X				7	
Attributes:		Global	Search run			Link					
			not classified			not classified					

DOUBLE	\$AC_PRTIME_A_INC					Increment ProgramRunTIME-Aux.			Cross. R.:		
Description:											
<p>\$AC_PRTIME_A_INC "ProgramRunTIME-Auxiliary-INCrement"</p> <p>Incrementation of accumulated program run time (auxiliary time)</p> <p>During a block search, the anticipated processing time of the skipped blocks in the part program can be calculated by the NCK and stored in OPI variable 'acPRTIME_M'. Since certain times (e.g. PLC times) are not considered, the calculated program runtime can be corrected by setting this variable explicitly.</p>											
Axes:							NCK Version:		13.00.00		
Unit:		-	min:					max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:											
write:		X				X				7	
Attributes:		Global	Search run			Link					
			not classified			not classified					

DOUBLE	\$AC_PATHN					Normalized path parameter			Cross. R.:		
Description:											
<p>Variable \$AC_PATHN is a normalized path parameter whose value varies between 0 at the block start and 1 at the block end.</p>											
Axes:							NCK Version:		06.00.00		
Unit:		-	min:		0				max:		1
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:			X	X			X	X	X		
write:											
Attributes:		Global	Search run			Link					
			not classified			not classified					

1.1 List of system variables

DOUBLE	\$AC_DTBW					Distance from block start in WCS			Cross. R.:	
Description: Variable \$AC_DTBW determines the geometric distance from the block start in the workpiece coordinate system. The programmed position is used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.										
Axes:					NCK Version:			06.00.00		
Unit:	inch	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run			Link					
		not classified			not classified					

INT	\$AC_REPOS_PATH_MODE					Still to be defined			Cross. R.:	
Description: \$AC_REPOS_PATH_MODE Type of Repos mode 0 not defined. 1 == RMB Repos approach to start of interrupted block 2 == RMI Repos approach to interruption point in interrupted block 3 == RME Repos approach to end of interrupted block 4 == RMN Repos approach to next geometric point in interrupted block The variable is defined if a REPOS command is currently being executed, or if a new REPOS mode has been specified via the VDI.										
Axes:					NCK Version:			51.00.00		
Unit:	-	min:				max:		4		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run			Link					
		According to part program			not classified					

DOUBLE	\$AC_DTBB					Distance from block start in BCS			Cross. R.:	
Description: Variable \$AC_DTBB determines the geometric distance from the block start in the basic coordinate system. The programmed position is used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.										
Axes:					NCK Version:			06.00.00		
Unit:	inch	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run			Link					
		not classified			not classified					

DOUBLE	\$AC_DTEW					Distance from block end in WCS			Cross. R.:	
Description:										
Variable \$AC_DTEW determines the geometric distance from the block end in the workpiece coordinate system.										
The programmed position is used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.										
Axes:					NCK Version:			06.00.00		
Unit:		inch	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$AC_DTEB					Distance from block end in BCS			Cross. R.:	
Description:										
Variable \$AC_DTEB determines the geometric distance from the block end in the basic coordinate system.										
The programmed position is used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.										
Axes:					NCK Version:			06.00.00		
Unit:		inch	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$AC_PLTBB					Path from block start in BCS			Cross. R.:	
Description:										
Variable \$AC_PLTBB determines the path from the block start in the basic coordinate system.										
Axes:					NCK Version:			06.00.00		
Unit:		inch	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$AC_PLTEB					Path to block end in BCS			Cross. R.:	
Description:										
Variable \$AC_PLTEB determines the path to the block end in the basic coordinate system.										
Axes:					NCK Version:			06.00.00		
Unit:		inch	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

1.1 List of system variables

DOUBLE	\$AC_DELT					Path distance to go in WCS			Cross. R.:	
Description: Variable \$AC_DELT is used to read the stored path distance to go in the workpiece coordinate system after delete distance to go in motion-synchronous actions.										
Axes:					NCK Version:			06.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$P_APDV					Still to be defined			Cross. R.:	
Description: \$P_APDV Returns True if the position values which can be read with \$P_APR[X] or \$P_AEP[X] (respectively starting point or contour point in the case of smooth approach and retraction) are valid.										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$P_F					Programmed path feed			Cross. R.:	
Description: Variable \$P_F is used to read the last programmed path feed F.										
Axes:					NCK Version:			06.00.00		
Unit:	inch/min	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_F					Active programmed path feed			Cross. R.:	
Description: Variable \$AC_F is used to read the active programmed path feed F.										
Axes:					NCK Version:			20.10.00		
Unit:	inch/min	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AC_F_G0					Max. rapid traverse in block			Cross. R.:	
Description:										
Variable \$AC_F_G0 returns the maximum rapid traverse velocity in the block.										
Axes:					NCK Version:			53.00.00		
Unit:		inch/min	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X		X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$AC_OVR					Active path override			Cross. R.:	
Description:										
Variable \$AC_OVR determines the active path override.										
The path override is calculated by multiplying the operator override, the programmed override and the override defined via synchronized actions. The overall factor is limited to the maximum value defined by machine data \$MN_OVR_FACTOR_LIMIT_BIN or \$MN_OVR_FACTOR_FEEDRATE[31].										
A programmed value is included in the calculation in absolute terms.										
If a value less than 0.0 is programmed, alarm 14756 is output.										
The value of the variable must be rewritten in every interpolation cycle or else a value of 100% is applied.										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:		X					X		X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

DOUBLE	\$AC_PLC_OVR					PLC override			Cross. R.:	
Description:										
\$AC_PLC_OVR supplies the override defined by the PLC.										
Axes:					NCK Version:			54.00.00		
Unit:		-	min:				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

1.1 List of system variables

DOUBLE	\$AC_TOTAL_OVR					Overall path override			Cross. R.:	
Description:										
\$AC_TOTAL_OVR supplies the overall path override (PLC_OVR * NC_OVR).										
Axes:					NCK Version:			54.00.00		
Unit:		min:					max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:		Global			Search run			Link		
					not classified			not classified		

DOUBLE	\$AC_VC					Additive path feed override			Cross. R.:	
Description:										
\$AC_VC										
Additive path feed override for synchronized actions										
The override value must be rewritten in every lpo cycle or else a value of 0 is applied.										
The override value is ignored with an override of 0. Otherwise, the override value is applied independent of the override.										
The total feedrate cannot be made negative by an override value.										
An upper limit is applied to ensure that the maximum axis velocities and acceleration rates cannot be exceeded. The maximum feedrate is limited by \$MN_OVR_FACTOR_LIMIT_BIN, \$MN_OVR_FACTOR_FEEDRATE[30] (see machine data).										
The override value is not included in the calculation in the case of G0, G33, G331, G332 and G63.										
The variable can be accessed only from synchronized actions.										
Axes:					NCK Version:			06.00.00		
Unit:		min:		DBL_MIN			max:		DBL_MAX	
	Lin.- /angle speed.									
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X		X	
write:		X					X		X	7
Attributes:		Global			Search run			Link		
					not classified			not classified		

DOUBLE	\$AC_PATHACC					Path acceleration for real-time events			Cross. R.:	
Description:										
\$AC_PATHACC										
Defines an increased path acceleration for override changes and stop/start events.										
\$AC_PATHACC is taken into account only if the value is higher than the prepared acceleration limit.										
A value of 0 deselects the function.										
Values which cause machine axis acceleration rates twice the rate configured in \$MA_MAX_AX_ACCEL[.] are limited internally.										
Axes:					NCK Version:			45.00.00		
Unit:		min:		0.			max:		DBL_MAX	
	inch/s ²									
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:		Global			Search run			Link		
					not classified			not classified		

DOUBLE	\$AC_PATHJERK					Path jerk for real-time events			Cross. R.:	
Description: \$AC_PATHJERK Defines an increased path jerk for override changes and stop/start events. \$AC_PATHJERK is taken into account only if the value is higher than the prepared jerk limit. A value of 0 deselects the function.										
Axes:					NCK Version:			45.00.00		
Unit:	inch/s ³	min:	0.			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_VACTB					Path velocity of geometry axes			Cross. R.:	
Description: \$AC_VACTB Path velocity in the basic coordinate system. The velocity is calculated from the velocities of the geometry axes - independent of FGROUPE. The variable can be accessed only from synchronized actions										
Axes:					NCK Version:			06.00.00		
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_VACTW					WCS path velocity of geometry axes			Cross. R.:	
Description: \$AC_VACTW Path velocity in the workpiece coordinate system The velocity is calculated from the velocities of the geometry axes - independent of FGROUPE. The variable can be accessed only from synchronized actions										
Axes:					NCK Version:			06.00.00		
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$P_S[n]					Programmed spindle speed			Cross. R.:	
Description: \$P_S[n] n: Number of spindle Last programmed spindle speed										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:	Spindle					NCK Version:		06.00.00		
Unit:	Rot/min	min:				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_S[1]					Current spindle speed			Cross. R.:	
Description: \$AA_S[n] n: Number of spindle Actual spindle speed. The sign corresponds to the direction of rotation.										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:						NCK Version:		06.00.00		
Unit:	Rot/min	min:				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$P_CONSTCUT_S[n]					Programmed cutting rate			Cross. R.:	
Description: \$P_CONSTCUT_S[n] n: Number of spindle Last programmed constant cutting rate										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:						NCK Version:		42.00.00		
Unit:	ft/min	min:				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_CONSTCUT_S[n]				Current constant cutting rate				Cross. R.:	
Description: \$AC_CONSTCUT_S[n] n: Number of spindle Current constant cutting rate.										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:	Spindle				NCK Version:				42.00.00	
Unit:	ft/min	min:					max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$P_SEARCH_S[n]				Search run: speed, cutting rate				Cross. R.:	
Description: \$P_SEARCH_S[n] n: Number of spindle Last programmed spindle speed collected during block search or cutting rate										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:	Spindle				NCK Version:				20.01.00	
Unit:	Rot/min	min:					max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$P_SDIR[n]				Programmed direction of spindle rotation				Cross. R.:	
Description: \$P_SDIR[n] n: Number of spindle Last programmed direction of spindle rotation 3: CW spindle rotation, 4: CCW spindle rotation, 5: Spindle stop										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:	Spindle				NCK Version:				06.00.00	
Unit:	-	min:	3				max:	5		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AC_SDIR[n]				Current direction of spindle rotation				Cross. R.:	
Description: \$AC_SDIR[n] n: Number of spindle Current direction of spindle rotation 3: CW spindle rotation, 4: CCW spindle rotation, 5: Spindle stop										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:	Spindle				NCK Version:				06.00.00	
Unit:	-	min:	3				max:	5		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$P_SEARCH_SDIR[n]					Block search: progr. direction of spindle rotation			Cross. R.:	
Description: \$P_SEARCH_SDIR[n] n: Number of spindle Last programmed direction of spindle rotation collected during block search 3: M3 CW spindle rotation 4: M4 CCW spindle rotation 5: M5 Spindle stop -19: M19, SPOS, SPOSA spindle positioning, position and approach mode is read from SEARCH variables 70: M70 Changeover to axis mode -5: No direction of rotation programmed, not output.										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:	Spindle					NCK Version:		20.01.00		
Unit:	-	min:	3			max:	70			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$P_SMODE[n]					Spindle mode			Cross. R.:	
Description: \$P_SMODE[n] n: Number of spindle The spindle mode resulting from the last spindle programming action is returned. 0: No spindle programmed in channel, or spindle is active in another channel, or is being used by the PLC (FC18) or synchronized actions. 1: Speed control mode 2: Positioning mode 3: Synchronous mode 4: Axis mode										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:	Spindle					NCK Version:		06.00.00		
Unit:	-	min:				max:	4			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AC_SMODE[n]				Current spindle mode				Cross. R.:	
Description: \$AC_SMODE[n] n: Number of spindle Current spindle mode: 0: No spindle programmed in channel 1: Speed control mode 2: Positioning mode 3: Synchronous mode 4: Axis mode										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:	Spindle				NCK Version:				13.00.00	
Unit:	-	min:					max:	4		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$P_SGEAR[n]				Spindle: set gear stage				Cross. R.:	
Description: \$P_SGEAR[n] n: Number of spindle Spindle gear stage last programmed or requested by S programming in the case of M40 1: 1. Gear stage requested 5: 5. Gear stage requested										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:					NCK Version:				41.00.00	
Unit:	-	min:	1				max:	5		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AC_SGEAR[n]					Active spindle gear stage			Cross. R.:	
Description: \$AC_SGEAR[n] n: Number of spindle Active spindle gear stage 1: 1. Gear stage is active 5: 5. Gear stage is active										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:					NCK Version:			41.00.00		
Unit:		-	min:		1			max:		5
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$P_SAUTOGEAR[n]					Automatic gear stage change			Cross. R.:	
Description: \$P_SAUTOGEAR[n] n: Number of spindle Automatic gear stage change (M40) is programmed. 0: Gear stages are requested by M41..M45 1: Gear stage is calculated and requested according to programmed speed (S) (M40 automatic gear stage change is active)										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:					NCK Version:			41.00.00		
Unit:		-	min:					max:		1
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$P_SEARCH_SGEAR[n]				Search run: Gear stage M code				Cross. R.:	
Description: \$P_SEARCH_SGEAR[n] n: Number of spindle Last programmed gear stage M function collected during block search 40: M40 automatic gear stage change 41: M41 1st gear stage requested ... 45: M45 5th gear stage requested										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:				NCK Version:				20.01.00		
Unit:	-	min:	1				max:	5		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$P_SEARCH_SPOS[n]				Search run: Spindle position, path				Cross. R.:	
Description: \$P_SEARCH_SPOS[n] n: Number of spindle Spindle position or traversing path last programmed via M19, SPOS or SPOSA and collected during block search. Position: 0...359,999 if the value in MD 30330 MODULO_RANGE is 360.0 degrees Path: -100000000 ... 100000000 degrees. The sign specifies the direction of travel.										
Description of array limits: n: Spindle number 0 ... max. spind for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:				NCK Version:				20.01.00		
Unit:	Degrees	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$P_SEARCH_SPOSMODE[n]				Search run: Position approach mode				Cross. R.:	
Description: \$P_SEARCH_SPOSMODE[n] n: Number of spindle Position approach mode last programmed via M19, SPOS or SPOSA and collected during block search. 0: DC 1: AC 2: IC 3: DC 4: ACP 5: ACN										
Description of array limits: n: Spindle number 0 ... Max. spindle number for the spindle numbers configured in MD 35000 SPIND_ASSIGN_TO_MACHAX.										
Axes:						NCK Version:		20.01.00		
Unit:		-	min:					max:		5
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				not classified				

INT	\$P_NUM_SPINDLES				Number of spindles in channel				Cross. R.:	
Description: \$P_NUM_SPINDLES Calculates the maximum number of spindles in the channel 0: No spindle programmed in channel. 1..n: Number of spindles in channel.										
Axes:						NCK Version:		20.01.00		
Unit:		-	min:					max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

INT	\$P_MSNUM				Number of master spindle				Cross. R.:	
Description: \$P_MSNUM Returns the number of the master spindle. 0: No spindle programmed in channel 1..n: Number of master spindle										
Axes:						NCK Version:		06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AC_MSNUM					Number of master spindle			Cross. R.:	
Description: \$AC_MSNUM Returns the number of the current master spindle. 0: No spindle configured 1..n: Number of master spindle										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$P_MTHNUM					Still to be defined			Cross. R.:	
Description: \$P_MTHNUM - meaningful only when magazine management is active Returns the number of the master toolholder. 0: No master toolholder configured 1..n: Number of master toolholder										
Axes:					NCK Version:			20.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$AC_MTHNUM					Still to be defined			Cross. R.:	
Description: \$AC_MTHNUM - meaningful only when magazine management is active Returns the number of the current master toolholder: 0: No master toolholder configured 1..n: Number of master toolholder										
Axes:					NCK Version:			20.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:		Global			Search run			Link		
		not classified			not classified					

BOOL	\$P_GWPS[31]				Still to be defined	Cross. R.:				
Description: \$P_GWPS[n] Constant grinding wheel surface speed ON if TRUE										
Description of array limits: n: Spindle number										
Axes:				NCK Version:		06.00.00				
Unit:	Lin.- /angle speed.	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run			Link					
		not classified			not classified					

DOUBLE	\$AC_FCT1LL				Lower limit for 1st polynomial function	Cross. R.:				
Description: Variable \$AC_FCT1LL is used to define the lower limit for the first polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Axes:				NCK Version:		06.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run			Link					
		not classified			not classified					

DOUBLE	\$AC_FCT2LL				Lower limit for 2nd polynomial function	Cross. R.:				
Description: Variable \$AC_FCT2LL is used to define the lower limit for the second polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Axes:				NCK Version:		06.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run			Link					
		not classified			not classified					

1.1 List of system variables

DOUBLE	\$AC_FCT3LL					Lower limit for 3rd polynomial function		Cross. R.:			
Description: Variable \$AC_FCT3LL is used to define the lower limit for the third polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).											
Axes:					NCK Version:		06.00.00				
Unit:		-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X		X		
write:	X	X	X			X	X		X	7	
Attributes:		Global Search run				Link					
		not classified				not classified					

DOUBLE	\$AC_FCT1UL					Upper limit for 1st polynomial function		Cross. R.:			
Description: Variable \$AC_FCT1UL is used to define the upper limit for the first polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).											
Axes:					NCK Version:		06.00.00				
Unit:		-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X	X			X	X		X	7	
Attributes:		Global Search run				Link					
		not classified				not classified					

DOUBLE	\$AC_FCT2UL					Upper limit for 2nd polynomial function		Cross. R.:			
Description: Variable \$AC_FCT2UL is used to define the upper limit for the second polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).											
Axes:					NCK Version:		06.00.00				
Unit:		-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X	X			X	X		X	7	
Attributes:		Global Search run				Link					
		not classified				not classified					

DOUBLE	\$AC_FCT3UL					Upper limit for 3rd polynomial function		Cross. R.:		
Description: Variable \$AC_FCT3UL is used to define the upper limit for the third polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Axes:					NCK Version:		06.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_FCT1C[4]					Coefficients for 1st polynomial function		Cross. R.:		
Description: Array variable \$AC_FCT1C[n] is used to program polynomial coefficients a0 - a3 for the first polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Description of array limits: n: Degree of order of coefficient 0 - 3										
Axes:					NCK Version:		06.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_FCT2C[4]					Coefficients for 2nd polynomial function		Cross. R.:		
Description: Array variable \$AC_FCT2C[n] is used to program polynomial coefficients a0 - a3 for the second polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Description of array limits: n: Degree of order of coefficient 0 - 3										
Axes:					NCK Version:		06.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AC_FCT3C[4]				Coefficients for 3rd polynomial function			Cross. R.:		
Description: Array variable \$AC_FCT3C[n] is used to program polynomial coefficients a0 - a3 for the third polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Description of array limits: n: Degree of order of coefficient 0 - 3										
Axes:				NCK Version:			06.00.00			
Unit:		min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:		Global				Search run		Link		
		not classified				not classified				

DOUBLE	\$AC_FCTLL[n]				Lower limit of polynomial functions			Cross. R.:		
Description: Array variable \$AC_FCTLL[n] is used to define the lower limit for the nth polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Description of array limits: The dimension is defined in \$MC_MM_NUM_FCTDEF_ELEMENTS. n: Number of the polynomial										
Axes:				NCK Version:			06.00.00			
Unit:		min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global				Search run		Link		
		not classified				not classified				

DOUBLE	\$AC_FCTUL[n]				Upper limit of polynomial functions			Cross. R.:		
Description: Array variable \$AC_FCTUL[n] is used to define the upper limit for the nth polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Description of array limits: The dimension is defined in \$MC_MM_NUM_FCTDEF_ELEMENTS. n: Number of the polynomial										
Axes:				NCK Version:			06.00.00			
Unit:		min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global				Search run		Link		
		not classified				not classified				

DOUBLE	\$AC_FCT0[n]				1st coefficient of polynomial functions			Cross. R.:		
Description:										
Array variable \$AC_FCT0[n] is used to program the a0 coefficient for the nth polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Description of array limits:										
The dimension is defined in \$MC_MM_NUM_FCTDEF_ELEMENTS. n: Number of the polynomial										
Axes:				NCK Version:				06.00.00		
Unit:		-		min: DBL_MIN			max: DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_FCT1[n]				2. coefficient of polynomial functions			Cross. R.:		
Description:										
Array variable \$AC_FCT1[n] is used to program the a1 coefficient for the nth polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Description of array limits:										
The dimension is defined in \$MC_MM_NUM_FCTDEF_ELEMENTS. n: Number of the polynomial										
Axes:				NCK Version:				06.00.00		
Unit:		-		min: DBL_MIN			max: DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_FCT2[n]				3. coefficient of polynomial functions			Cross. R.:		
Description:										
Array variable \$AC_FCT2[n] is used to program the a2 coefficient for the nth polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Description of array limits:										
The dimension is defined in \$MC_MM_NUM_FCTDEF_ELEMENTS. n: Number of the polynomial										
Axes:				NCK Version:				06.00.00		
Unit:		-		min: DBL_MIN			max: DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AC_FCT3[n]				4. coefficient of polynomial functions				Cross. R.:	
Description: Array variable \$AC_FCT3[n] is used to program the a3 coefficient for the nth polynomial function. The polynomial function can also be defined by FCTDEF(polynomial no., lower limit, upper limit, a0, a1, a2, a3).										
Description of array limits: The dimension is defined in \$MC_MM_NUM_FCTDEF_ELEMENTS. n: Number of the polynomial										
Axes:				NCK Version:				06.00.00		
Unit:		-		min: DBL_MIN				max: DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global Search run				Link				
		not classified				not classified				

INT	\$AC_ALARM_STAT				Alarm responses				Cross. R.:	
Description: Variable \$AC_ALARM_STAT returns selected alarm responses. The following bits are possible: 0x04Channel status NOREADY 0x40Stop due to alarm 0x200Signal to PLC 0x11Axes in follow-up										
Axes:				NCK Version:				16.00.00		
Unit:		-		min: INT_MIN				max: INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

BOOL	\$AN_ESR_TRIGGER				Still to be defined				Cross. R.:	
Description: \$AN_ESR_TRIGGER = 1 Trigger "Extended stop and retract"										
Axes:				NCK Version:				16.00.00		
Unit:		-		min: FALSE				max: TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:		X					X		X	7
Attributes:		Global Search run				Link				
		not classified				not classified				

BOOL	\$AN_BUS_FAIL_TRIGGER					Reserved for Siemens			Cross. R.:	
Description: Reserved for Siemens										
Axes:					NCK Version:			51.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:		X					X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$AC_ESR_TRIGGER					Still to be defined			Cross. R.:	
Description: \$AC_ESR_TRIGGER = 1 Trigger "numerically controlled ESR"										
Axes:					NCK Version:			42.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:		X					X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_OPERATING_TIME					Operating time of NC programs in AUTOMATIC mode			Cross. R.:	
Description: \$AC_OPERATING_TIME measures the total operating time of all NC programs in AUTOMATIC mode between NC Start and end of program / NC Reset (in seconds) The timer is zeroed after each Power On. The measurement can be activated using channel MD 27860 \$MC_PROCESS_TIMER: Bit 0 = 1\$AC_OPERATING_TIME measurement is active. The following selection of further measurement conditions is possible: Bit 4 = 0No measurement when dryrun feed active Bit 4 = 1Measurement even when dryrun feed active Bit 5 = 0No measurement during program test Bit 5 = 1Measurement even during program test Use in NC program: IF \$AC_OPERATING_TIME < 12000 GOTOB STARTMARK										
Axes:					NCK Version:			19.00.00		
Unit:	s	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$AC_CYCLE_TIME					Execution time of the selected NC program			Cross. R.:		
Description:											
<p>\$AC_CYCLE_TIME measures the operating time of the selected NC program between NC Start and end of program/NC Reset (in seconds).</p> <p>The timer is cleared after each program start.</p> <p>The measurement can be activated using channel MD 27860 \$MC_PROCESS_TIMER: Bit 1 = 1\$AC_CYCLE_TIME measurement of current program operating time is active.</p> <p>The following selection of further measurement conditions is possible: Bit 4 = 0No measurement when dryrun feed active Bit 4 = 1Measurement even when dryrun feed active Bit 5 = 0No measurement during program test Bit 5 = 1Measurement even during program test</p> <p>Use in NC program: IF \$AC_CYCLE_TIME > 2400 GOTOF ALARM01</p>											
Axes:							NCK Version:		19.00.00		
Unit:	s	min:	DBL_MIN			max:		DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X	X			X	X	X	X	7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$AC_CUTTING_TIME					Machining time			Cross. R.:		
Description:											
<p>\$AC_CUTTING_TIME is used to measure the machining time (in seconds).</p> <p>This time is defined as the operating time of the path axes (at least one is active) excluding periods when rapid traverse is active in all NC programs between NC Start and end of program / NC Reset</p> <p>optionally including/not including active tool.</p> <p>The measurement is also interrupted whenever a dwell time is active.</p> <p>The timer is automatically reset each time the control boots with default values.</p> <p>The measurement can be activated using channel MD 27860 \$MC_PROCESS_TIMER: Bit 2 = 1\$AC_CUTTING_TIME measurement is active.</p> <p>The following selection of further measurement conditions is possible: Bit 4 = 0No measurement when dryrun feed active Bit 4 = 1Measurement even when dryrun feed active Bit 5 = 0No measurement during program test Bit 5 = 1Measurement even during program test</p> <p>Use in NC program: IF \$AC_CUTTING_TIME > 6000 GOTOF ACT_M06</p>											
Axes:							NCK Version:		19.00.00		
Unit:	s	min:	DBL_MIN			max:		DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X	X			X	X	X	X	7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$AC_REQUIRED_PARTS					Definition of the number of required workpieces			Cross. R.:	
<p>Description:</p> <p>\$AC_REQUIRED_PARTS can be used to define the number of workpieces which, when reached, causes the number of actual workpieces \$AC_ACTUAL_PARTS to be reset (workpiece target).</p> <p>Channel MD 27880 \$MC_PART_COUNTER can be used to activate the display alarm "workpiece target reached" and channel VDI signal "workpiece target reached":</p> <p>Bit 0 = 1:\$AC_REQUIRED_PARTS counter is active</p> <p>Further meaning of bit 1 only when bit 0 = 1: Bit 1 = 0: Alarm/VDI output when \$AC_ACTUAL_PARTS matches \$AC_REQUIRED_PARTS Bit 1 = 1: Alarm/VDI output when \$AC_SPECIAL_PARTS matches \$AC_REQUIRED_PARTS</p> <p>Use in NC program: \$AC_REQUIRED_PARTS = ACTUAL_LOS e.g. for defining a batch size, a daily production output ...</p>										
Axes:					NCK Version:			19.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AC_TOTAL_PARTS					Total number of all machined workpieces			Cross. R.:	
<p>Description:</p> <p>The \$AC_TOTAL_PARTS counter indicates the number of all workpieces machined since the start time. The counter is incremented by 1 when the MC command defined in channel MD 27882\$MC_PART_COUNTER_MCODE[0] is output to the PLC. The counter is automatically reset only when the control boots with default values. Channel MD 27880 \$MC_PART_COUNTER can be used to activate the timer: Bit 4 = 1: \$AC_TOTAL_PARTS counter is active</p> <p>Further meaning of bits 5-6 only when bit 4 = 1: Bit 5 = 0: The \$AC_TOTAL_PARTS counter is incremented by 1 on a VDI output of M02/M30 Bit 5 = 1: The \$AC_TOTAL_PARTS counter is incremented by 1 when the M command from MD PART_COUNTER_MCODE[0] is output. Bit 6 = 0:\$AC_TOTAL_PARTS active even during program test/block search Bit 6 = 1:No processing of \$AC_TOTAL_PARTS during program test/block search</p> <p>Use in NC program: IF \$AC_TOTAL_PARTS> SERVICE_COUNT GOTOF MARK_END</p>										
Axes:					NCK Version:			19.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$AC_ACTUAL_PARTS				Number of workpieces currently machined			Cross. R.:		
<p>Description:</p> <p>The \$AC_ACTUAL_PARTS counter records the number of all workpieces machined since the start time. When the workpiece target is reached (\$AC_REQUIRED_PARTS), the counter is automatically reset (\$AC_REQUIRED_PARTS not equal to 0).</p> <p>The counter is incremented by 1 when the MC command defined in channel MD 27882\$MC_PART_COUNTER_MCODE[1] is output to the PLC.</p> <p>The counter is automatically reset only when the control boots with default values.</p> <p>Channel MD 27880 \$MC_PART_COUNTER can be used to activate the timer: Bit 4 = 1: \$AC_TOTAL_PARTS counter is active</p> <p>Further meaning of bits 5-6 only when bit 4 = 1: Bit 5 = 0: The \$AC_TOTAL_PARTS counter is incremented by 1 on a VDI output of M02/M30 Bit 5 = 1: The \$AC_TOTAL_PARTS counter is incremented by 1 when the M command from MD PART_COUNTER_MCODE[0] is output. Bit 6 = 0:\$AC_TOTAL_PARTS active even during program test/block search Bit 6 = 1:No processing of \$AC_TOTAL_PARTS during program test/block search</p> <p>Use in NC program: IF \$AC_ACTUAL_PARTS == 0 GOTOF NEW_RUN</p>										
Axes:						NCK Version:		19.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AC_SPECIAL_PARTS				Number of workpieces counter by user			Cross. R.:		
<p>Description:</p> <p>The \$AC_SPECIAL_PARTS counter allows the user to apply his own strategy for counting workpieces. Channel MD 27880 \$MC_PART_COUNTER can be used to activate the timer: Bit 12 = 1: \$AC_SPECIAL_PARTS counter is active</p> <p>Further meaning of bits 13-15 only when bit 12 = 1: Bit 13 = 0: The \$AC_SPECIAL_PARTS counter is incremented by 1 on a VDI output of M02/M30 Bit 13 = 1: The \$AC_SPECIAL_PARTS counter is incremented by 1 when the M command from MD PART_COUNTER_MCODE[2] is output. Bit 14 = 0: \$AC_SPECIAL_PARTS active even during program test/block search Bit 14 = 1: No processing of \$AC_SPECIAL_PARTS during program test/block search</p> <p>Use in NC program: \$AC_SPECIAL_PARTS = R20</p>										
Axes:						NCK Version:		19.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$AC_G0MODE					Path traversal with G0		Cross. R.:			
Description:											
\$AC_G0MODE											
0: G0 not active											
1: G0 and linear interpolation active											
2: G0 and non-linear interpolation active.											
The response of the path axes to G0 depends on machine data											
\$MC_G0_LINEAR_MODE (Siemens mode) or \$MC_EXTERN_G0_LINEAR_MODE											
(ISO mode):											
With linear interpolation, the path axes traverse together,											
With non-linear interpolation, the path axes are traversed											
as positioning axes.											
Axes:							NCK Version:		42.00.00		
Unit:		-	min:					max:		2	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:			X					X	X	X	
write:											
Attributes:		Global	Search run					Link			
			not classified					not classified			

INT	\$AC_MEAS_SEMA					Semaphore to measurement interface		Cross. R.:			
Description:											
Variable for workpiece and tool measurement.											
Variable \$AA_MEAS_SEMA is used to synchronize measuring processes. The variable should be set to 1 before each assignment of the measurement interface and set to 0 when releasing it. Only one measurement interface is available for each channel and should be assigned only if the \$AC_MEAS_SEMA contains the value 0.											
Application:											
if (\$AC_MEAS_SEMA == 0)											
\$AC_MEAS_SEMA = 1 ; Assign measurement interface											
endif											
Axes:							NCK Version:		43.00.00		
Unit:		-	min:					max:		1	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X		X		
write:		X					X		X		7
Attributes:		Global	Search run					Link			
			not classified					not classified			

1.1 List of system variables

INT	\$AC_MEAS_LATCH[4]				Unlatch measuring points				Cross. R.:	
Description:										
Variable for workpiece and tool measurement.										
Axial variable \$AA_MEAS_LATCH[n] is used to unlatch all current axis positions with reference to a selected coordinate system. Variable \$AC_MEAS_P1_COORD is used to select the coordinate system.										
\$AC_MEAS_P4_COORD.										
Application:										
\$AA_MEAS_LATCH[0] = 1 ; Unlatch 1st measuring point of all axes										
\$AA_MEAS_LATCH[1] = 1 ; Unlatch 2nd measuring point of all axes										
\$AA_MEAS_LATCH[2] = 1 ; Unlatch 3rd measuring point of all axes										
\$AA_MEAS_LATCH[3] = 1 ; Unlatch 4th measuring point of all axes										
The unlatched measuring point is stored in \$AA_MEAS_POINT1[ax].										
Description of array limits:										
0: 1st measuring point, ... , 3: 4th measuring point										
Axes:						NCK Version:		43.00.00		
Unit:		-		min:				max:		1
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:		Global				Search run		Link		
						not classified		not classified		

INT	\$AC_MEAS_P1_COORD				Coordinate system 1st measuring point				Cross. R.:	
Description:										
Variable for workpiece and tool measurement.										
Variable \$AC_MEAS_P1_COORD is used to set the coordinate system frame for the 1st measuring point.										
Application:										
\$AC_MEAS_P1_COORD = 0 ; WCS										
\$AC_MEAS_P1_COORD = 1 ; BCS										
\$AC_MEAS_P1_COORD = 2 ; MCS										
\$AC_MEAS_P1_COORD = 3 ; SZS										
Axes:						NCK Version:		50.00.00		
Unit:		-		min:		0		max:		3
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global				Search run		Link		
						not classified		not classified		

INT	\$AC_MEAS_P2_COORD				Coordinate system 2nd measuring point			Cross. R.:		
Description: Variable for workpiece and tool measurement. Variable \$AC_MEAS_P2_COORD is used to set the coordinate system frame for the 2nd measuring point. Application: \$AC_MEAS_P2_COORD = 0 ; WCS \$AC_MEAS_P2_COORD = 1 ; BCS \$AC_MEAS_P2_COORD = 2 ; MCS \$AC_MEAS_P2_COORD = 3 ; SZS										
Axes:						NCK Version:		50.00.00		
Unit:		-	min: 0				max: 3			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes: Global		Search run				Link				
		not classified				not classified				

INT	\$AC_MEAS_P3_COORD				Coordinate system 3rd measuring point			Cross. R.:		
Description: Variable for workpiece and tool measurement. Variable \$AC_MEAS_P3_COORD is used to set the coordinate system frame for the 3rd measuring point. Application: \$AC_MEAS_P3_COORD = 0 ; WCS \$AC_MEAS_P3_COORD = 1 ; BCS \$AC_MEAS_P3_COORD = 2 ; MCS \$AC_MEAS_P3_COORD = 3 ; SZS										
Axes:						NCK Version:		50.00.00		
Unit:		-	min: 0				max: 3			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes: Global		Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AC_MEAS_P4_COORD				Coordinate system 4th measuring point			Cross. R.:		
Description: Variable for workpiece and tool measurement. Variable \$AC_MEAS_P4_COORD is used to set the coordinate system frame for the 4th measuring point. Application: \$AC_MEAS_P4_COORD = 0 ; WCS \$AC_MEAS_P4_COORD = 1 ; BCS \$AC_MEAS_P4_COORD = 2 ; MCS \$AC_MEAS_P4_COORD = 3 ; SZS										
Axes:						NCK Version:		50.00.00		
Unit:	-	min:	0			max:	3			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AC_MEAS_SET_COORD				Coordinate system of position setpoint			Cross. R.:		
Description: Variable for workpiece and tool measurement. Variable \$AC_MEAS_SET_COORD is used to set the coordinate system for the position setpoint. Application: \$AC_MEAS_SET_COORD = 0 ; WCS \$AC_MEAS_SET_COORD = 1 ; BCS \$AC_MEAS_SET_COORD = 2 ; MCS \$AC_MEAS_SET_COORD = 3 ; SZS										
Axes:						NCK Version:		50.00.00		
Unit:	-	min:	0			max:	3			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_MEAS_WP_SETANGLE				Workpiece position angle setpoint			Cross. R.:		
Description: Variable for workpiece and tool measurement. Axial variable \$AA_MEAS_WP_SETANGLE is used to define an angle setpoint for the workpiece position.										
Axes:						NCK Version:		43.00.00		
Unit:	Degrees	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_MEAS_CORNER_SETANGLE					Cutting angle setpoint for workpiece corner			Cross. R.:		
Description: Variable for workpiece and tool measurement. Variable \$AA_MEAS_CORNER_SETANGLE is used to define an angle setpoint for the corner of a workpiece.											
Axes:					NCK Version:			43.00.00			
Unit:	Degrees	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$AC_MEAS_DIR_APPROACH					Approach direction to workpiece			Cross. R.:		
Description: Variable for workpiece and tool measurement. Variable \$AA_MEAS_DIR_APPROACH is used to define the direction of approach to the workpiece. The following values are possible: 0:+x 1:-x 2:+y 3:-y 4:+z 5:-z											
Axes:					NCK Version:			43.00.00			
Unit:	-	min:	0				max:	5			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$AC_MEAS_ACT_PLANE					Working plane for workpiece			Cross. R.:		
Description: Variable for workpiece and tool measurement. Variable \$AC_MEAS_ACT_PLANE is used to define the working plane. The working plane is needed in order to define the tool orientation. The following values are possible: 0: G17 working plane x/y infeed direction z 1: G18 working plane z/x infeed direction y 2: G19 working plane y/z infeed direction x											
Axes:					NCK Version:			43.00.00			
Unit:	-	min:	0				max:	2			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

INT	\$AC_MEAS_FINE_TRANS					Fine offset			Cross. R.:	
Description:										
Variable for workpiece and tool measurement.										
When measuring workpieces, translation offsets can be entered in the fine offset component of the selected frame. Variable \$AC_MEAS_FINE_TRANS is used for this purpose.										
The following values are possible:										
0: Translation offset is entered in coarse offset										
1: Translation offset is entered in fine offset										
Axes:							NCK Version:		45.00.00	
Unit:		-		min: 0		max:		1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AC_MEAS_FRAME_SELECT				Frame selection for workpiece measurement			Cross. R.:		
<p>Description:</p> <p>Variable for workpiece and tool measurement. Variable \$AC_MEAS_FRAME_SELECT is used to select the frame in which the calculated frame is entered. The following values are possible:</p> <p>0:\$P_SETFRAME 1:\$P_PARTFRAME 2:\$P_EXTFRAME 10..25:\$P_CHBFRAME[0..15] 50..65:\$P_NCBFRAME[0..15] 100..199:\$P_IFRAME 500:\$P_TOOLFRAME 501:\$P_WPFRAME 502:\$P_TRAFRAME 503:\$P_PFRAME 504:\$P_CYCFRAME 1010..1025: \$P_CHBFRAME[0..15], when G500 is active 1050..1065: \$P_NCBFRAME[0..15], when G500 is active 2000: \$P_SETFR 2001:\$P_PARTFR 2002:\$P_EXTFR 2010..2025: \$P_CHBFR[0..15] 2050..2065: \$P_NCBFR[0..15] 2100..2199: \$P_UIFR[0..99] 2500:\$P_TOOLFR 2501:\$P_WPFR 2502:\$P_TRAFR 2504:\$P_CYCFR 3010..3025: \$P_CHBFR[0..15], when G500 is active 3050..3065: \$P_NCBFR[0..15], when G500 is active</p>										
Axes:						NCK Version:		43.00.00		
Unit:		-		min: 0		max:		3065		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AC_MEAS_CHSFR				Frame selection for system frames			Cross. R.:		
Description: Variable for workpiece and tool measurement. In order to convert a position from one coordinate system to another, \$AC_MEAS_CHSFR can be used to define the composition of the desired frame chain. The value of the variable should be selected according to the system frame bitmask \$MC_MM_SYSTEM_FRAME_MASK. Application: \$AC_MEAS_CHSFR = 'B1001' Only the system frames for preset actual value and TOROT are included in the calculation of the new overall frame.										
Axes:						NCK Version:		50.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AC_MEAS_NCBFR				Frame selection for global basic frames			Cross. R.:		
Description: Variable for workpiece and tool measurement. In order to convert a position from one coordinate system to another, \$AC_MEAS_NCBFR can be used to define the composition of the desired frame chain. The value of the variable should be interpreted as a bitmask from 0x0 to 0xFFFF for the global basic frames (up to 16 frames in total). Application: \$AC_MEAS_NCBFR = 'B11' Only the first two global basic frames are included in the calculation of the new overall frame.										
Axes:						NCK Version:		50.00.00		
Unit:	-	min:	0			max:	0xFFFF			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AC_MEAS_CHBFR					Frame selection for channel basic frames		Cross. R.:			
Description: Variable for workpiece and tool measurement. In order to convert a position from one coordinate system to another, \$AC_MEAS_CHBFR can be used to define the composition of the desired frame chain. The value of the variable should be interpreted as a bitmask from 0x0 to 0xFFFF for the channel basic frames (up to 16 frames in total). Application: \$AC_MEAS_CHBFR = 'B11' Only the first two channel basic frames are included in the calculation of the new overall frame.											
Axes:							NCK Version:		50.00.00		
Unit:		-	min:		0		max:		0xFFFF		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:		Global Search run					Link				
		not classified					not classified				

INT	\$AC_MEAS_UIFR					Frame selection for settable frames		Cross. R.:			
Description: Variable for workpiece and tool measurement. In order to convert a position from one coordinate system to another, \$AC_MEAS_UIFR can be used to define the composition of the desired frame chain. The variable range for the settable frames is from 0 to 99 (up to 100 in total). Application: \$AC_MEAS_UIFR = 1 The G54 frame is included in the calculation of the new overall frame.											
Axes:							NCK Version:		50.00.00		
Unit:		-	min:		0		max:		99		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:		Global Search run					Link				
		not classified					not classified				

INT	\$AC_MEAS_PFRAME					Frame selection for the prog. frame		Cross. R.:			
Description: Variable for workpiece and tool measurement. In order to convert a position from one coordinate system to another, \$AC_MEAS_PFRAME can be used to define the composition of the desired frame chain. The following values are allowed: \$AC_MEAS_PFRAME = 1 ; Programmable frame is not included in calculation \$AC_MEAS_PFRAME = 0 ; Programmable frame is included in calculation											
Axes:							NCK Version:		50.00.00		
Unit:		-	min:		0		max:		1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:		Global Search run					Link				
		not classified					not classified				

1.1 List of system variables

INT	\$SAC_MEAS_T_NUMBER					Tool selection		Cross. R.:		
Description:										
Variable for workpiece and tool measurement.										
Variable \$SAC_MEAS_T_NUMBER is used to select the tool for workpiece and tool measurement. The tool number of the active tool must match the selected tool. The active tool is included in the calculation when T0 is selected. If no tool is selected, the tool selected by \$SAC_MEAS_T_NUMBER is used in the calculation.										
Axes:					NCK Version:		43.00.00			
Unit:		min:		0		max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global				Search run		Link		
						not classified		not classified		

INT	\$SAC_MEAS_TOOL_MASK					Tool position		Cross. R.:		
Description:										
Variable for workpiece and tool measurement.										
Variable \$SAC_MEAS_TOOL_MASK specifies the tool position and considers the tool lengths for workpiece and tool measurement.										
The following values are possible:										
0x0:Default setting; all tool lengths are included										
0x1:The radius of the tool is not included in the calculation										
0x2:The tool position is in the x direction (G19)										
0x4:The tool position is in the y direction (G18)										
0x8:The tool position is in the z direction (G17)										
0x10:The length of the tool is not included in the calculation.										
Whether or not the radius of a milling tool is included in the calculation is determined from the tool position and direction of approach. If the direction of approach is not specified explicitly, it is derived from the selected plane. The direction of approach is in -z for G17, -y for G18 and -x for G19.										
Axes:					NCK Version:		50.00.00			
Unit:		min:		0		max:		0x10		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global				Search run		Link		
						not classified		not classified		

INT	\$AC_MEAS_D_NUMBER					Cutting edge selection			Cross. R.:	
Description:										
Variable for workpiece and tool measurement.										
Variable \$AC_MEAS_D_NUMBER is used to select the tool cutting edge for workpiece and tool measurement. The tool cutting edge number of the active tool must match the selected cutting edge. The active cutting edge is included in the calculation when D0 is selected. If no tool is selected, the cutting edge selected by \$AC_MEAS_D_NUMBER is used in the calculation.										
Axes:					NCK Version:			43.00.00		
Unit:		min:		0			max:		INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global				Search run			Link	
						not classified			not classified	

INT	\$AC_MEAS_TYPE					Measurement type selection			Cross. R.:	
Description:										
Variable for workpiece and tool measurement.										
Variable \$AA_MEAS_TYPE is used to select the type of measurement.										
The following values are possible:										
0: Default setting										
1: x edge										
2: y edge										
3: z edge										
4: Corner 1										
5: Corner 2										
6: Corner 3										
7: Corner 4										
8: Hole										
9: Shaft										
10: Tool length										
11: Tool diameter										
12: Groove										
13: Web										
14: Preset actual value memory for geo and special axes										
15: Preset actual value memory for special axes only										
16: Inclined edge										
17: Plane_Angles (2 solid angles in one plane)										
18: Plane_Normal (3 solid angles in one plane with specified setpoint)										
19: Dimension_1 (1-dimensional setpoint specification)										
20: Dimension_2 (2-dimensional setpoint specification)										
21: Dimension_3 (3-dimensional setpoint specification)										
22: ToolMagnifier (ShopTurn: Measurement of tool lengths with magnifier)										
23: ToolMarkedPos (ShopTurn: Measurement of a tool length with marked position)										
24: Coordinate transformation of a position										
25: Rectangle										
Axes:					NCK Version:			43.00.00		
Unit:		min:		0			max:		25	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global				Search run			Link	
						not classified			not classified	

1.1 List of system variables

INT	\$AC_MEAS_VALID				Validity bits of measurement variables.				Cross. R.:	
Description:										
Variable for workpiece and tool measurement.										
Variable \$AC_MEAS_VALID is used to define which system variables are valid for the current measurement. The value should be set to 0 before every measurement										
The individual bits are set implicitly when the corresponding variables are written.										
Bit 0: \$AA_MEAS_POINT1[axis]										
Bit 1: \$AA_MEAS_POINT2[axis]										
Bit 2: \$AA_MEAS_POINT3[axis]										
Bit 3: \$AA_MEAS_POINT4[axis]										
Bit 4: \$AA_MEAS_SETPOINT[axis]										
Bit 5: \$AC_MEAS_WP_SETANGLE										
Bit 6: \$AC_MEAS_CORNER_SETANGLE										
Bit 7: \$AC_MEAS_T_NUMBER										
Bit 8: \$AC_MEAS_D_NUMBER										
Bit 9: \$AC_MEAS_DIR_APPROACH										
Bit 10: \$AC_MEAS_ACT_PLANE										
Bit 11: \$AC_MEAS_FRAME_SELECT										
Bit 12: \$AC_MEAS_TYPE										
Bit 13: \$AC_MEAS_FINE_TRANS										
Bit 14: \$AA_MEAS_SETANGLE[axis]										
Bit 15: \$AC_MEAS_SCALEUNIT										
Bit 16: \$AC_MEAS_TOOL_MASK										
Bit 17: \$AC_MEAS_P1_COORD										
Bit 18: \$AC_MEAS_P2_COORD										
Bit 19: \$AC_MEAS_P3_COORD										
Bit 20: \$AC_MEAS_P4_COORD										
Bit 21: \$AC_MEAS_SET_COORD										
Bit 22: \$AC_MEAS_CHSFR										
Bit 23: \$AC_MEAS_NCBFR										
Bit 24: \$AC_MEAS_CHBFR										
Bit 25: \$AC_MEAS_UIFR										
Bit 26: \$AC_MEAS_PFRAME										
Axes:				NCK Version:				43.00.00		
Unit:		-		min:		INT_MIN		max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

FRAME	\$AC_MEAS_FRAME					Result frame for workpiece measurement			Cross. R.:	
Description: Variable for workpiece and tool measurement. Variable \$AC_MEAS_FRAME is the result frame for workpiece measurement. This frame is calculated by the MEASURE() function or a PI service and is not part of the active frame chain. The calculated result frame can then be copied into the selected frame (\$AC_MEAS_FRAME_SELECT) by the part program or a further PI service.										
Axes:					NCK Version:			43.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_MEAS_WP_ANGLE					Workpiece position angle			Cross. R.:	
Description: Variable for workpiece and tool measurement. Variable \$AC_MEAS_WP_ANGLE is the calculated workpiece position angle for workpiece measurement. The value specifies the relative position of the workpiece in the workpiece coordinate system (WCS).										
Axes:					NCK Version:			43.00.00		
Unit:	Degrees	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_MEAS_CORNER_ANGLE					Angle of a corner			Cross. R.:	
Description: Variable for workpiece and tool measurement. Variable \$AC_MEAS_CORNER_ANGLE is the calculated cutting angle of the corner for workpiece measurement.										
Axes:					NCK Version:			43.00.00		
Unit:	Degrees	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AC_MEAS_DIAMETER		Tool diameter				Cross. R.:			
Description:										
Variable for workpiece and tool measurement.										
Variable \$AC_MEAS_DIAMETER is the calculated diameter for tool measurement.										
Axes:					NCK Version:	43.00.00				
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_MEAS_TOOL_LENGTH		Tool length				Cross. R.:			
Description:										
Variable for workpiece and tool measurement.										
Variable \$AC_MEAS_TOOL_LENGTH is the calculated tool length for tool measurement.										
Axes:					NCK Version:	43.00.00				
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_MEAS_RESULTS[10]		Measurement results				Cross. R.:			
Description:										
Variable for workpiece and tool measurement.										
Array variable \$AC_MEAS_RESULTS[n] contains the calculation results. The measurement type (\$AC_MEAS_TYPE) determines which elements of the array are written.										
Description of array limits:										
Measurement results										
Axes:					NCK Version:	45.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AC_MEAS_SCALEUNIT					Measurement unit			Cross. R.:	
Description:										
Variable for workpiece and tool measurement.										
Variable \$AC_MEAS_SCALEUNIT defines the unit of measurement according to the configuration for input and output values.										
The following values are possible:										
0: Unit of measurement as configured (default setting)										
1: Unit of measurement with reference to active G code is INCH: G70/G700 METRIC: G71/G710										
Axes:					NCK Version:			48.00.00		
Unit:		-	min:		0			max:		1
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$P_CHANNO					Still to be defined			Cross. R.:	
Description:										
Interrogate current channel number.										
Axes:					NCK Version:			48.00.00		
Unit:		-	min:		1			max:		10
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AC_SERUPRO					Still to be defined			Cross. R.:	
Description:										
\$AC_SERUPRO										
Interrogate whether search type Serupro is active. (Serupro: "Block search via program test")										
Can be used in Synacts and the part program										
\$AC_SERUPRO == 0 Search type Serupro is not active										
\$AC_SERUPRO == 1 Search type Serupro is active										
Axes:					NCK Version:			48.00.00		
Unit:		-	min:					max:		1
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$AC_VACTBF					Path velocity in the BCS			Cross. R.:	
Description: \$AC_VACTBF supplies the path velocity in the basic coordinate system. FGroup and FGREF are taken into account.										
Axes:					NCK Version:			55.00.00		
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X			
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_VACTWF					Path velocity in the WCS			Cross. R.:	
Description: Path velocity in workpiece coordinate system. FGROUP and FGREF are taken into account.										
Axes:					NCK Version:			55.00.00		
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X			
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

FRAME	\$P_CHBFR0					Access to 1st channel basic frame			Cross. R.:	
Description: Access to 1st channel basic frame. Corresponds to \$P_CHBFR[0].										
Axes:					NCK Version:			56.00.00		
Geometry axis Channel axis Machine axis										
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR1					Access to 2nd channel basic frame			Cross. R.:	
Description:										
Access to 2nd channel basic frame. Corresponds to \$P_CHBFR[1].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR2					Access to 3rd channel basic frame			Cross. R.:	
Description:										
Access to 3rd channel basic frame. Corresponds to \$P_CHBFR[2].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR3					Access to 4th channel basic frame			Cross. R.:	
Description:										
Access to 4th channel basic frame. Corresponds to \$P_CHBFR[3].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_CHBFR4					Access to 5th channel basic frame			Cross. R.:	
Description:										
Access to 5th channel basic frame. Corresponds to \$P_CHBFR[4].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR5					Access to 6th channel basic frame			Cross. R.:	
Description:										
Access to 6th channel basic frame. Corresponds to \$P_CHBFR[5].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR6					Access to 7th channel basic frame			Cross. R.:	
Description:										
Access to 7th channel basic frame. Corresponds to \$P_CHBFR[6].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR7					Access to 8th channel basic frame			Cross. R.:	
Description:										
Access to 8th channel basic frame. Corresponds to \$P_CHBFR[7].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR8					Access to 9th channel basic frame			Cross. R.:	
Description:										
Access to 9th channel basic frame. Corresponds to \$P_CHBFR[8].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR9					Access to 10th channel basic frame			Cross. R.:	
Description:										
Access to 10th channel basic frame. Corresponds to \$P_CHBFR[9].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_CHBFR10					Access to 11th channel basic frame			Cross. R.:	
Description:										
Access to 11th channel basic frame. Corresponds to \$P_CHBFR[10].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR11					Access to 12th channel basic frame			Cross. R.:	
Description:										
Access to 12th channel basic frame. Corresponds to \$P_CHBFR[11].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR12					Access to 13th channel basic frame			Cross. R.:	
Description:										
Access to 13th channel basic frame. Corresponds to \$P_CHBFR[12].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_CHBFR13					Access to 14th channel basic frame			Cross. R.:	
Description:										
Access to 14th channel basic frame. Corresponds to \$P_CHBFR[13].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR14					Access to 15th channel basic frame			Cross. R.:	
Description:										
Access to 15th channel basic frame. Corresponds to \$P_CHBFR[14].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFR15					Access to 16th channel basic frame			Cross. R.:	
Description:										
Access to 16th channel basic frame. Corresponds to \$P_CHBFR[15].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_NCBFR0					Access to 1st NCU-global basic frame			Cross. R.:	
Description: Access to 1st NCU-global basic frame. Corresponds to \$P_NCBFR[0].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR1					Access to 2nd NCU-global basic frame			Cross. R.:	
Description: Access to 2nd NCU-global basic frame. Corresponds to \$P_NCBFR[1].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR2					Access to 3rd NCU-global basic frame			Cross. R.:	
Description: Access to 3rd NCU-global basic frame. Corresponds to \$P_NCBFR[2].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR3					Access to 4th NCU-global basic frame				Cross. R.:
Description:										
Access to 4th NCU-global basic frame. Corresponds to \$P_NCBFR[3].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR4					Access to 5th NCU-global basic frame				Cross. R.:
Description:										
Access to 5th NCU-global basic frame. Corresponds to \$P_NCBFR[4].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR5					Access to 6th NCU-global basic frame				Cross. R.:
Description:										
Access to 6th NCU-global basic frame. Corresponds to \$P_NCBFR[5].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_NCBFR6					Access to 7th NCU-global basic frame			Cross. R.:	
Description:										
Access to 7th NCU-global basic frame. Corresponds to \$P_NCBFR[6].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR7					Access to 8th NCU-global basic frame			Cross. R.:	
Description:										
Access to 8th NCU-global basic frame. Corresponds to \$P_NCBFR[7].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR8					Access to 9th NCU-global basic frame			Cross. R.:	
Description:										
Access to 9th NCU-global basic frame. Corresponds to \$P_NCBFR[8].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR9					Access to 10th NCU-global basic frame			Cross. R.:	
Description: Access to 10th NCU-global basic frame. Corresponds to \$P_NCBFR[9].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR10					Access to 11th NCU-global basic frame			Cross. R.:	
Description: Access to 11th NCU-global basic frame. Corresponds to \$P_NCBFR[10].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR11					Access to 12th NCU-global basic frame			Cross. R.:	
Description: Access to 12th NCU-global basic frame. Corresponds to \$P_NCBFR[11].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_NCBFR12					Access to 13th NCU-global basic frame			Cross. R.:	
Description: Access to 13th NCU-global basic frame. Corresponds to \$P_NCBFR[12].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR13					Access to 14th NCU-global basic frame			Cross. R.:	
Description: Access to 14th NCU-global basic frame. Corresponds to \$P_NCBFR[13].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR14					Access to 15th NCU-global basic frame			Cross. R.:	
Description: Access to 15th NCU-global basic frame. Corresponds to \$P_NCBFR[14].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFR15					Access to 16th NCU-global basic frame			Cross. R.:	
Description: Access to 16th NCU-global basic frame. Corresponds to \$P_NCBFR[15].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME0					Access to 1st current channel basic frame			Cross. R.:	
Description: Access to 1st current channel basic frame. Corresponds to \$P_CHBFRAME[0].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME1					Access to 2nd current channel basic frame			Cross. R.:	
Description: Access to 2nd current channel basic frame. Corresponds to \$P_CHBFRAME[1].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_CHBFRAME2					Access to 3rd current channel basic frame			Cross. R.:	
Description: Access to 3rd current channel basic frame. Corresponds to \$P_CHBFRAME[2].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME3					Access to 4th current channel basic frame			Cross. R.:	
Description: Access to 4th current channel basic frame. Corresponds to \$P_CHBFRAME[3].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME4					Access to 5th current channel basic frame			Cross. R.:	
Description: Access to 5th current channel basic frame. Corresponds to \$P_CHBFRAME[4].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME5					Access to 6th current channel basic frame			Cross. R.:	
Description: Access to 6th current channel basic frame. Corresponds to \$P_CHBFRAME[5].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME6					Access to 7th current channel basic frame			Cross. R.:	
Description: Access to 7th current channel basic frame. Corresponds to \$P_CHBFRAME[6].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME7					Access to 8th current channel basic frame			Cross. R.:	
Description: Access to 8th current channel basic frame. Corresponds to \$P_CHBFRAME[7].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_CHBFRAME8					Access to 9th current channel basic frame			Cross. R.:	
Description: Access to 9th current channel basic frame. Corresponds to \$P_CHBFRAME[8].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME9					Access to 10th current channel basic frame			Cross. R.:	
Description: Access to 10th current channel basic frame. Corresponds to \$P_CHBFRAME[9].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME10					Access to 11th current channel basic frame			Cross. R.:	
Description: Access to 11th current channel basic frame. Corresponds to \$P_CHBFRAME[10].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME11					Access to 12th current channel basic frame			Cross. R.:	
Description: Access to 12th current channel basic frame. Corresponds to \$P_CHBFRAME[11].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME12					Access to 13th current channel basic frame			Cross. R.:	
Description: Access to 13th current channel basic frame. Corresponds to \$P_CHBFRAME[12].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME13					Access to 14th current channel basic frame			Cross. R.:	
Description: Access to 14th current channel basic frame. Corresponds to \$P_CHBFRAME[13].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_CHBFRAME14					Access to 15th current channel basic frame			Cross. R.:	
Description: Access to 15th current channel basic frame. Corresponds to \$P_CHBFRAME[14].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_CHBFRAME15					Access to 16th current channel basic frame			Cross. R.:	
Description: Access to 16th current channel basic frame. Corresponds to \$P_CHBFRAME[15].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME0					1. 1st current NCU-global basic frame			Cross. R.:	
Description: Access to 1st current NCU-global basic frame. Corresponds to \$P_NCBFRAME[0].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME1					2. 1st current NCU-global basic frame		Cross. R.:		
Description:										
Access to 2nd current NCU-global basic frame. Corresponds to \$P_NCBFRAME[1].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME2					3. 1st current NCU-global basic frame		Cross. R.:		
Description:										
Access to 3rd current NCU-global basic frame. Corresponds to \$P_NCBFRAME[2].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME3					4. 1st current NCU-global basic frame		Cross. R.:		
Description:										
Access to 4th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[3].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_NCBFRAME4					5. 1st current NCU-global basic frame		Cross. R.:		
Description:										
Access to 5th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[4].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME5					6. 1st current NCU-global basic frame		Cross. R.:		
Description:										
Access to 6th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[5].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME6					7. 1st current NCU-global basic frame		Cross. R.:		
Description:										
Access to 7th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[6].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_NCBFRAME7					8. 1st current NCU-global basic frame			Cross. R.:	
Description:										
Access to 8th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[7].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME8					9. 1st current NCU-global basic frame			Cross. R.:	
Description:										
Access to 9th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[8].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME9					10. 1st current NCU-global basic frame			Cross. R.:	
Description:										
Access to 10th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[9].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

FRAME	\$P_NCBFRAME10					11. 1st current NCU-global basic frame					Cross. R.:
Description:											
Access to 11th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[10].											
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

FRAME	\$P_NCBFRAME11					12. 1st current NCU-global basic frame					Cross. R.:
Description:											
Access to 12th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[11].											
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

FRAME	\$P_NCBFRAME12					13. 1st current NCU-global basic frame					Cross. R.:
Description:											
Access to 13th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[12].											
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

FRAME	\$P_NCBFRAME13					14. 1st current NCU-global basic frame			Cross. R.:	
Description: Access to 14th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[13].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME14					15. 1st current NCU-global basic frame			Cross. R.:	
Description: Access to 15th current NCU-global basic frame. Corresponds to \$P_NCBFRAME[14].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

FRAME	\$P_NCBFRAME15					16. 1st current NCU-global basic frame			Cross. R.:	
Description: 16. 16th current NCU-global basic frame Corresponds to \$P_NCBFRAME[15].										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		56.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$P_TRAFO_CHAIN[4]				Programmed chained transformation				Cross. R.:		
Description:											
\$P_TRAFO_CHAIN[n]											
Code numbers of chained transformations of programmed TRACON according to machine data \$MC_TRAFO_TYPE_m.											
.											
Supplies the code number of the nth chained transformation of the programmed TRACON, starting with n=0.											
\$P_TRAFO_CHAIN[0] is the 1st chained transformation if a TRACON is programmed. If a TRACON command is not programmed, the code number of the programmed transformation is returned (e.g. 257 for TRANSMIT). If there is no transformation programmed, the value '0' is returned.											
\$P_TRAFO_CHAIN[1] is the 2nd chained transformation if a TRACON is programmed. Otherwise a '0' is returned.											
The same applies accordingly for \$P_TRAFO_CHAIN[2] and \$P_TRAFO_CHAIN[3].											
Description of array limits:											
n: Index of the chained transformation.											
Axes:						NCK Version:		51.06.00			
Unit:		-		min: 0		max:		INT_MAX			
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:											
Attributes:		Global				Search run		Link			
						not classified		not classified			

INT	\$AC_TRAFO_CHAIN[4]				Active chained transformation				Cross. R.:		
Description:											
\$AC_TRAFO_CHAIN[n]											
Code numbers of chained transformations of active TRACON according to machine data \$MC_TRAFO_TYPE_m.											
.											
Supplies the code number of the nth chained transformation of the active TRACON, starting with n=0.											
\$AC_TRAFO_CHAIN[0] is the 1st chained transformation if a TRACON is programmed. If a TRACON command is not active, the code number of the programmed transformation is returned (e.g. 257 for TRANSMIT). If no transformation is active, the value '0' is returned.											
\$AC_TRAFO_CHAIN[1] is the 2nd chained transformation if a TRACON is active. Otherwise a '0' is returned.											
The same applies accordingly for \$AC_TRAFO_CHAIN[2] and \$AC_TRAFO_CHAIN[3].											
Description of array limits:											
n: Index of the chained transformation.											
Axes:						NCK Version:		51.06.00			
Unit:		-		min: 0		max:		INT_MAX			
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X	X			X	X		X	
write:											
Attributes:		Global				Search run		Link			
						not classified		not classified			

DOUBLE	\$AC_MEAS_INPUT[10]					Measuring input parameter			Cross. R.:	
Description: Variable for workpiece and tool measurement. Array variable \$AC_MEAS_INPUT[n] is used to enter measuring input parameters for workpiece and tool measurement. The control effect of the parameters is documented in the measurement variants.										
Description of array limits: n=0..9: Measuring input parameter										
Axes:					NCK Version:			51.08.00		
Unit:		min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$A_DBSB[1024]					PLC data byte (signed)			Cross. R.:	
Description: Array variable \$A_DBSB[n] is used to read and write a data byte (8 bits) from PLC. The byte is signed and can be read and written in the range from -128 to 127. A memory area is reserved in the communications buffer of these modules (DPR) for high-speed data exchange between PLC and NC. The PLC uses function calls (FC) and the NCK uses \$ variables to access this memory. See also \$A_DBB[n].										
Description of array limits: n: Position offset within I/O area 0 - ...										
Axes:					NCK Version:			58.00.00		
Unit:		min:		-128			max:		127	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X		X		X	X		X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

INT	\$A_DBSW[1024]					PLC data word (signed)			Cross. R.:	
Description: Array variable \$A_DBSW[n] is used to read and write a data word (16 bits) from PLC. The word is signed and can be read and written in the range from -32768 to 32767. A memory area is reserved in the communications buffer of these modules (DPR) for high-speed data exchange between PLC and NC. The PLC uses function calls (FC) and the NCK uses \$ variables to access this memory. See also \$A_DBW[n].										
Description of array limits: n: Position offset within I/O area 0 - ...										
Axes:					NCK Version:			58.00.00		
Unit:		min:		-32768			max:		32767	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X		X		X	X		X	7
Attributes:		Global			Search run			Link		
		not classified			not classified					

1.1 List of system variables

INT	\$P_SUB_AXFCT				Substitution active				Cross. R.:	
Description:										
Returns a bitmask according to machine data \$MA_AXIS_LANG_SUB_MASK. An enabled bit means that the substitution of the corresponding function is active:										
Bit 0 = 1:Automatic gear stage change (M40) and direct gear stage change (M41-M45)										
Bit 1 = 1:Spindle positioning with SPOS/SPOSA/M19										
Axes:						NCK Version:		58.00.00		
Unit:		-	min:		0		max:		3	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global Search run				Link				
		According to part program				No restriction				

INT	\$P_SUB_GEAR				Programmed gear stage				Cross. R.:	
Description:										
Returns the programmed or calculated gear stage in the substitution subprogram of an NC language substitution configured with \$MA_AXIS_LANG_SUB_MASK. Outside the substitution subprogram, the variable returns the gear stage of the master spindle.										
Axes:						NCK Version:		58.00.00		
Unit:		-	min:		41		max:		45	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global Search run				Link				
		According to part program				No restriction				

BOOL	\$P_SUB_AUTOGEAR				Automatic gear stage change active				Cross. R.:	
Description:										
In the substitution subprogram of an NC language substitution configured with \$MA_AXIS_LANG_SUB_MASK, this variable indicates whether an automatic gear stage change (M40) was active in the part program line which initiated the substitution process. Outside the substitution process, the variable returns the current setting in the interpreter.										
Axes:						NCK Version:		58.00.00		
Unit:		-	min:		FALSE		max:		TRUE	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global Search run				Link				
		According to part program				No restriction				

AXIS	\$P_SUB_LA					Leading spindle of active coupling			Cross. R.:	
Description:										
In the substitution subprogram of an NC language substitution configured with \$MA_AXIS_LANG_SUB_MASK, this variable supplies the axis identifier of the leading spindle of the active coupling which initiated the substitution process.										
Outside the substitution process, the variable aborts program execution and triggers an alarm.										
Axes:					NCK Version:			58.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global			Search run			Link		
					According to part program			No restriction		

AXIS	\$P_SUB_CA					Following spindle of active coupling			Cross. R.:	
Description:										
In the substitution subprogram of an NC language substitution configured with \$MA_AXIS_LANG_SUB_MASK, this variable supplies the axis identifier of the following spindle of the active coupling which initiated the substitution process.										
Outside the substitution process, the variable aborts program execution and triggers an alarm.										
Axes:					NCK Version:			58.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global			Search run			Link		
					According to part program			No restriction		

STRING	\$P_BLOCKNO					Modal block number level-specific			Cross. R.:	
Description:										
\$P_BLOCKNO[n]										
Supplies the last programmed block number of program level n.										
Example:										
\$P_BLOCKNO[0]										
Supplies the modal block number of the program on program level 0 = main program name.										
MD 10284 \$MN_DISPLAY_FUNCTION_MASK Bit0 must be = 1.										
Block numbers programmed during DISPLOF cannot be read with \$P_BLOCKNO.										
Description of array limits:										
n: Defines the program level from which the block number is to be read.										
Numerical value: 0 to 11										
max. string length										
Axes:					NCK Version:			58.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:										
Attributes:		Global			Search run			Link		
					not classified			not classified		

1.1 List of system variables

INT	\$P_LINENO[12]				Line number level-specific				Cross. R.:		
Description:											
\$P_LINENO[n] Supplies the last programmed line number of program level n.											
Example: \$P_LINENO[0] Supplies the line number of the program on program level 0 = main program level.											
Description of array limits:											
n: Defines the program level from which the line number is to be read. Numerical value: 0 to 11											
Axes:				NCK Version:				58.00.00			
Unit:		-		min: INT_MIN				max:		INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:											
Attributes:		Global				Search run					Link
						not classified					not classified

INT	\$AC_AUTO_JOG_STATE				Status Jog in Auto				Cross. R.:		
Description:											
1: Automatic is selected, \$MN_JOG_MODE_MASK is set and the mode group is "BAG-Reseted". By actuating the +/- buttons or the handwheel, you can jog in Auto mode.											
2: After a JOG movement has been performed, this mode group was switched by the system to JOG. The VDI and OPI still display Automatic mode.											
0: Other											
Remark: This information covers the whole mode group and is available to each mode group channel via \$AC_AUTO_JOG_STATE.											
Axes:				NCK Version:				59.00.00			
Unit:		-		min: 0				max:		2	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X					X	X	X		
write:											
Attributes:		Global				Search run					Link
						not classified					not classified

DOUBLE	\$AC_FIFO[n,m]				FIFO stack	Cross. R.:				
Description:										
Variable \$AC_FIFO[n,m] access the n-th. first in first out stack. See also \$AC_FIFO1 .. \$AC_FIFO10. \$MC_NUM_AC_FIFO is used to define the range of n values and thus the number of FIFO Stacks \$AC_FIFO1 - \$AC_FIFO10. The elements of the stack memory are saved in R variables. The length of all FIFO stacks is configured with \$MC_LEN_AC_FIFO. \$MC_START_AC_FIFO is used to specify the number of the start R variable, from which the FIFO elements are stored. R variables assigned to FIFO areas should not be written elsewhere. The number of R variables must be set in machine data \$MC_MM_NUM_R_PARAM such that all FIFO variables can be stored: \$MC_MM_NUM_R_PARAM = \$MC_MM_START_FIFO + \$MC_NUM_AC_FIFO * (\$MC_LEN_AC_FIFO + 6) The FIFO variable is an array variable. Indices 0 - 5 have special meanings: m = 0: When written with index 0, a new value is stored in the FIFO. When read with index 0, the oldest element is read and removed from the FIFO. m=1: Access to the first element read m=2: Access to the last element read m=3: Total of all FIFO elements if Bit0 in \$MC_MM_MODE_FIFO is set. m=4: Number of elements available in the FIFO m=5: Current write index relative to the start of the FIFO m=6: Oldest element m=7: Second oldest etc.										
Description of array limits:										
The dimension is defined in \$MC_NUM_AC_FIFO. The dimension is defined in \$MC_LEN_AC_FIFO.										
Axes:						NCK Version:	60.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X				X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AC_AUXFU_M_VALUE[64]				Value of active m-auxiliary function				Cross. R.:	
Description:										
The array variable \$AC_AUXFU_M_VALUE[n] is used to read the value of the M auxiliary function that has been collected last for an auxiliary function group (search run) or output. Auxiliary functions are assigned to groups. The index corresponds to the group number decremented by one. The index 0 determines the value of the M auxiliary function output last for the first group. If an auxiliary function has not yet been output for the group specified, the variable returns the value -1. The relevant extension can be determined with the variable \$AC_AUXFU_M_EXT[n]. The variable \$AC_AUXFU_M_STATE[n] determines the current output status.										
Description of array limits:										
The index corresponds to the auxiliary function group number decremented by one.										
Axes:				NCK Version:				59.00.00		
Unit:		-		min:		INT_MIN		max:		INT_MAX
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM Acc. R.
read:		X	X	X			X	X	X	X
write:										
Attributes:		Global				Search run				Link
						not classified				not classified

INT	\$AC_AUXFU_M_EXT[64]				Extension of active m-auxiliary function				Cross. R.:	
Description:										
The array variable \$AC_AUXFU_M_EXT[n] is used to read the extension of the M auxiliary function that has been collected last for an auxiliary function group (search run) or output. Auxiliary functions are assigned to groups. The index corresponds to the group number decremented by one. The index 0 determines the extension of the M auxiliary function output last for the first group. If an auxiliary function has not yet been output for the group specified, the variable returns the value -1. The relevant value of the auxiliary function can be determined with the variable \$AC_AUXFU_M_VALUE[n]. The variable \$AC_AUXFU_M_STATE[n] determines the current output status.										
Description of array limits:										
The index corresponds to the auxiliary function group number decremented by one.										
Axes:				NCK Version:				59.00.00		
Unit:		-		min:		INT_MIN		max:		INT_MAX
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM Acc. R.
read:		X	X	X			X	X	X	X
write:										
Attributes:		Global				Search run				Link
						not classified				not classified

INT	\$AC_AUXFU_M_STATE[64]				Output state of active m-auxiliary function			Cross. R.:		
Description:										
The array variable \$AC_AUXFU_M_STATE[n] is used to read the output status of the M auxiliary function that has been collected last for an auxiliary function group (search run) or output. Auxiliary functions are assigned to groups. The index corresponds to the group number decremented by one. The index 0 determines the status of the M auxiliary function output last for the first group. If an auxiliary function has not yet been output for the group specified, the variable returns the value 0. If the value is greater than 0, the relevant auxiliary function value can be determined with the variable \$AC_AUXFU_M_VALUE[n]. The variable \$AC_AUXFU_M_EXT[n] determines the current extension of the auxiliary function.										
The variable returns the following values:										
0: Auxiliary function not available										
1: M-auxiliary function collected via search run										
2: M-auxiliary function output to the PLC										
3: M-auxiliary function output to the PLC, transfer has been acknowledged.										
4: M-auxiliary function managed by the PLC and integrated into the PLC.										
5: M-auxiliary function managed by the PLC, function has been acknowledged.										
Description of array limits:										
The index corresponds to the auxiliary function group number decremented by one.										
Axes:						NCK Version:		59.00.00		
Unit:		-		min: 0		max:		5		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$P_THREAD_PITCH				programmed thread pitch			Cross. R.:		
Description:										
\$P_THREAD_PITCH provides the lead with G33, G34, G35, G331 and G332 programmed under the address I, J or K. Value 0 is supplied in the RESET state or if no lead has been programmed. With G33, G34 and G35 a positive value is always returned. With G331 and G332, the sign results from the spindle rotation direction: positive in clockwise direction (as with M3) or negative in counterclockwise direction (as with M4).										
In the following example, \$P_THREAD_PITCH provides the value "1.5".										
N11 M4 S500										
N12 G33 Z10 K1.4										
N13 G33 Z12 K1.5										
N14 R1=\$P_THREAD_PITCH ;R1=1.5										
Axes:						NCK Version:		60.00.00		
Unit:		THREA D_PITC H		min: DBL_MIN		max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$P_THREAD_PITCH_INC				programmed thread pitch increment				Cross. R.:	
Description:										
<p>\$P_THREAD_PITCH_INC supplies the value programmed under the address F for the lead change (G34/G35). Value 0 is supplied in the RESET state or if no lead change has been programmed. The returned value is positive in the case of G34 or negative in the case of G35.</p>										
Example:										
M3 S400										
G35 F2 Z10 K5										
R1=\$P_THREAD_PITCH_INC ;R1= -2										
Axes:				NCK Version:				60.00.00		
Unit:	THREA D_PITC H_INCR EMENT	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_THREAD_PITCH				programmed thread pitch				Cross. R.:	
Description:										
<p>\$AC_THREAD_PITCH provides the lead for G33, G34, G35, G331 and G332 programmed under address I, J or K. In the RESET state or if no lead has been programmed, the value 0 is given. With G33, G34 and G35, a positive value is always returned. With G331 and G332, the sign from the spindle rotating direction is as follows: positive for clockwise rotation (as with M3) or negative for counterclockwise rotation (as with M4).</p> <p>In the following example, \$AC_THREAD_PITCH provides the value "1.5" :</p> <p>...</p>										
N11 M4 S500										
N12 G33 Z10 K1.4										
N13 G33 Z12 K1.5										
N14 R1=\$AC_THREAD_PITCH ;R1= 1.5										
Axes:				NCK Version:				60.00.00		
Unit:	THREA D_PITC H	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_THREAD_PITCH_INC				current thread pitch increment				Cross. R.:	
Description: \$AC_THREAD_PITCH_INC provides the value programmed under the address F for the lead change (G34/G35). In the RESET state or if a change in lead has not been programmed, the value 0 will be supplied.										
Example: M3 S400 G34 F4 Z10 K2 R1=\$P_THREAD_PITCH_INC ;R1= 4										
Axes:				NCK Version:				60.00.00		
Unit:	THREA D_PITC H_INCR EMENT	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_THREAD_PITCH_ACT				current thread pitch just now				Cross. R.:	
Description: \$AC_THREAD_PITCH_ACT provides the current value for the lead. This value is continuously updated in blocks with G34 or G35 according to the value programmed under F. Only with thread blocks (G33, G34, G35, G331 and G332) a value unequal zero is supplied.										
Axes:				NCK Version:				60.00.00		
Unit:	THREA D_PITC H	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$P_TOOLROT[3]					Programmed tool rotation direction			Cross. R.:	
Description: \$P_TOOLROT[n] Programmed tool rotation vector Normalized vector with length 1 and the components (n = 1, 2, 3) in the range - 1, ..., 1. 1: x-component 2: y-component 3: z-component If no tool is active, the following unit vector is returned, depending on the active plane: G17: (0, 1, 0) G18: (1, 0, 0) G19: (0, 0, 1)										
Description of array limits: n: Components 1 - 3										
Axes:						NCK Version:		60.00.00		
Unit:	-	min:	-1.0			max:	1.0			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AC_TOOLR_ACT[3]					Active tool rotation direction			Cross. R.:	
Description: \$AC_TOOLR_ACT[n] Active command rotation vector Normalized vector with length 1 and the components (n = 1, 2, 3) in the range - 1, ..., 1. 1: x-component 2: y-component 3: z-component If no tool is active, the following unit vector is returned, depending on the active plane: G17: (0, 1, 0) G18: (1, 0, 0) G19: (0, 0, 1)										
Description of array limits: n: Components 1 - 3										
Axes:						NCK Version:		60.00.00		
Unit:	-	min:	-1.0			max:	1.0			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AC_TOOLR_END[3]					End rotation direction vector					Cross. R.:
Description:											
\$AC_TOOLR_END[n]											
End rotation vector of active block											
Normalized vector with length 1 and the components (n = 1, 2, 3) in the range - 1, ..., 1.											
1: x-component											
2: y-component											
3: z-component											
If no tool is active, the following unit vector is returned, depending on the active plane:											
G17: (0, 1, 0)											
G18: (1, 0, 0)											
G19: (0, 0, 1)											
Description of array limits:											
n: Components 1 - 3											
Axes:						NCK Version:	60.00.00				
Unit:	-	min:	-1.0			max:	1.0				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$AC_TOOLR_DIFF					Remaining angle of the tool rotation direction					Cross. R.:
Description:											
\$AC_TOOLR_DIFF											
Remaining angle of tool rotation in active block in degree in the range 0 ... 180 degree.											
Axes:						NCK Version:	60.00.00				
Unit:	Degrees	min:	0.0			max:	180.0				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$VC_TOOLR[3]					Actual rotation direction vector			Cross. R.:	
Description: \$VC_TOOLR[n] Actual tool rotation Normalized vector with length 1 and the components (n = 1, 2, 3) in the range - 1, ..., 1. 1: x-component 2: y-component 3: z-component If no tool is active, the following unit vector is returned, depending on the active plane: G17: (0, 1, 0) G18: (1, 0, 0) G19: (0, 0, 1)										
Description of array limits: n: Components 1 - 3										
Axes:						NCK Version:		60.00.00		
Unit:	-	min:	-1.0			max:	1.0			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$VC_TOOLR_DIFF					Angle between set and actual rotation			Cross. R.:	
Description: \$VC_TOOLR_DIFF Angle between command and actual tool rotation in degree in the range 0 ... 180 degree.										
Axes:						NCK Version:		60.00.00		
Unit:	Degrees	min:	0.0			max:	180.0			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$VC_TOOLR_STAT					Status of actual rotation direction vector			Cross. R.:	
Description: \$VC_TOOLR_STAT Status of calculation of actual tool rotation: 0: MCS -> BCS Transformation in one ipo cycle -1: MCS -> BCS transformation not in one ipo cycle possible										
Axes:						NCK Version:		60.00.00		
Unit:	-	min:	-1			max:	0			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

BOOL	\$P_SIMUL				Simulation search run active				Cross. R.:	
Description:										
Value==TRUE										
The part program is executed in the control under the Simulation search run mode.										
The simulation search run is a search run (with calculation) which is aborted with an internal M30 once the end of the program has been reached.										
The control is internally in search run mode, the variables \$P_SEARCH, \$P_SERACH1, \$P_SEARCH2 and \$P_SERACHL are also correctly supplied.										
Parts program adjustments can be made through variables \$P_SEARCH* or \$P_SIMUL. \$P_SIMUL is designed only for adjustments restricted to the simulation search run.										
Value==FALSE No simulation search run is active.										
Axes:						NCK Version:		61.00.00		
Unit:		-		min: FALSE		max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

INT	\$P_SUB_STAT				state of substitution subroutine				Cross. R.:	
Description:										
A replacement of the tool programming has been configured (address D, DL, T or M function through which the tool change cycle is called up). \$P_SUB_STAT now permits polling to see if the substitution process is active and if the process is executed at the start or the end of the block:										
Value 0: Substitution subprogram not active										
Value 1: Substitution subprogram active, call-up at start of block										
Value 2: Substitution subprogram active, call-up at end of block										
The system variable is influenced by machine data \$MN_T_NO_FCT_CYCLE_MODE bit1 and 2.										
Axes:						NCK Version:		61.00.00		
Unit:		-		min: 0		max:		2		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		According to part program				No restriction				

1.1 List of system variables

INT	\$A_USEDND[32]				Workpiece counts for cutting edges			Cross. R.:		
Description: \$A_USEDND[toolHolder] The number of cutting edges used in tool holder s, counted since the last setpiece command, including the currently active cutting edge. toolHolder=1,...,maximum tool holder number toolHolder=0 = The master tool holder is selected Result = >0 = Number of cutting edges that have been used. Result = 0 = There have been no cuts since the last setpiece command. Result = -1 = Tool Management Tool Monitoring is not active. Result = -2 = toolHolder is not the value of a defined tool holder.										
Description of array limits: toolHolder: Spindle number / Tool holder number 1 - SLMAXMAGLOCATIONSWITHDISTANCE 0 = designates the master tool holder										
Axes:						NCK Version:		62.00.00		
Unit:		-		min: 0		max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$A_USEDT[32,1500]				Workpiece counts for cutting edges			Cross. R.:		
Description: \$A_USEDT[toolHolder, usedCuttingEdgeIndex] T-Number for the i-th cutting edge used with tool holder s since the last setpiece command, including the currently active cutting edge. toolHolder=1,...,maximum tool holder number toolHolder=0 = The master tool holder is selected Result = >0 = T-Number (can occur several times) (if different D-corrections of the tool were used). Result = 0 = There have been no cuts since the last setpiece command. Result = -1 = Tool Management Tool Monitoring is not active. Result = -2 = toolHolder is not the value of a defined tool holder.										
Description of array limits: toolHolder: Spindle number / Tool holder number 1 - SLMAXMAGLOCATIONSWITHDISTANCE 0 = designates the master tool holder usedCuttingEdgeIndex: index 1 - \$A_USEDND[toolHolder]										
Axes:						NCK Version:		62.00.00		
Unit:		-		min: 0		max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$A_USEDDD[32,1500]				Workpiece counts for cutting edges				Cross. R.:	
Description: \$A_USEDDD[toolHolder, usedCuttingEdgeIndex] D-Number for the i-th cutting edge used with tool holder s since the last setpiece command, including the currently active cutting edge. toolHolder=1,...,maximum tool holder number toolHolder=0 = The master tool holder is selected Result = >0 = D-Number (can occur several times) (if different D-corrections of the tool were used). Result = 0 = There have been no cuts since the last setpiece command. Result = -1 = Tool Management Tool Monitoring is not active. Result = -2 = toolHolder is not the value of a defined tool holder.										
Description of array limits: toolHolder: Spindle number / Tool holder number 1 - SLMAXMAGLOCATIONSWITHDISTANCE 0 = designates the master tool holder usedCuttingEdgeIndex: index 1 - \$A_USEDND[toolHolder]										
Axes:						NCK Version:		62.00.00		
Unit:	-	min:	0				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1.5 Toolholder data

DOUBLE	\$TC_CARR1[n]				Still to be defined				Cross. R.:	
Description: \$TC_CARR1[n] x component of offset vector I1 Attention! All system parameters beginning with '\$TC_' are parameters belonging to the TOA area. The special characteristic of this area is that machine data 28085 = MM_LINK_TOA_UNIT can be set to allow different NCK channels to access these parameters. If this type of parameter setting has been selected by the NCK, you must be aware that changing these data can have a negative impact on other channels. Before you change any data settings, make sure that the changes will have only a local effect on the channel in which they are made.										
Description of array limits: The maximum number of toolholders can be set in \$MN_MM_NUM_TOOL_CARRIER. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:						NCK Version:		13.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_CARR2[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR2[n] y component of offset vector I1										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR3[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR3[n] z component of offset vector I1										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR4[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR4[n] x component of offset vector I2										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR5[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR5[n] y component of offset vector I2										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR6[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR6[n] z component of offset vector I2										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR7[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR7[n] x component of rotary axis v1										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_CARR8[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR8[n] y component of rotary axis v1										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR9[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR9[n] z component of rotary axis v1										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR10[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR10[n] x component of rotary axis v2										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR11[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR11[n] y component of rotary axis v2										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

DOUBLE	\$TC_CARR12[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR12[n] z component of rotary axis v2										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

DOUBLE	\$TC_CARR13[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR13[n] Angle of rotation alpha1 (in degrees)										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

1.1 List of system variables

DOUBLE	\$TC_CARR14[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR14[n] Angle of rotation alpha2 (in degrees)										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR15[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR15[n] x component of offset vector I3										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			13.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR16[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR16[n] y component of offset vector I3										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			14.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR17[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR17[n] z component of offset vector I3										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			14.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR18[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR18[n] x component of offset vector I4										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			14.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR19[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR19[n] y component of offset vector I4										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			20.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_CARR20[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR20[n] z component of offset vector I4										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			20.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

AXIS	\$TC_CARR21[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR21[n] Axis identifier of 1st rotary axis										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			20.00.00		
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

AXIS	\$TC_CARR22[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR22[n] Axis identifier of 2nd rotary axis										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			20.00.00		
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

CHAR	\$TC_CARR23[n]				Still to be defined	Cross. R.:				
Description: \$TC_CARR23[n] Type of kinematics: P: Rotatable workpiece (Part) M: Rotatable tool and rotatable workpiece (Mixed) T or any other character apart from P and M: Rotatable tool										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = T, i.e. toolholder with orientatable tool.										
Axes:					NCK Version:	20.00.00				
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

DOUBLE	\$TC_CARR24[n]				Still to be defined	Cross. R.:				
Description: \$TC_CARR24[n] Offset of 1st rotary axis in degrees Specifies the angle in degrees of the 1st rotary axis at which the axis assumes its initial position.										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:	43.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

1.1 List of system variables

DOUBLE	\$TC_CARR25[n]					Still to be defined	Cross. R.:			
Description: \$TC_CARR25[n] Offset of 2nd rotary axis in degrees Specifies the angle in degrees of the 2nd rotary axis at which the axis assumes its initial position.										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:						NCK Version:	43.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR26[n]					Still to be defined	Cross. R.:			
Description: \$TC_CARR26[n] Specifies the offset of the 1st rotary axis if its position is not continuously variable (Hirth tooth system). It is evaluated only if \$TC_CARR28 is set to a value other than zero. For exact meanings, please refer to the description of \$TC_CARR28										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:						NCK Version:	43.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR27[n]					Still to be defined	Cross. R.:			
Description:										
<p>\$TC_CARR27[n] Specifies the offset of the 1st rotary axis if its position is not continuously variable (Hirth tooth system). It is evaluated only if \$TC_CARR29 is set to a value other than zero. For exact meanings, please refer to the description of \$TC_CARR29</p>										
Description of array limits:										
<p>The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.</p>										
Axes:						NCK Version:	43.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR28[n]					Still to be defined	Cross. R.:			
Description:										
<p>\$TC_CARR28[n] Specifies the size of the minimum increment (in degrees) by which the rotary axis can change position (e.g. for Hirth tooth systems). A programmed or calculated angle is rounded to the nearest value calculated from $\phi = s + n * d$ when n is an integer.</p> <p>In this equation $s = \\$TC_CARR28$ $d = \\$TC_CARR26$ If \$TC_CARR28 equals zero, \$TC_CARR26 and \$TC_CARR28 are not used. The settings in machine data \$MC_TOCARR_ROT_ANGLE_INCR[i] and \$MC_TOCARR_ROT_ANGLE_OFFSET[i] are applied instead.</p>										
Description of array limits:										
<p>The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.</p>										
Axes:						NCK Version:	43.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_CARR29[n]					Still to be defined	Cross. R.:			
Description:										
<p>\$TC_CARR29[n] Specifies the size of the minimum increment (in degrees) by which the second rotary axis can change position (e.g. for Hirth tooth systems). A programmed or calculated angle is rounded to the nearest value calculated from $\phi = s + n * d$ when n is an integer.</p> <p>In this equation $s = \\$TC_CARR29$ $d = \\$TC_CARR27$ If $\\$TC_CARR29$ equals zero, $\\$TC_CARR28$ and $\\$TC_CARR29$ are not used. The settings in machine data $\\$MC_TOCARR_ROT_ANGLE_INCR[i]$ and $\\$MC_TOCARR_ROT_ANGLE_OFFSET[i]$ are applied instead.</p>										
Description of array limits:										
The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:						NCK Version:	43.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR30[n]					Still to be defined	Cross. R.:			
Description:										
<p>\$TC_CARR30[n] Specifies the minimum position of the 1st rotary axis. Zu vollstaendigen For description, see $\\$TC_CARR32$</p>										
Description of array limits:										
The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:						NCK Version:	43.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR31[n]					Still to be defined	Cross. R.:			
Description: \$TC_CARR31[n] Specifies the minimum position of the 2nd rotary axis. Zu vollstaendigen For description, see \$TC_CARR33										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:						NCK Version:	43.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR32[n]					Still to be defined	Cross. R.:			
Description: \$TC_CARR32[n] Specifies the maximum position of the 1st rotary axis. When the angle of the 1st rotary axis of an orientatable toolholder aligned according to a frame (TCOFR) is calculated, the only acceptable solutions are those which lie within the \$TC_CARR30 to \$TC_CARR32 range. The same applies when the rotary angle is programmed absolutely (TCOABS). If both \$TC_CARR30 and \$TC_CARR32 equal zero, the limits are not evaluated.										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:						NCK Version:	43.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_CARR33[n]				Still to be defined	Cross. R.:				
Description:										
<p>\$TC_CARR33[n] Specifies the maximum position of the 2nd rotary axis. When the angle of the 2nd rotary axis of an orientatable toolholder aligned according to a frame (TCOFR) is calculated, the only acceptable solutions are those which lie within the \$TC_CARR31 to \$TC_CARR33 range. The same applies when the rotary angle is programmed absolutely (TCOABS). If both \$TC_CARR31 and \$TC_CARR33 equal zero, the limits are not evaluated.</p>										
Description of array limits:										
<p>The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.</p>										
Axes:					NCK Version:	43.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

STRING	\$TC_CARR34[n,MAX_STRINGLEN GTH]				Still to be defined	Cross. R.:				
Description:										
<p>\$TC_CARR34[n] Contains a freely definable string. This is provided as a free identifier for the orientatable toolholder. Within the NCK, however, it has no significance at all and is therefore not evaluated. This identifier should not be used for other purposes as it may be used in a future upgrade to allow the activation of an orientatable toolholder via a name rather than a number.</p>										
Description of array limits:										
<p>The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK. max. string length</p>										
Axes:					NCK Version:	48.00.00				
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

STRING	\$TC_CARR35[n,MAX_STRINGLEN GTH]					Still to be defined	Cross. R.:			
Description: \$TC_CARR35[n] Contains a freely definable string. This is provided as a free identifier for the first rotary axis. Within the NCK, however, it has no significance at all and is therefore not evaluated. It can also be used for any other purpose.										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK. max. string length										
Axes:						NCK Version:	48.00.00			
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

STRING	\$TC_CARR36[n,MAX_STRINGLEN GTH]					Still to be defined	Cross. R.:			
Description: \$TC_CARR36[n] Contains a freely definable string. This is provided as a free identifier for the second rotary axis. Within the NCK, however, it has no significance at all and is therefore not evaluated. It can also be used for any other purpose.										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK. max. string length										
Axes:						NCK Version:	48.00.00			
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$TC_CARR37[n]				Still to be defined	Cross. R.:				
Description: \$TC_CARR37[n] Contains an integer number for identifying the toolholder. Within the NCK, however, it has no significance at all and is therefore not evaluated.										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:	48.00.00				
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

DOUBLE	\$TC_CARR38[n]				Still to be defined	Cross. R.:				
Description: \$TC_CARR38[n] Contains a position (X component of retraction position) Within the NCK, however, it has no significance at all and is therefore not evaluated.										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:	48.00.00				
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

DOUBLE	\$TC_CARR39[n]					Still to be defined	Cross. R.:			
Description: \$TC_CARR39[n] Contains a position (Y component of retraction position) Within the NCK, however, it has no significance at all and is therefore not evaluated.										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:						NCK Version:	48.00.00			
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR40[n]					Still to be defined	Cross. R.:			
Description: \$TC_CARR40[n] Contains a position (X component of retraction position) Within the NCK, however, it has no significance at all and is therefore not evaluated.										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:						NCK Version:	48.00.00			
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_CARR41[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR41[n] x component of fine offset of offset vector I1										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR42[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR42[n] y component of fine offset of offset vector I1										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR43[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR43[n] z component of fine offset of offset vector I1										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR44[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR44[n] x component of fine offset of offset vector I2										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR45[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR45[n] y component of fine offset of offset vector I2										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR46[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR46[n] x component of fine offset of offset vector I2										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_CARR55[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR55[n] x component of fine offset of offset vector I3										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR56[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR56[n] y component of fine offset of offset vector I3										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR57[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR57[n] z component of fine offset of offset vector I3										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR58[n]					Still to be defined					Cross. R.:
Description: \$TC_CARR58[n] x component of fine offset of offset vector I4											
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.											
Axes:					NCK Version:					52.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_CARR59[n]					Still to be defined					Cross. R.:
Description: \$TC_CARR59[n] y component of fine offset of offset vector I4											
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.											
Axes:					NCK Version:					52.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_CARR60[n]					Still to be defined					Cross. R.:
Description: \$TC_CARR60[n] z component of fine offset of offset vector I4											
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.											
Axes:					NCK Version:					52.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$TC_CARR64[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR64[n] Fine offset of offset (\$TC_CARR24) of 1st rotary axis in degrees										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:		-	min:		DBL_MIN			max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_CARR65[n]					Still to be defined			Cross. R.:	
Description: \$TC_CARR65[n] Fine offset of offset (\$TC_CARR25) of 2nd rotary axis in degrees										
Description of array limits: The maximum number of toolholders can be set in machine data. The default setting is = 0, i.e. no data of this type are configured on the NCK.										
Axes:					NCK Version:			52.00.00		
Unit:		-	min:		DBL_MIN			max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1.6 Channel-specific protection zones

BOOL	\$SC_PA_ACTIV_IMMED[n]					Protection zone immediately active			Cross. R.:	
Description: \$SC_PA_ACTIV_IMMED[n] Protection zone immediately active after boot TRUE: The protection zone is activated immediately the control has booted and the axes have been referenced FALSE: The protection zone is not immediately active Note: This variable can only be written as a system variable and is not affected by the NC commands between NPROTDEF(..) and EXECUTE(n). Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_NCK_PRO , _N_COMPLETE_PRO and _N_INITIAL_INI										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN .										
Axes:							NCK Version:		06.00.00	
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

CHAR	\$SC_PA_T_W[n]					Protection zone specific to workpiece/tool			Cross. R.:	
Description: \$SC_PA_T_W[n] Protection zone specific to workpiece/tool 0: Workpiece-specific protection zone 3: Tool-specific protection zone Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO , _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN .										
Axes:							NCK Version:		06.00.00	
Unit:	-	min:	0			max:	3			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$SC_PA_ORI[n]				Orientation of protection zone				Cross. R.:	
Description: \$SC_PA_ORI[n] Orientation of protection zone 0: Polygon definition in the plane from the 1st and 2nd geo axes (G17) 1: Polygon definition in the plane from the 3rd and 1st geo axes (G18) 2: Polygon definition in the plane from the 2nd and 3rd geo axes (G19) Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN.										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	0				max:	2		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$SC_PA_LIM_3DIM[n]				Scope of application-limiting protection zone				Cross. R.:	
Description: \$SC_PA_LIM_3DIM[n] Identifier for limitation of protection zone in the axis perpendicular to the polygon definition 0: No limitation 1: Limitation in the positive direction 2: Limitation in the negative direction 3: Limitation in both directions Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN.										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	0				max:	3		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$SC_PA_PLUS_LIM[n]				Limitation of protection zone applicate plus				Cross. R.:	
Description: \$SC_PA_PLUS_LIM[n] Positive limitation of protection zones in the axis perpendicular to the polygon definition. Effective only if \$SC_PA_LIM_3DIM[n]=1 or = 3. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN.										
Axes:						NCK Version:		06.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$SC_PA_MINUS_LIM[n]				Limitation of protection zone applicate minus				Cross. R.:	
Description: \$SC_PA_MINUS_LIM[n] Negative limitation of protection zone in minus direction in the axis perpendicular to the polygon definition. Effective only if \$SC_PA_LIM_3DIM[n]=2 or = 3. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN.										
Axes:						NCK Version:		06.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$SC_PA_CONT_NUM[n]				Number of valid contour elements				Cross. R.:	
Description: \$SC_PA_CONT_NUM[n] Number of valid contour elements Protection zones need at least 2 contour elements for a complete description. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN.										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	0				max:	10		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$SC_PA_CONT_TYP[n,m]				Type of the contour element				Cross. R.:	
Description: \$SC_PA_CONT_TYP"[n,m] Type (G1, G2, G3) of contour element =0: Contour not defined =1: Straight =2: Circle element (clockwise) =3: Circle element (counterclockwise) The end point is determined by \$SC_PA_CONT_ORD or \$SC_PA_CONT_ABS. With contour types G2 and G3, \$SC_PA_CENT_ORD or \$SC_PA_CENT_ABS determines the center point of the circle element. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	0				max:	3		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$SC_PA_CONT_ORD[n,m]					End point of contour element (ordinate)			Cross. R.:	
<p>Description: \$SC_PA_CONT_ORD[n,m] End point of contour element (ordinate) See also description of \$SC_PA_CONT_TYP</p> <p>Note: This variable is not restored during REORG.</p> <p>Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.</p> <p>Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)</p>										
Axes:							NCK Version:		06.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$SC_PA_CONT_ABS[n,m]					End point of contour element (abscissa)			Cross. R.:	
<p>Description: \$SC_PA_CONT_ABS[n,m] End point of contour element (abscissa) See also description of \$SC_PA_CONT_TYP</p> <p>Note: This variable is not restored during REORG.</p> <p>Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.</p> <p>Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)</p>										
Axes:							NCK Version:		06.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$SC_PA_CENT_ORD[n,m]					Center point of contour element (ordinate)		Cross. R.:			
Description: \$SC_PA_CENT_ORD[n,m] Center point of contour element (ordinate) Relevant only if \$SC_PA_CONT_TYP[n,m] = 2 or = 3. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.											
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)											
Axes:							NCK Version:		06.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$SC_PA_CENT_ABS[n,m]					Center point of contour element (abscissa)		Cross. R.:			
Description: \$SC_PA_CENT_ABS[n,m] Center point of contour element (abscissa) Relevant only if \$SC_PA_CONT_TYP[n,m] = 2 or = 3. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_CHAx_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI CHAx: x=channel no.											
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_CHAN. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)											
Axes:							NCK Version:		06.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1.7 Tool parameters

INT	\$TC_DP1[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DP1[t,d] Tool type When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP1[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DP2[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DP2[t,d] Tool point direction When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP2[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	DBL_MIN				max:	DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_DP3[32000,32000]				Still to be defined				Cross. R.:	
Description: \$TC_DP3[t,d] Geometry - length 1 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP3[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:				NCK Version:				06.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DP4[32000,32000]				Still to be defined				Cross. R.:	
Description: \$TC_DP4[t,d] Geometry - length 2 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP4[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:				NCK Version:				06.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DP5[32000,32000]				Still to be defined				Cross. R.:	
Description: \$TC_DP5[t,d] Geometry - length 3 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP5[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:				NCK Version:				06.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DP6[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_DP6[t,d] Geometry - radius When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP6[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		inch	min:		DBL_MIN			max:		DBL_MAX	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global			Search run			Link			
					not classified			No restriction			

DOUBLE	\$TC_DP7[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_DP7[t,d] Slotting saw: Corner radius When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP7[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		inch	min:		DBL_MIN			max:		DBL_MAX	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global			Search run			Link			
					not classified			No restriction			

DOUBLE	\$TC_DP8[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_DP8[t,d] Slotting saw: Length When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP8[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		inch	min:		DBL_MIN			max:		DBL_MAX	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global			Search run			Link			
					not classified			No restriction			

1.1 List of system variables

DOUBLE	\$TC_DP9[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_DP9[t,d] Reserved When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP9[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		inch	min:		DBL_MIN			max:		DBL_MAX	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global			Search run			Link			
					not classified			No restriction			

DOUBLE	\$TC_DP10[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_DP10[t,d] Angle between tool face and toroidal surface When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP10[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		-	min:		DBL_MIN			max:		DBL_MAX	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global			Search run			Link			
					not classified			No restriction			

DOUBLE	\$TC_DP11[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_DP11[t,d] Angle between tool longitudinal axis and upper end of toroidal surface When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP11[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		-	min:		DBL_MIN			max:		DBL_MAX	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global			Search run			Link			
					not classified			No restriction			

DOUBLE	\$TC_DP12[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_DP12[t,d] Wear - length 1 - \$TC_DP3 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP12[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		inch	min:		DBL_MIN			max:		DBL_MAX	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global					Search run			Link	
							not classified			No restriction	

DOUBLE	\$TC_DP13[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_DP13[t,d] Wear - length 2 - \$TC_DP4 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP13[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		inch	min:		DBL_MIN			max:		DBL_MAX	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global					Search run			Link	
							not classified			No restriction	

DOUBLE	\$TC_DP14[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_DP14[t,d] Wear - length 3 - \$TC_DP5 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP14[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		inch	min:		DBL_MIN			max:		DBL_MAX	
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global					Search run			Link	
							not classified			No restriction	

1.1 List of system variables

DOUBLE	\$TC_DP15[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DP15[t,d] Wear - radius - \$TC_DP6 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP15[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	inch	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DP16[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DP16[t,d] Slotting saw: Wear - corner radius - \$TC_DP7 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP16[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	inch	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DP17[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DP17[t,d] Slotting saw: Wear length - \$TC_DP8 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP17[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	inch	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DP18[32000,32000]					Still to be defined					Cross. R.:
Description: \$TC_DP18[t,d] Wear - reserved - \$TC_DP9 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP18[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:						NCK Version:	06.00.00				
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_DP19[32000,32000]					Still to be defined					Cross. R.:
Description: \$TC_DP19[t,d] Wear - angle between tool face and toroidal surface - \$TC_DP10 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP19[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:						NCK Version:	06.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_DP20[32000,32000]					Still to be defined					Cross. R.:
Description: \$TC_DP20[t,d] Wear - angle between tool longitudinal axis and upper end of toroidal surface - \$TC_DP11 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP20[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:						NCK Version:	06.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$TC_DP21[32000,32000]					Still to be defined					Cross. R.:
Description: \$TC_DP21[t,d] Basis - length 1 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP21[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:						NCK Version:	06.00.00				
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_DP22[32000,32000]					Still to be defined					Cross. R.:
Description: \$TC_DP22[t,d] Basis - length 2 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP22[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:						NCK Version:	06.00.00				
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_DP23[32000,32000]					Still to be defined					Cross. R.:
Description: \$TC_DP23[t,d] Basis - length 3 When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP23[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:						NCK Version:	06.00.00				
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_DP24[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DP24[t,d] Clearance angle When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP24[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:	06.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DP25[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DP25[t,d] Reserved When the 'flat D number management' function is active, the syntax is as follows: \$TC_DP25[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:	06.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$TC_DPCE[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DPCE[t,d] = 'cutting edge number' of compensation data block t,d When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCE[d] CE stands for <C>utting<E>dge Value range of legal 'cutting edge numbers': 1 up to value of machine data \$MN_MM_MAX_CUTTING_EDGE_PERTOOL.										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			16.00.00		
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_DPH[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DPH[t,d] = 'H cutting edge number' of compensation data block t,d for Fanuc0 M When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPH[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_DPV[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DPV[t,d] = tool cutting edge orientation When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPV[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			43.00.00		
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DPV3[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DPV3[t,d] = L1 component of tool cutting edge orientation When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPV3[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			43.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DPV4[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DPV4[t,d] = L2 component of tool cutting edge orientation When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPV4[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			43.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DPV5[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_DPV5[t,d] = Z component of tool cutting edge orientation When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPV5[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			43.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_DPVN3[32000,32000]				L1 component of the orientation normal				Cross. R.:	
Description: \$TC_DPVN3[t,d] = L1 component of the orientation normal of the tool cutting edge. If the function 'flat D-number management' is active, the syntax is as follows: \$TC_DPVN3[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: tool cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:				NCK Version:				58.00.00		
Unit:		min:		DBL_MIN				max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DPVN4[32000,32000]				L2 component of the orientation normal				Cross. R.:	
Description: \$TC_DPVN4[t,d] = L2 component of the orientation normal of the tool cutting edge. If the function 'flat D-number management' is active, the syntax is as follows: \$TC_DPVN4[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: tool cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:				NCK Version:				58.00.00		
Unit:		min:		DBL_MIN				max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DPVN5[32000,32000]				L3 component of the orientation normal				Cross. R.:	
Description: \$TC_DPVN5[t,d] = L3 component of the orientation normal of the tool cutting edge. If the function 'flat D-number management' is active, the syntax is as follows: \$TC_DPVN5[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: tool cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:				NCK Version:				58.00.00		
Unit:		min:		DBL_MIN				max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

1.1.8 OEM user cutting edge data

DOUBLE	\$TC_DPC1[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC1[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC1[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_DPC2[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC2[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC2[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	DBL_MIN			max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_DPC3[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC3[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC3[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global	Search run				Link				
			not classified				No restriction				

DOUBLE	\$TC_DPC4[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC4[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC4[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global	Search run				Link				
			not classified				No restriction				

DOUBLE	\$TC_DPC5[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC5[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC5[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global	Search run				Link				
			not classified				No restriction				

DOUBLE	\$TC_DPC6[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC6[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC6[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global				Search run			Link		
						not classified			No restriction		

DOUBLE	\$TC_DPC7[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC7[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC7[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global				Search run			Link		
						not classified			No restriction		

DOUBLE	\$TC_DPC8[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC8[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC8[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			06.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global				Search run			Link		
						not classified			No restriction		

1.1 List of system variables

DOUBLE	\$TC_DPC9[32000,32000]					Still to be defined					Cross. R.:
Description:											
The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC9[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC9[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:						NCK Version:	06.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_DPC10[32000,32000]					Still to be defined					Cross. R.:
Description:											
The type can be specified by machine data. DOUBLE is the default setting \$TC_DPC10[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPC10[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:						NCK Version:	06.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_DPCS1[32000,32000]					Still to be defined					Cross. R.:
Description:											
The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS1[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS1[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:						NCK Version:	18.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_DPCS2[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS2[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS2[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global	Search run				Link				
			not classified				No restriction				

DOUBLE	\$TC_DPCS3[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS3[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS3[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global	Search run				Link				
			not classified				No restriction				

DOUBLE	\$TC_DPCS4[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS4[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS4[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global	Search run				Link				
			not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_DPCS5[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS5[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS5[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global	Search run				Link				
			not classified				No restriction				

DOUBLE	\$TC_DPCS6[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS6[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS6[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global	Search run				Link				
			not classified				No restriction				

DOUBLE	\$TC_DPCS7[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS7[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS7[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X				
write:		X					X				7
Attributes:		Global	Search run				Link				
			not classified				No restriction				

DOUBLE	\$TC_DPCS8[32000,32000]					Still to be defined			Cross. R.:		
Description:											
The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS8[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS8[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

DOUBLE	\$TC_DPCS9[32000,32000]					Still to be defined			Cross. R.:		
Description:											
The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS9[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS9[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

DOUBLE	\$TC_DPCS10[32000,32000]					Still to be defined			Cross. R.:		
Description:											
The type can be specified by machine data. DOUBLE is the default setting \$TC_DPCS10[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_DPCS10[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

1.1 List of system variables

DOUBLE	\$TC_SCP13[32000,32000]					Still to be defined			Cross. R.:	
Description: Offset for \$TC_DP3: \$TC_SCP13[t,d] comparable to \$TC_DP12[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_SCP13[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP14[32000,32000]					Still to be defined			Cross. R.:	
Description: Offset for \$TC_DP4: \$TC_SCP14[t,d] comparable to \$TC_DP13[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_SCP14[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP15[32000,32000]					Still to be defined			Cross. R.:	
Description: Offset for \$TC_DP5: \$TC_SCP15[t,d] comparable to \$TC_DP14[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_SCP15[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP16[32000,32000]					Still to be defined			Cross. R.:	
Description: Offset for \$TC_DP6: \$TC_SCP16[t,d] comparable to \$TC_DP15[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_SCP16[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP17[32000,32000]					Still to be defined			Cross. R.:	
Description: Offset for \$TC_DP7: \$TC_SCP17[t,d] comparable to \$TC_DP16[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_SCP17[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP18[32000,32000]					Still to be defined			Cross. R.:	
Description: Offset for \$TC_DP8: \$TC_SCP18[t,d] comparable to \$TC_DP17[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_SCP18[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_SCP19[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP9: \$TC_SCP19[t,d] comparable to \$TC_DP18[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP19[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:		min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP20[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP10: \$TC_SCP20[t,d] comparable to \$TC_DP19[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP20[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:		min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP21[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP11: \$TC_SCP21[t,d] comparable to \$TC_DP20[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP21[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:		min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP23[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP3: \$TC_SCP23[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP23[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP24[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP4: \$TC_SCP24[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP24[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP25[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP5: \$TC_SCP25[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP25[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_SCP26[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP6: \$TC_SCP26[t,d] comparable to \$TC_DP15[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP26[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP27[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP7: \$TC_SCP27[t,d] comparable to \$TC_DP16[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP27[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP28[32000,32000]		Still to be defined				Cross. R.:			
Description:										
\$TC_SCP28[t,d] comparable to \$TC_DP17[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP28[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP29[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP9: \$TC_SCP29[t,d] comparable to \$TC_DP18[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP29[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP30[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP10: \$TC_SCP30[t,d] comparable to \$TC_DP19[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP30[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP31[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP11: \$TC_SCP31[t,d] comparable to \$TC_DP20[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP31[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$TC_SCP33[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP3: \$TC_SCP33[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP33[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP34[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP4: \$TC_SCP34[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP34[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP35[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP5: \$TC_SCP35[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP35[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP36[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP6: \$TC_SCP36[t,d] comparable to \$TC_DP15[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP36[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP37[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP7: \$TC_SCP37[t,d] comparable to \$TC_DP16[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP37[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP38[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP8: \$TC_SCP38[t,d] comparable to \$TC_DP17[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP38[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_SCP39[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP9: \$TC_SCP39[t,d] comparable to \$TC_DP18[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP39[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP40[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP10: \$TC_SCP40[t,d] comparable to \$TC_DP19[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP40[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP41[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP11: \$TC_SCP41[t,d] comparable to \$TC_DP20[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP41[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP43[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP3: \$TC_SCP43[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP43[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP44[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP4: \$TC_SCP44[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP44[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP45[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP5: \$TC_SCP45[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP45[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

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DOUBLE	\$TC_SCP46[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP6: \$TC_SCP46[t,d] comparable to \$TC_DP15[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP46[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP47[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP7: \$TC_SCP47[t,d] comparable to \$TC_DP16[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP47[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP48[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP8: \$TC_SCP48[t,d] comparable to \$TC_DP17[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP48[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP49[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP9: \$TC_SCP49[t,d] comparable to \$TC_DP18[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP49[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP50[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP10: \$TC_SCP50[t,d] comparable to \$TC_DP19[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP50[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP51[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP11: \$TC_SCP51[t,d] comparable to \$TC_DP20[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP51[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_SCP53[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP3: \$TC_SCP53[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP53[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP54[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP4: \$TC_SCP54[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP54[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP55[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP5: \$TC_SCP55[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP55[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP56[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP6: \$TC_SCP56[t,d] comparable to \$TC_DP15[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP56[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP57[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP7: \$TC_SCP57[t,d] comparable to \$TC_DP16[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP57[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP58[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP8: \$TC_SCP58[t,d] comparable to \$TC_DP17[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP58[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_SCP59[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP9: \$TC_SCP59[t,d] comparable to \$TC_DP18[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP59[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN					max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run					Link				
		not classified					No restriction				

DOUBLE	\$TC_SCP60[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP10: \$TC_SCP60[t,d] comparable to \$TC_DP19[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP60[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN					max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run					Link				
		not classified					No restriction				

DOUBLE	\$TC_SCP61[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP11: \$TC_SCP61[t,d] comparable to \$TC_DP20[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_SCP61[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN					max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run					Link				
		not classified					No restriction				

DOUBLE	\$TC_SCP63[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP3: \$TC_SCP63[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP63[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP64[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP4: \$TC_SCP64[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP64[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP65[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP5: \$TC_SCP65[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP65[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_SCP66[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP6: \$TC_SCP66[t,d] comparable to \$TC_DP15[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP66[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP67[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP7: \$TC_SCP67[t,d] comparable to \$TC_DP16[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP67[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP68[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP8: \$TC_SCP68[t,d] comparable to \$TC_DP17[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_SCP68[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_SCP69[32000,32000]					Still to be defined			Cross. R.:		
Description: Offset for \$TC_DP9: \$TC_SCP69[t,d] comparable to \$TC_DP18[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_SCP69[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			15.00.00			
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP70[32000,32000]					Still to be defined			Cross. R.:		
Description: Offset for \$TC_DP10: \$TC_SCP70[t,d] comparable to \$TC_DP19[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_SCP70[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			15.00.00			
Unit:	-	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_SCP71[32000,32000]					Still to be defined			Cross. R.:		
Description: Offset for \$TC_DP11: \$TC_SCP71[t,d] comparable to \$TC_DP20[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_SCP71[d]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:			15.00.00			
Unit:	-	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$TC_ECP13[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP3: \$TC_ECP13[t,d] comparable to \$TC_DP12[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP13[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP14[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP4: \$TC_ECP14[t,d] comparable to \$TC_DP13[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP14[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP15[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP5: \$TC_ECP15[t,d] comparable to \$TC_DP14[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP15[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP16[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP6: \$TC_ECP16[t,d] comparable to \$TC_DP15[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP16[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP17[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP7: \$TC_ECP17[t,d] comparable to \$TC_DP16[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP17[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP18[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP8: \$TC_ECP18[t,d] comparable to \$TC_DP17[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP18[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$TC_ECP19[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP9: \$TC_ECP19[t,d] comparable to \$TC_DP18[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP19[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP20[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP10: \$TC_ECP20[t,d] comparable to \$TC_DP19[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP20[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP21[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP11: \$TC_ECP21[t,d] comparable to \$TC_DP20[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP21[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP23[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP3: \$TC_ECP23[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP23[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP24[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP4: \$TC_ECP24[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP24[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP25[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP5: \$TC_ECP25[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP25[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_ECP26[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP6: \$TC_ECP26[t,d] comparable to \$TC_DP15[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP26[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP27[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP7: \$TC_ECP27[t,d] comparable to \$TC_DP16[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP27[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP28[32000,32000]		Still to be defined				Cross. R.:			
Description:										
\$TC_ECP28[t,d] comparable to \$TC_DP17[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP28[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP29[32000,32000]					Still to be defined			Cross. R.:	
Description: Offset for \$TC_DP9: \$TC_ECP29[t,d] comparable to \$TC_DP18[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_ECP29[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP30[32000,32000]					Still to be defined			Cross. R.:	
Description: Offset for \$TC_DP10: \$TC_ECP30[t,d] comparable to \$TC_DP19[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_ECP30[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP31[32000,32000]					Still to be defined			Cross. R.:	
Description: Offset for \$TC_DP11: \$TC_ECP31[t,d] comparable to \$TC_DP20[t,d] When the 'flat D number management' function is active, the syntax is as follows: \$TC_ECP31[d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_ECP33[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP3: \$TC_ECP33[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP33[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP34[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP4: \$TC_ECP34[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP34[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP35[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP5: \$TC_ECP35[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP35[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP36[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP6: \$TC_ECP36[t,d] comparable to \$TC_DP15[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP36[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP37[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP7: \$TC_ECP37[t,d] comparable to \$TC_DP16[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP37[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP38[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP8: \$TC_ECP38[t,d] comparable to \$TC_DP17[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP38[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$TC_ECP39[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP9: \$TC_ECP39[t,d] comparable to \$TC_DP18[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP39[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP40[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP10: \$TC_ECP40[t,d] comparable to \$TC_DP19[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP40[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP41[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP11: \$TC_ECP41[t,d] comparable to \$TC_DP20[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP41[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP43[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP3: \$TC_ECP43[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP43[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP44[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP4: \$TC_ECP44[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP44[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP45[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP5: \$TC_ECP45[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP45[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_ECP46[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP6: \$TC_ECP46[t,d] comparable to \$TC_DP15[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP46[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP47[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP7: \$TC_ECP47[t,d] comparable to \$TC_DP16[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP47[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP48[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP8: \$TC_ECP48[t,d] comparable to \$TC_DP17[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP48[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP49[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP9: \$TC_ECP49[t,d] comparable to \$TC_DP18[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP49[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP50[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP10: \$TC_ECP50[t,d] comparable to \$TC_DP19[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP50[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP51[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP11: \$TC_ECP51[t,d] comparable to \$TC_DP20[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP51[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

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DOUBLE	\$TC_ECP53[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP3: \$TC_ECP53[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP53[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP54[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP4: \$TC_ECP54[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP54[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP55[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP5: \$TC_ECP55[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP55[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP56[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP6: \$TC_ECP56[t,d] comparable to \$TC_DP15[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP56[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP57[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP7: \$TC_ECP57[t,d] comparable to \$TC_DP16[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP57[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP58[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP8: \$TC_ECP58[t,d] comparable to \$TC_DP17[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP58[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_ECP59[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP9: \$TC_ECP59[t,d] comparable to \$TC_DP18[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP59[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP60[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP10: \$TC_ECP60[t,d] comparable to \$TC_DP19[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP60[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP61[32000,32000]					Still to be defined					Cross. R.:
Description:											
Offset for \$TC_DP11: \$TC_ECP61[t,d] comparable to \$TC_DP20[t,d]											
When the 'flat D number management' function is active, the syntax is as follows:											
\$TC_ECP61[d]											
Description of array limits:											
t: T number 1 - SLMAXTOOLNUMBER											
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER											
Axes:					NCK Version:					15.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_ECP63[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP3: \$TC_ECP63[t,d] comparable to \$TC_DP12[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP63[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP64[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP4: \$TC_ECP64[t,d] comparable to \$TC_DP13[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP64[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP65[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP5: \$TC_ECP65[t,d] comparable to \$TC_DP14[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP65[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_ECP66[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP6: \$TC_ECP66[t,d] comparable to \$TC_DP15[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP66[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP67[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP7: \$TC_ECP67[t,d] comparable to \$TC_DP16[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP67[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP68[32000,32000]		Still to be defined				Cross. R.:			
Description:										
Offset for \$TC_DP8: \$TC_ECP68[t,d] comparable to \$TC_DP17[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP68[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:						NCK Version:		15.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP69[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP9: \$TC_ECP69[t,d] comparable to \$TC_DP18[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP69[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP70[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP10: \$TC_ECP70[t,d] comparable to \$TC_DP19[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP70[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ECP71[32000,32000]					Still to be defined			Cross. R.:	
Description:										
Offset for \$TC_DP11: \$TC_ECP71[t,d] comparable to \$TC_DP20[t,d]										
When the 'flat D number management' function is active, the syntax is as follows:										
\$TC_ECP71[d]										
Description of array limits:										
t: T number 1 - SLMAXTOOLNUMBER										
d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

1.1.9 Tool management monitoring data

DOUBLE	\$TC_MOP1[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MOP1[t,d] Prewarning limit for downtime										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-		min:				max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

DOUBLE	\$TC_MOP2[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MOP2[t,d] Residual tool life										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-		min:				max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOP3[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MOP3[t,d] Prewarning limit for workpiece count										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-		min:		INT_MIN		max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOP4[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MOP4[t,d] Residual workpieces										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_MOP5[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MOP5[t,d] Prewarning limit for wear										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:					max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_MOP6[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MOP6[t,d] Residual wear										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			15.00.00		
Unit:	inch	min:					max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_MOP11[32000,32000]				Still to be defined				Cross. R.:	
Description: \$TC_MOP11[t,d] Specified tool life										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:				NCK Version:				15.00.00		
Unit:		-		min:				max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

INT	\$TC_MOP13[32000,32000]				Still to be defined				Cross. R.:	
Description: \$TC_MOP13[t,d] Specified workpiece count										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:				NCK Version:				15.00.00		
Unit:		-		min:		INT_MIN		max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

DOUBLE	\$TC_MOP15[32000,32000]				Still to be defined				Cross. R.:	
Description: \$TC_MOP15[t,d] Specified wear										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:				NCK Version:				15.00.00		
Unit:		inch		min:				max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

1.1.10 OEM user monitoring data

INT	\$TC_MOPC1[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC1[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MOPC2[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC2[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MOPC3[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC3[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$TC_MOPC4[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC4[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPC5[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC5[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPC6[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC6[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPC7[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC7[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPC8[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC8[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPC9[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC9[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

1.1 List of system variables

INT	\$TC_MOPC10[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPC10[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPCS1[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS1[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPCS2[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS2[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPCS3[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS3[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPCS4[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS4[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPCS5[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS5[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

1.1 List of system variables

INT	\$TC_MOPCS6[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS6[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$TC_MOPCS7[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS7[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$TC_MOPCS8[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS8[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$TC_MOPCS9[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS9[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MOPCS10[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MOPCS10[t,d]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER d: Cutting edge number / D number 1 - SLMAXCUTTINGEDGENUMBER										
Axes:					NCK Version:			18.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

1.1.11 Tool-related data

STRING	\$TC_TP2[32000,MAX_STRINGLEN GTH]					Still to be defined			Cross. R.:	
Description: \$TC_TP2[t] Tool identifier										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER max. string length										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:		Global				Search run			Link	
						not classified			No restriction	

1.1 List of system variables

INT	\$TC_TP1[32000]					Still to be defined			Cross. R.:		
Description: \$TC_TP1[t] Duplo number											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_TP3[32000]					Still to be defined			Cross. R.:		
Description: \$TC_TP3[t] Size on left											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_TP4[32000]					Still to be defined			Cross. R.:		
Description: \$TC_TP4[t] Size on right											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_TP5[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TP5[t] Size at top										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_TP6[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TP6[t] Size at bottom										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_TP7[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TP7[t] Magazine location type										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$TC_TP8[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TP8[t] Status										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_TP9[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TP9[t] Type of tool monitoring										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_TP11[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TP11[t] Replacement-change strategy										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_TP10[32000]					Still to be defined			Cross. R.:		
Description: \$TC_TP10[t] Tool info											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_TPC1[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC1[t]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$TC_TPC2[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC2[t]											
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$TC_TPC3[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC3[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPC4[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC4[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPC5[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC5[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPC6[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC6[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPC7[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC7[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPC8[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC8[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_TPC9[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC9[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPC10[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPC10[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPCS1[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS1[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPCS2[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS2[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPCS3[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS3[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPCS4[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS4[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_TPCS5[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS5[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPCS6[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS6[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPCS7[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS7[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPCS8[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS8[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPCS9[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS9[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPCS10[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_TPCS10[t]										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

1.1.12 Tool-related grinding data

INT	\$TC_TPG1[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TPG1[t] Spindle number										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_TPG2[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TPG2[t] Chaining rule										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPG3[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TPG3[t] Minimum grinding wheel radius										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:		inch	min:					max:	DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPG4[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TPG4[t] Minimum grinding wheel width										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	inch	min:				max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPG5[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TPG5[t] Current grinding wheel width										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	inch	min:				max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPG6[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TPG6[t] Maximum speed										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:				max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_TPG7[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TPG7[t] Max. peripheral speed										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	ft/s	min:				max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_TPG8[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TPG8[t] Angle of inclined grinding wheel										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_TPG9[32000]					Still to be defined			Cross. R.:	
Description: \$TC_TPG9[t] Parameter no. f. radius calculation										
Description of array limits: t: T number 1 - SLMAXTOOLNUMBER										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:				max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1.13 Magazine location data

BOOL	\$TC_MPP3[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MPP3[n,m] Consider adjacent location On/Off										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MPP1[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MPP1[n,m] Location type										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:					max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MPP2[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MPP2[n,m] Location type										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			00.00.00		
Unit:	-	min:					max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$TC_MPP6[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_MPP6[n,m] T no. of tool in this location											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			06.00.00			
Unit:		-		min:				max:		INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

INT	\$TC_MPP4[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_MPP4[n,m] Location state											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			06.00.00			
Unit:		-		min:				max:		INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

INT	\$TC_MPP5[32000,32000]					Still to be defined			Cross. R.:		
Description: \$TC_MPP5[n,m] Buffer magazine: Location type index Real magazines:Wear group number											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			06.00.00			
Unit:		-		min:				max:		INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

INT	\$TC_MPP7[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MPP7[n,m] Adapter number of tool adapter in this location										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			15.00.00		
Unit:		-		min:				max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

INT	\$TC_MPP66[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MPP66[n,m] T no. of tool stored in buffer for which the location defined by n,m is reserved. A write operation is meaningful only when a backup file is loaded to the NCK. The name assignment is based on \$TC_MPP6 - T no. of tool stored in the magazine location.										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			43.00.00		
Unit:		-		min:				max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

1.1.14 OEM user magazine location data

INT	\$TC_MPPC1[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC1[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-		min:		INT_MIN		max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

1.1 List of system variables

INT	\$TC_MPPC2[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC2[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MPPC3[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC3[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MPPC4[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC4[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MPPC5[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC5[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MPPC6[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC6[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

INT	\$TC_MPPC7[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC7[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run			Link	
						not classified			No restriction	

1.1 List of system variables

INT	\$TC_MPPC8[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC8[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MPPC9[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC9[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MPPC10[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPC10[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:		-	min:	INT_MIN				max:	INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MPPCS1[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS1[n,m]											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

INT	\$TC_MPPCS2[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS2[n,m]											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

INT	\$TC_MPPCS3[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS3[n,m]											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run			Link		
						not classified			No restriction		

1.1 List of system variables

INT	\$TC_MPPCS4[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS4[n,m]											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MPPCS5[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS5[n,m]											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MPPCS6[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS6[n,m]											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MPPCS7[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS7[n,m]											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MPPCS8[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS8[n,m]											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MPPCS9[32000,32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS9[n,m]											
Description of array limits: n: Physical magazine number m: Physical location number											
Axes:					NCK Version:			18.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

INT	\$TC_MPPCS10[32000,32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MPPCS10[n,m]										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$TC_MDP1[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MDP1[n,m] Distance to tool change point betw. magazine n and location m of 1st internal magazine internal mag. 1 distance parameter										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$TC_MDP2[32000,32000]					Still to be defined			Cross. R.:	
Description: \$TC_MDP2[n,m] Distance to tool change point betw. magazine n and location m of 2nd internal magazine internal mag. 2 distance parameter										
Description of array limits: n: Physical magazine number m: Physical location number										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$TC_MLSR[32000,32000]				Still to be defined				Cross. R.:	
Description: \$TC_MLSR[n,m]=0 Assignment of buffer location n to buffer location m m must identify a location of type 'Spindle'. n must identify a location which is not a 'Spindle' type location. In this way it is possible, for example, to define which grippers, spindles, etc. are assigned. The default parameter setting is 0. The write operation defines a relationship, the read operation checks whether a particular relationship exists. If it does not exist, the read operation generates an alarm. define links of grippers,... to spindles.										
Description of array limits: n: Physical magazine location number of location type other than SPINDLE m: Physical magazine location number of location type SPINDLE										
Axes:						NCK Version:		06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

INT	\$TC_MPTH[8,8]				Still to be defined				Cross. R.:	
Description: \$TC_MPTH[n,m] Magazine location type hierarchy mag.location (place)types hierarchy parameter										
Description of array limits: n: Hierarchy 0 - SLMAXHIERARCHYNUMBER-1 m: Location type 0 - SLMAXHIERARCHYENTRIES - 1										
Axes:						NCK Version:		06.00.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

1.1 List of system variables

1.1.15 Tool management magazine description data

STRING	\$TC_MAP2[32000,MAX_STRINGLE NGTH]					Still to be defined			Cross. R.:	
Description: \$TC_MAP2[n] Identifier of magazine										
Description of array limits: n: Magazine number 1 - .. max. string length										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:										
write:										
Attributes:		Global				Search run		Link		
						not classified		No restriction		

INT	\$TC_MAP1[32000]					Still to be defined			Cross. R.:	
Description: \$TC_MAP1[n] Type of magazine										
Description of array limits: n: Magazine number 1 - ..										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

INT	\$TC_MAP3[32000]					Still to be defined			Cross. R.:	
Description: \$TC_MAP3[n] Status of magazine										
Description of array limits: n: Magazine number 1 - ..										
Axes:						NCK Version:		06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

INT	\$TC_MAP4[32000]					Still to be defined			Cross. R.:	
Description: \$TC_MAP4[n] Chaining to next magazine										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAP5[32000]					Still to be defined			Cross. R.:	
Description: \$TC_MAP5[n] Chaining to previous magazine										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAP6[32000]					Still to be defined			Cross. R.:	
Description: \$TC_MAP6[n] Number of lines										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$TC_MAP7[32000]					Still to be defined			Cross. R.:	
Description: \$TC_MAP7[n] Number of columns										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAP8[32000]					Still to be defined			Cross. R.:	
Description: \$TC_MAP8[n] Current magazine position in relation to tool change position										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAP9[32000]					Still to be defined			Cross. R.:	
Description: \$TC_MAP9[n] Current wear group number										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			15.00.00		
Unit:	-	min:	INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAP10[32000]				Still to be defined				Cross. R.:	
Description: \$TC_MAP10[n] Current search strategies of magazine. - Tool search strategy - Empty location search strategy The NCK enters the value of \$TC_MAMP2 per default.										
Description of array limits: n: Magazine number 1 - ..										
Axes:				NCK Version:				20.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1.16 OEM user tool management magazine description data

INT	\$TC_MAPC1[32000]				Still to be defined				Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC1[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:				NCK Version:				06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPC2[32000]				Still to be defined				Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC2[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:				NCK Version:				06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$TC_MAPC3[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC3[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPC4[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC4[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPC5[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC5[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPC6[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC6[n]											
Description of array limits: n: Magazine number 1 - ..											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MAPC7[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC7[n]											
Description of array limits: n: Magazine number 1 - ..											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MAPC8[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC8[n]											
Description of array limits: n: Magazine number 1 - ..											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

INT	\$TC_MAPC9[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC9[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPC10[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPC10[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPCS1[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS1[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPCS2[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS2[n]											
Description of array limits: n: Magazine number 1 - ..											
Axes:					NCK Version:			18.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MAPCS3[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS3[n]											
Description of array limits: n: Magazine number 1 - ..											
Axes:					NCK Version:			18.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MAPCS4[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS4[n]											
Description of array limits: n: Magazine number 1 - ..											
Axes:					NCK Version:			18.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

INT	\$TC_MAPCS5[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS5[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPCS6[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS6[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPCS7[32000]					Still to be defined			Cross. R.:	
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS7[n]										
Description of array limits: n: Magazine number 1 - ..										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$TC_MAPCS8[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS8[n]											
Description of array limits: n: Magazine number 1 - ..											
Axes:					NCK Version:			18.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MAPCS9[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS9[n]											
Description of array limits: n: Magazine number 1 - ..											
Axes:					NCK Version:			18.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

INT	\$TC_MAPCS10[32000]					Still to be defined			Cross. R.:		
Description: The type can be specified by machine data. INT is the default setting \$TC_MAPCS10[n]											
Description of array limits: n: Magazine number 1 - ..											
Axes:					NCK Version:			18.00.00			
Unit:	-	min:	INT_MIN				max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

1.1.17 Magazine module parameter

STRING	\$TC_MAMP1[-1,MAX_STRINGLENGTH]					Still to be defined			Cross. R.:	
Description: \$TC_MAMP1 Identifier of magazine block										
Description of array limits: Scalar variable max. string length										
Axes:							NCK Version:		06.00.00	
Unit:		-	min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run		Link			
					not classified		No restriction			

INT	\$TC_MAMP2[-1]					Still to be defined			Cross. R.:	
Description: \$TC_MAMP2 Type of tool search										
Description of array limits: Scalar variable										
Axes:							NCK Version:		06.00.00	
Unit:		-	min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run		Link			
					not classified		No restriction			

INT	\$TC_MAMP3[-1]					Still to be defined			Cross. R.:	
Description: \$TC_MAMP3 Handling of tools in wear groups										
Description of array limits: Scalar variable										
Axes:							NCK Version:		15.00.00	
Unit:		-	min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run		Link			
					not classified		No restriction			

1.1.18 Adapter data

INT	\$TC_ADPTT[32000]					Still to be defined			Cross. R.:	
Description: \$TC_ADPTT[a] Adapter transformation number										
Description of array limits: a: Adapter number 1 - SLMAXADAPTERNUMBER										
Axes:							NCK Version:		15.00.00	
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ADPT1[32000]					Still to be defined			Cross. R.:	
Description: \$TC_ADPT1[a] Adapter geometry: Length 1										
Description of array limits: a: Adapter number 1 - SLMAXADAPTERNUMBER										
Axes:							NCK Version:		15.00.00	
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$TC_ADPT2[32000]					Still to be defined			Cross. R.:	
Description: \$TC_ADPT2[a] Adapter geometry: Length 2										
Description of array limits: a: Adapter number 1 - SLMAXADAPTERNUMBER										
Axes:							NCK Version:		15.00.00	
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$TC_ADPT3[32000]					Still to be defined			Cross. R.:		
Description: \$TC_ADPT3[a] Adapter geometry: Length 3											
Description of array limits: a: Adapter number 1 - SLMAXADAPTERNUMBER											
Axes:					NCK Version:			15.00.00			
Unit:	inch	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1.19 Measuring system compensation values

DOUBLE	\$AA_ENC_COMP[n,m]					Still to be defined			Cross. R.:		
Description: \$AA_ENC_COMP[n,m,a] Compensation values a: Machine axes											
Description of array limits: n: Encoder no. 0-1 m: Point no. 0 - <MD value>											
Axes:					NCK Version:			06.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$AA_ENC_COMP_STEP[n]					Still to be defined			Cross. R.:		
Description: \$AA_ENC_COMP_STEP[n,a] Increment a: Machine axes											
Description of array limits: n: Encoder no. 0-1											
Axes:					NCK Version:			06.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$AA_ENC_COMP_MIN[n]				Still to be defined	Cross. R.:				
Description: \$AA_ENC_COMP_MIN[n,a] Start position of compensation a: Machine axes										
Description of array limits: n: Encoder no. 0-1										
Axes:	Machine axis				NCK Version:	06.00.00				
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AA_ENC_COMP_MAX[n]				Still to be defined	Cross. R.:				
Description: \$AA_ENC_COMP_MAX[n,a] End position of compensation a: Machine axes										
Description of array limits: n: Encoder no. 0-1										
Axes:	Machine axis				NCK Version:	06.00.00				
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

BOOL	\$AA_ENC_COMP_IS_MODULO[n]				Still to be defined	Cross. R.:				
Description: \$AA_ENC_COMP_IS_MODULO[n,a] Compensation is modulo a: Machine axes										
Description of array limits: n: Encoder no. 0-1										
Axes:	Machine axis				NCK Version:	06.00.00				
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

1.1.20 Quadrant error compensation

DOUBLE	\$AA_QEC[n,m]					Still to be defined			Cross. R.:	
Description: \$AA_QEC[n,m,a] Result of learning process a: Machine axes										
Description of array limits: n: 0 m: No. of point: 0 - \$MN_MM_QEC_MAX_POINTS										
Axes:	Machine axis					NCK Version:		06.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$AA_QEC_COARSE_STEPS[n]					Still to be defined			Cross. R.:	
Description: \$AA_QEC_COARSE_STEPS[n,a] Compensation values: Rough quantization of characteristic a: Machine axes										
Description of array limits: n: 0										
Axes:	Machine axis					NCK Version:		06.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$AA_QEC_FINE_STEPS[n]					Still to be defined			Cross. R.:	
Description: \$AA_QEC_FINE_STEPS[n,a] Fine quantization of characteristic a: Machine axes										
Description of array limits: n: 0										
Axes:	Machine axis					NCK Version:		06.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

DOUBLE	\$AA_QEC_ACCEL_1[n]					Still to be defined			Cross. R.:	
Description: \$AA_QEC_ACCEL_1[n,a] Acceleration at 1st knee point according to definition [mm/s2 or inch/s2 or degree/s2] a: Machine axes										
Description of array limits: n: 0										
Axes:	Machine axis					NCK Version:			06.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AA_QEC_ACCEL_2[n]					Still to be defined			Cross. R.:	
Description: \$AA_QEC_ACCEL_2[n,a] Acceleration at 2nd knee point according to definition [mm/s2 or inch/s2 or degree/s2] a: Machine axes										
Description of array limits: n: 0										
Axes:	Machine axis					NCK Version:			06.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AA_QEC_ACCEL_3[n]					Still to be defined			Cross. R.:	
Description: \$AA_QEC_ACCEL_3[n,a] Acceleration at 3rd knee point according to definition [mm/s2 or inch/s2 or degree/s2] a: Machine axes										
Description of array limits: n: 0										
Axes:	Machine axis					NCK Version:			06.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$AA_QEC_MEAS_TIME_1[n]		Still to be defined				Cross. R.:			
Description:										
\$AA_QEC_MEAS_TIME_1[n,a]										
Measuring time for range \$AA_QEC_ACCEL_1										
a: Machine axes										
Description of array limits:										
n: 0										
Axes:	Machine axis				NCK Version:		06.00.00			
Unit:	s	min:					max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AA_QEC_MEAS_TIME_2[n]		Still to be defined				Cross. R.:			
Description:										
\$AA_QEC_MEAS_TIME_2[n,a]										
Measuring time for range \$AA_QEC_ACCEL_2										
a: Machine axes										
Description of array limits:										
n: 0										
Axes:	Machine axis				NCK Version:		06.00.00			
Unit:	s	min:					max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AA_QEC_MEAS_TIME_3[n]		Still to be defined				Cross. R.:			
Description:										
\$AA_QEC_MEAS_TIME_3[n,a]										
Measuring time for range \$AA_QEC_ACCEL_3										
a: Machine axes										
Description of array limits:										
n: 0										
Axes:	Machine axis				NCK Version:		06.00.00			
Unit:	s	min:					max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AA_QEC_TIME_1[n]					Still to be defined			Cross. R.:	
Description: \$AA_QEC_TIME_1[n,a] 1. Filtering time for feedforward element a: Machine axes										
Description of array limits: n: 0										
Axes:	Machine axis					NCK Version:		06.00.00		
Unit:	s	min:					max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AA_QEC_TIME_2[n]					Still to be defined			Cross. R.:	
Description: \$AA_QEC_TIME_2[n,a] 2. Filtering time for feedforward element a: Machine axes										
Description of array limits: n: 0										
Axes:	Machine axis					NCK Version:		06.00.00		
Unit:	s	min:					max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AA_QEC_LEARNING_RATE[n]					Still to be defined			Cross. R.:	
Description: \$AA_QEC_LEARNING_RATE[n,a] Learning rate for network a: Machine axes										
Description of array limits: n: 0										
Axes:	Machine axis					NCK Version:		06.00.00		
Unit:	-	min:					max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

BOOL	\$AA_QEC_DIRECTIONAL[n]					Still to be defined			Cross. R.:	
Description: \$AA_QEC_DIRECTIONAL[n,a] TRUE: Direction-dependent compensation FALSE: No direction-dependent compensation a: Machine axes										
Description of array limits: n: 0										
Axes: Machine axis					NCK Version:			06.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1.21 Interpolator compensation

DOUBLE	\$AN_CEC[n,m]					Still to be defined			Cross. R.:	
Description: \$AN_CEC[n,m] Compensation value										
Description of array limits: n: Number of compensation table 0 - (maximum value can be set in MD) m: Number of interpolation point 0 - (maximum value can be set in MD)										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

AXIS	\$AN_CEC_INPUT_AXIS[n]					Still to be defined			Cross. R.:	
Description: \$AN_CEC_INPUT_AXIS[n]: Name of axis whose setpoint is used as the compensation table input										
Description of array limits: n: Number of compensation table 0 - (maximum value can be set in MD)										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:					max:			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

AXIS	\$AN_CEC_OUTPUT_AXIS[n]					Still to be defined			Cross. R.:		
Description: \$AN_CEC_OUTPUT_AXIS[n]: Name of axis to which the output of the compensation table is applied											
Description of array limits: n: Number of compensation table 0 - (maximum value can be set in MD)											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:					max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$AN_CEC_STEP[n]					Still to be defined			Cross. R.:		
Description: \$AN_CEC_STEP[n] Distance of offset values											
Description of array limits: n: Number of compensation table 0 - (maximum value can be set in MD)											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$AN_CEC_MIN[n]					Still to be defined			Cross. R.:		
Description: AN_CEC_MIN[n] Start position of compensation table											
Description of array limits: n: Number of compensation table 0 - (maximum value can be set in MD)											
Axes:					NCK Version:			06.00.00			
Unit:	-	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$AN_CEC_MAX[n]					Still to be defined			Cross. R.:	
Description: AN_CEC_MAX[n] End position of compensation table										
Description of array limits: n: Number of compensation table 0 - (maximum value can be set in MD)										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$AN_CEC_DIRECTION[n]					Still to be defined			Cross. R.:	
Description: \$AN_CEC_DIRECTION[n] Activates direction-dependent action of compensation table										
Description of array limits: n: Number of compensation table 0 - (maximum value can be set in MD)										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$AN_CEC_MULT_BY_TABLE[n]					Still to be defined			Cross. R.:	
Description: \$AN_CEC_MULT_BY_TABLE[n] Number of table whose output value is to be multiplied by the output value of the compensation table 0: Both travel directions of basic axis 1: Positive travel direction of basic axis -1: Negative travel direction of basic axis										
Description of array limits: n: Number of compensation table 0 - (maximum value can be set in MD)										
Axes:					NCK Version:			06.00.00		
Unit:	-	min:	-1			max:	1			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

BOOL	\$AN_CEC_IS_MODULO[n]		Still to be defined				Cross. R.:			
Description:										
\$AN_CEC_IS_MODULO[n]										
TRUE: Cyclical repetition of compensation table										
FALSE: No cyclical repetition of compensation table										
Description of array limits:										
n: Number of compensation table 0 - (maximum value can be set in MD)										
Axes:						NCK Version:		06.00.00		
Unit:		-		min: FALSE		max: TRUE				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
		not classified				No restriction				

1.1.22 NCK-specific protection zones

BOOL	\$SN_PA_ACTIV_IMMED[n]		Protection zone immediately active				Cross. R.:			
Description:										
\$SN_PA_ACTIV_IMMED[n]										
Protection zone immediately active after boot										
TRUE: The protection zone is activated immediately										
the control has booted and the axes have been referenced										
FALSE: The protection zone is not immediately active										
Note: This variable can only be written as a system variable and is not affected by										
the NC commands between NPROTDEF(..) and EXECUTE(n).										
Note: This variable is not restored during REORG.										
Note: This variable is saved during data backup.										
Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI										
Description of array limits:										
n: Number of protection zone										
The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK.										
Axes:						NCK Version:		06.00.00		
Unit:		-		min: FALSE		max: TRUE				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global				Search run		Link		
		not classified				No restriction				

1.1 List of system variables

CHAR	\$SN_PA_T_W[n]					Protection zone specific to workpiece/tool			Cross. R.:		
Description: \$SN_PA_T_W[n] Protection zone specific to workpiece/tool 0: Workpiece-specific protection zone 3: Tool-specific protection zone Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI											
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK.											
Axes:							NCK Version:		06.00.00		
Unit:		-	min:		0	max:		3			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:		Global		Search run			Link				
		not classified			No restriction						

INI	\$SN_PA_ORI[n]					Orientation of protection zone			Cross. R.:		
Description: \$SN_PA_ORI[n] Orientation of protection zone 0: Polygon definition in the plane from the 1st and 2nd geo axes (G17) 1: Polygon definition in the plane from the 3rd and 1st geo axes (G18) 2: Polygon definition in the plane from the 2nd and 3rd geo axes (G19) Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI											
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK.											
Axes:							NCK Version:		06.00.00		
Unit:		-	min:		0	max:		2			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:		Global		Search run			Link				
		not classified			No restriction						

INT	\$SN_PA_LIM_3DIM[n]	Scope of application-limiting protection zone							Cross. R.:	
<p>Description:</p> <p>\$SN_PA_LIM_3DIM[n] Identifier for limitation of protection zone in the axis perpendicular to the polygon definition 0: No limitation 1: Limitation in the positive direction 2: Limitation in the negative direction 3: Limitation in both directions</p> <p>Note: This variable is not restored during REORG.</p> <p>Note: This variable is saved during data backup. Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI</p>										
<p>Description of array limits:</p> <p>n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK.</p>										
Axes:							NCK Version:		06.00.00	
Unit:	-	min:	0			max:	3			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$SN_PA_PLUS_LIM[n]	Limitation of protection zone applicate plus							Cross. R.:	
<p>Description:</p> <p>\$SN_PA_PLUS_LIM[n] Positive limitation of protection zones in the axis perpendicular to the polygon definition Effective only if \$SN_PA_LIM_3DIM[n]=1 or = 3.</p> <p>Note: This variable is not restored during REORG.</p> <p>Note: This variable is saved during data backup. Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI</p>										
<p>Description of array limits:</p> <p>n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK.</p>										
Axes:							NCK Version:		06.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$SN_PA_MINUS_LIM[n]				Limitation of protection zone applicate minus				Cross. R.:	
Description: \$SN_PA_MINUS_LIM[n] Negative limitation of protection zone in minus direction in the axis perpendicular to the polygon definition Effective only if \$SN_PA_LIM_3DIM[n]=2 or = 3. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK.										
Axes:					NCK Version:	06.00.00				
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$SN_PA_CONT_NUM[n]				Number of valid contour elements				Cross. R.:	
Description: \$SN_PA_CONT_NUM[n] Number of valid contour elements Protection zones need at least 2 contour elements for a complete description. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK.										
Axes:					NCK Version:	06.00.00				
Unit:	-	min:	0			max:	10			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run			Link					
		not classified			No restriction					

INT	\$SN_PA_CONT_TYP[n,m]				Type of the contour element	Cross. R.:				
Description: \$SN_PA_CONT_TYP[n,m] Type (G1, G2, G3) of contour element =0: Contour not defined =1: Straight =2: Circle element (clockwise) =3: Circle element (counterclockwise) The end point is determined by \$SN_PA_CONT_ORD or \$SN_PA_CONT_ABS. With contour types G2 and G3, \$SN_PA_CENT_ORD or \$SN_PA_CENT_ABS determines the center point of the circle element. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)										
Axes:						NCK Version:		06.00.00		
Unit:		-		min: 0		max: 3				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global Search run				Link				
		not classified				No restriction				

DOUBLE	\$SN_PA_CONT_ORD[n,m]				End point of contour element (ordinate)	Cross. R.:				
Description: \$SN_PA_CONT_ORD[n,m] End point of contour element (ordinate) See also description of \$SN_PA_CONT_TYP Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)										
Axes:						NCK Version:		06.00.00		
Unit:		inch		min: DBL_MIN		max: DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:		Global Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$SN_PA_CONT_ABS[n,m]				End point of contour element (abscissa)				Cross. R.:	
Description: \$SN_PA_CONT_ABS[n,m] End point of contour element (abscissa) See also description of \$SN_PA_CONT_TYP Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: <u>N_NCK_PRO</u> , <u>N_COMPLETE_PRO</u> and <u>N_INITIAL_INI</u>										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)										
Axes:						NCK Version:		06.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$SN_PA_CENT_ORD[n,m]				Center point of contour element (ordinate)				Cross. R.:	
Description: \$SN_PA_CENT_ORD[n,m] Center point of contour element (ordinate) Relevant only if \$SN_PA_CONT_TYP[n,m] = 2 or = 3. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: <u>N_NCK_PRO</u> , <u>N_COMPLETE_PRO</u> and <u>N_INITIAL_INI</u>										
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)										
Axes:						NCK Version:		06.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$SN_PA_CENT_ABS[n,m]					Center point of contour element (abscissa)		Cross. R.:			
Description: \$SN_PA_CENT_ABS[n,m] Center point of contour element (abscissa) Relevant only if \$SN_PA_CONT_TYP[n,m] = 2 or = 3. Note: This variable is not restored during REORG. Note: This variable is saved during data backup. Blocks: _N_NCK_PRO, _N_COMPLETE_PRO and _N_INITIAL_INI											
Description of array limits: n: Number of protection zone The maximum dimension is defined in MD \$MN_MM_NUM_PROTECT_AREA_NCK. m: Number of the contour element (0 - MAXNUM_CONTOURNO_PROTECTAREA)											
Axes:							NCK Version:		06.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1.23 Cycle parameter assignment

DOUBLE	\$C_A					ISO cycle parameter for address A		Cross. R.:			
Description: \$C_A Value of programmed address A in ISO2/3 mode for cycle parameterization											
Axes:							NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

DOUBLE	\$C_B					ISO cycle parameter for address B		Cross. R.:			
Description: \$C_B Value of programmed address B in ISO2/3 mode for cycle parameterization											
Axes:							NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:	Global	Search run				Link					
		not classified				No restriction					

1.1 List of system variables

DOUBLE	\$C_C					ISO cycle parameter for address C		Cross. R.:		
Description: \$C_C Value of programmed address C in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_D					ISO cycle parameter for address D		Cross. R.:		
Description: \$C_D Value of programmed address D in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_E					ISO cycle parameter for address E		Cross. R.:		
Description: \$C_E Value of programmed address E in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_F					ISO cycle parameter for address F		Cross. R.:		
Description: \$C_F Value of programmed address F in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$C_G					ISO cycle parameter for address G		Cross. R.:		
Description: \$C_G Value of programmed address G in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_H					ISO cycle parameter for address H		Cross. R.:		
Description: \$C_H Value of programmed address H in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_I[10]					ISO cycle parameter for address I		Cross. R.:		
Description: \$C_I[] Value of programmed address I in ISO2/3 mode for cycle parameterization and macro programming with G65/G66. Description of array limits: Up to 10 entries with address K can be made in the block for macro programming with G65/G66. The values are stored in the array in the sequence in which they were programmed.										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$C_J[10]				ISO cycle parameter for address J				Cross. R.:	
Description: \$C_J[] Value of programmed address J in ISO2/3 mode for cycle parameterization and macro programming with G65/G66.										
Description of array limits: Up to 10 entries with address K can be made in the block for macro programming with G65/G66. The values are stored in the array in the sequence in which they were programmed.										
Axes:				NCK Version:				17.00.00		
Unit:		-	min: DBL_MIN				max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_K[10]				ISO cycle parameter for address K				Cross. R.:	
Description: \$C_K[] Value of programmed address K in ISO2/3 mode for cycle parameterization and macro programming with G65/G66.										
Description of array limits: Up to 10 entries with address K can be made in the block for macro programming with G65/G66. The values are stored in the array in the sequence in which they were programmed.										
Axes:				NCK Version:				17.00.00		
Unit:		-	min: DBL_MIN				max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_L				ISO cycle parameter for address L				Cross. R.:	
Description: \$C_L Value of programmed address L in ISO2/3 mode for cycle parameterization										
Axes:				NCK Version:				17.00.00		
Unit:		-	min: DBL_MIN				max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$C_M					ISO cycle parameter for address M		Cross. R.:		
Description: \$C_M Value of programmed address M in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_N					ISO cycle parameter for address N		Cross. R.:		
Description: \$C_N Value of programmed address N in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_O					ISO cycle parameter for address O		Cross. R.:		
Description: \$C_O Value of programmed address O in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_P					ISO cycle parameter for address P		Cross. R.:		
Description: \$C_P Value of programmed address P in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$C_Q					ISO cycle parameter for address Q		Cross. R.:		
Description: \$C_Q Value of programmed address Q in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_R					ISO cycle parameter for address R		Cross. R.:		
Description: \$C_R Value of programmed address R in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_S					ISO cycle parameter for address S		Cross. R.:		
Description: \$C_S Value of programmed address S in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_T					Cycle parameter for address T		Cross. R.:		
Description: \$C_T Value of programmed address T for cycle parameterization (ISO2/3 mode) and T function substitution (ISO2/3 and standard modes)										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_U					ISO cycle parameter for address U		Cross. R.:		
Description: \$C_U Value of programmed address U in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_V					ISO cycle parameter for address V		Cross. R.:		
Description: \$C_V Value of programmed address V in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_W					ISO cycle parameter for address W		Cross. R.:		
Description: \$C_W Value of programmed address W in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_X					ISO cycle parameter for address X		Cross. R.:		
Description: \$C_X Value of programmed address X in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$C_Y					ISO cycle parameter for address Y		Cross. R.:		
Description: \$C_Y Value of programmed address Y in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_Z					ISO cycle parameter for address Z		Cross. R.:		
Description: \$C_Z Value of programmed address Z in ISO2/3 mode for cycle parameterization										
Axes:						NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_DL					ISO parameter for address DL		Cross. R.:		
Description: Value of programmed address DL (additive tool offset) in the case of a subprogram call by M/T function substitution										
Axes:						NCK Version:		43.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_PI					ISO cycle parameter for address P		Cross. R.:		
Description: Program number of interrupt routine programmed with M96 Pxx in ISO2/3 mode										
Axes:						NCK Version:		52.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

STRING	\$C_TS[-1,MAX_STRINGLENGTH]					Still to be defined			Cross. R.:	
Description: \$C_TS String of the tool identifier programmed under address T for T function substitution (with active tool monitoring only)										
Description of array limits: The tool name appears once only in the block. Maximum string length										
Axes:					NCK Version:			18.00.00		
Unit:		-		min:		max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$C_A_PROG					ISO cycle parameter for address A			Cross. R.:	
Description: \$C_A_PROG Address A is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-		min:		max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$C_B_PROG					ISO cycle parameter for address B			Cross. R.:	
Description: \$C_B_PROG Address B is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-		min:		max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$C_C_PROG					ISO cycle parameter for address C			Cross. R.:	
Description: \$C_C_PROG Address C is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run			Link					
		not classified			No restriction					

INT	\$C_D_PROG					ISO cycle parameter for address D			Cross. R.:	
Description: \$C_D_PROG Address D is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run			Link					
		not classified			No restriction					

INT	\$C_E_PROG					ISO cycle parameter for address E			Cross. R.:	
Description: \$C_E_PROG Address E is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run			Link					
		not classified			No restriction					

INT	\$C_F_PROG					ISO cycle parameter for address F		Cross. R.:		
Description: \$C_F_PROG Address F is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:		17.00.00			
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$C_G_PROG					ISO cycle parameter for address G		Cross. R.:		
Description: \$C_G_PROG G function for cycle call is programmed in this block 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:		17.00.00			
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$C_H_PROG					ISO cycle parameter for address H		Cross. R.:		
Description: \$C_H_PROG Address H is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:		17.00.00			
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$C_I_PROG					ISO cycle parameter for address I		Cross. R.:		
Description: \$C_I_PROG Address I is programmed in a block with cycle macro call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:		17.00.00			
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$C_J_PROG					ISO cycle parameter for address J		Cross. R.:		
Description: \$C_J_PROG Address J is programmed in a block with cycle macro call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:		17.00.00			
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$C_K_PROG					ISO cycle parameter for address K		Cross. R.:		
Description: \$C_K_PROG Address K is programmed in a block with cycle macro call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:		17.00.00			
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$C_L_PROG					ISO cycle parameter for address L		Cross. R.:		
Description: \$C_L_PROG Address L is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$C_M_PROG					ISO cycle parameter for address M		Cross. R.:		
Description: \$C_M_PROG Address M is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$C_N_PROG					ISO cycle parameter for address N		Cross. R.:		
Description: \$C_N_PROG Address N is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$C_O_PROG					ISO cycle parameter for address O			Cross. R.:	
Description: \$C_O_PROG Address O is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:							NCK Version:		17.00.00	
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run		Link			
					not classified		No restriction			

INT	\$C_P_PROG					ISO cycle parameter for address P			Cross. R.:	
Description: \$C_P_PROG Address P is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:							NCK Version:		17.00.00	
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run		Link			
					not classified		No restriction			

INT	\$C_Q_PROG					ISO cycle parameter for address Q			Cross. R.:	
Description: \$C_Q_PROG Address Q is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:							NCK Version:		17.00.00	
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run		Link			
					not classified		No restriction			

INT	\$C_R_PROG					ISO cycle parameter for address R		Cross. R.:			
Description: \$C_R_PROG Address R is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.											
Axes:					NCK Version:		17.00.00				
Unit:		-	min:		max:						
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global Search run				Link					
		not classified				No restriction					

INT	\$C_S_PROG					ISO cycle parameter for address S		Cross. R.:			
Description: \$C_S_PROG Address S is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.											
Axes:					NCK Version:		17.00.00				
Unit:		-	min:		max:						
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global Search run				Link					
		not classified				No restriction					

INT	\$C_T_PROG					ISO cycle parameter for address T		Cross. R.:			
Description: \$C_T_PROG Address T is programmed in a block with cycle call or T function substitution 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.											
Axes:					NCK Version:		17.00.00				
Unit:		-	min:		max:						
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global Search run				Link					
		not classified				No restriction					

1.1 List of system variables

INT	\$C_U_PROG					ISO cycle parameter for address U			Cross. R.:		
Description: \$C_U_PROG Address U is programmed in the current block 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.											
Axes:							NCK Version:		17.00.00		
Unit:		-	min:					max:			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global			Search run		Link				
					not classified		No restriction				

INT	\$C_V_PROG					ISO cycle parameter for address V			Cross. R.:		
Description: \$C_V_PROG Address V is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.											
Axes:							NCK Version:		17.00.00		
Unit:		-	min:					max:			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global			Search run		Link				
					not classified		No restriction				

INT	\$C_W_PROG					ISO cycle parameter for address W			Cross. R.:		
Description: \$C_W_PROG Address W is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.											
Axes:							NCK Version:		17.00.00		
Unit:		-	min:					max:			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global			Search run		Link				
					not classified		No restriction				

INT	\$C_X_PROG					ISO cycle parameter for address X			Cross. R.:	
Description: \$C_X_PROG Address X is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$C_Y_PROG					ISO cycle parameter for address Y			Cross. R.:	
Description: \$C_Y_PROG Address Y is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

INT	\$C_Z_PROG					ISO cycle parameter for address Z			Cross. R.:	
Description: \$C_Z_PROG Address Z is programmed in a block with cycle call 0 = Not programmed 1 = Programmed 3 = Programmed incrementally Bit 0 is set if the address is programmed absolutely or incrementally. Bit 1 is set in addition if the address is programmed incrementally.										
Axes:					NCK Version:			17.00.00		
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$C_DL_PROG					ISO cycle parameter for address DL		Cross. R.:		
Description: Interrogation as to whether address DL (additive tool offset) has been programmed for a subprogram call per M/T function substitution. 0 = Not programmed 1 = An additive tool offset has been programmed under address DL.										
Axes:					NCK Version:		43.00.00			
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
		not classified				No restriction				

INT	\$C_TS_PROG					Parameter for tool name as string		Cross. R.:		
Description: Interrogation as to whether a tool identifier has been programmed under address T for a subprogram call per T function substitution. (with active tool monitoring only) 0 = Not programmed 1 = Programmed										
Axes:					NCK Version:		18.00.00			
Unit:		-	min:		max:			1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
		not classified				No restriction				

INT	\$C_PI_PROG					ISO cycle parameter for address P		Cross. R.:		
Description: 0 = Not programmed 1 = M96 Pxx interrupt routine programmed										
Axes:					NCK Version:		52.00.00			
Unit:		-	min:		max:					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global				Search run		Link		
		not classified				No restriction				

INT	\$C_ALL_PROG					Bit pattern specifying which addresses are programmed			Cross. R.:	
Description: \$C_ALL_PROG Bit pattern of all programmed addresses in a block with cycle call Bit0 = Address "A" Bit25 = Address "Z" Bit = 1 -> Address programmed Bit = 0 -> Address not programmed										
Axes:					NCK Version:			17.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$C_INC_PROG					Bit pattern specifying whether addresses are programmed incr.			Cross. R.:	
Description: \$C_INC_PROG Bit pattern of all incrementally programmed addresses in a block with cycle call Bit0 = Address "A" Bit25 = Address "Z" Bit = 1 -> Address incrementally programmed Bit = 0 -> Address absolutely programmed										
Axes:					NCK Version:			18.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$C_TYP_PROG					Bit pattern specifying whether addresses are progr. as INT/REAL			Cross. R.:	
Description: \$C_TYP_PROG Bit pattern of all addresses programmed with value INT or REAL Bit0 = Address "A" Bit25 = Address "Z" Bit = 1 -> Address programmed with real value Bit = 0 -> Address programmed with int value										
Axes:					NCK Version:			51.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

INT	\$C_I_NUM					Number of "I" addresses programmed in block			Cross. R.:	
Description: \$C_I_NUM The number of "I" addresses programmed in the block is stored in \$C_I_NUM. This value is always 1 for cycle programming if bit 0 is set in \$C_I_PROG. In the case of macro programming with G65/G66, this variable contains the number of "I" addresses programmed in the block (max. 10).										
Axes:							NCK Version:		18.00.00	
Unit:		-	min:					max:		10
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run			Link		
					not classified			No restriction		

INT	\$C_J_NUM					Number of "J" addresses programmed in block			Cross. R.:	
Description: \$C_J_NUM The number of "J" addresses programmed in the block is stored in \$C_J_NUM. This value is always 1 for cycle programming if bit 0 is set in \$C_J_PROG. In the case of macro programming with G65/G66, this variable contains the number of "J" addresses programmed in the block (max. 10).										
Axes:							NCK Version:		18.00.00	
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run			Link		
					not classified			No restriction		

INT	\$C_K_NUM					Number of "K" addresses programmed in block			Cross. R.:	
Description: \$C_K_NUM The number of "K" addresses programmed in the block is stored in \$C_K_NUM. This value is always 1 for cycle programming if bit 0 is set in \$C_K_PROG. In the case of macro programming with G65/G66, this variable contains the number of "K" addresses programmed in the block (max. 10).										
Axes:							NCK Version:		18.00.00	
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:		Global			Search run			Link		
					not classified			No restriction		

INT	\$C_I_ORDER[10]					Block number of address I for IJK blocks		Cross. R.:			
Description: \$C_I_ORDER[] Number of I J K block in which I has been programmed Up to 10 entries with address I can be made in the block for macro programming with G65/G66. This allows the sequence of IJK blocks to be evaluated The association between IJK blocks is always noted.											
Description of array limits: Up to 10 entries with address K can be made in the block for macro programming with G65/G66. This allows the sequence of IJK blocks to be evaluated The association between I J K blocks is always noted.											
Axes:							NCK Version:		49.00.00		
Unit:		-	min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run		Link			
		not classified				No restriction					

INT	\$C_J_ORDER[10]					Block number of address J for IJK blocks		Cross. R.:			
Description: \$C_J_ORDER[] Number of IJK block in which J has been programmed. Up to 10 entries with address J can be made in the block for macro programming with G65/G66. This allows the sequence of IJK blocks to be evaluated The association between IJK blocks is always noted.											
Description of array limits: Up to 10 entries with address K can be made in the block for macro programming with G65/G66. This allows the sequence of IJK blocks to be evaluated The association between I J K blocks is always noted.											
Axes:							NCK Version:		49.00.00		
Unit:		-	min:		DBL_MIN			max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:	X					X				7	
Attributes:		Global				Search run		Link			
		not classified				No restriction					

1.1 List of system variables

INT	\$C_K_ORDER[10]					Block number of address K for IJK blocks			Cross. R.:	
Description: \$C_K_ORDER[] Number of IJK block in which K has been programmed. Up to 10 entries with address K can be made in the block for macro programming with G65/G66. This allows the sequence of IJK blocks to be evaluated The association between IJK blocks is always noted.										
Description of array limits: Up to 10 entries with address K can be made in the block for macro programming with G65/G66. This allows the sequence of IJK blocks to be evaluated The association between I J K blocks is always noted.										
Axes:							NCK Version:		49.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$C_ME					Address extension for subprogram calls via M function			Cross. R.:	
Description: \$C_ME Address extension for address M for subprogram call per M function										
Axes:							NCK Version:		42.00.00	
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$C_TE					Address extension for subprogram calls via T function			Cross. R.:	
Description: \$C_TE Address extension for address T for subprogram call per M function										
Axes:							NCK Version:		42.00.00	
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$C_MACPAR[33]					Auxiliary variable for implementing # macros			Cross. R.:	
Description:										
\$MAC_PAR[n]										
Macro variable in Iso2/3 mode programmed in the original program with #<number>										
Description of array limits:										
The maximum number of ISO macroparameters is 33										
Axes:							NCK Version:		47.00.00	
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:	X					X				7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1.24 System data

DOUBLE	\$AN_SETUP_TIME					Time since booting with default values			Cross. R.:	
Description:										
The \$AN_SETUP_TIME timer counts the time elapsed since the control last booted with default values (in minutes).										
The timer is automatically reset each time the control boots with default data.										
Use in NC program:										
IF \$AN_SETUP_TIME > 60000 GOTOF MARK01										
Axes:							NCK Version:		19.00.00	
Unit:	s	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		State				No restriction				

DOUBLE	\$AN_POWERON_TIME					Time since control last booted			Cross. R.:	
Description:										
The \$AN_POWERON_TIME timer counts the time elapsed since the control last booted (in minutes).										
The timer is automatically reset each time the control boots.										
Use in NC program:										
IF \$AN_POWERON_TIME == 480 GOTOF MARK02										
Axes:							NCK Version:		19.00.00	
Unit:	s	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		State				No restriction				

1.1 List of system variables

DOUBLE	\$AN_NCK_VERSION				NCK version				Cross. R.:		
Description: NCK version NCK version: only the integer places in the floating-point number are evaluated, the decimal places can contain identifiers for intermediate versions used by the development department. The integer places contain the official software version identifier of the NCK: For example, the value for NCK version 20.00.00 is variable 20000.0 compare OPI N/Y nckVersion											
Axes:						NCK Version:		18.02.00			
Unit:		-	min:						max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X				X	X	X	X		
write:											
Attributes:		Global Search run				Link					
		Independent				No restriction					

BOOL	\$AN_IPO_LOAD_LIMIT				IPO utilization limit reached				Cross. R.:		
Description: Variable \$AN_IPO_LOAD_LIMIT returns TRUE when the interpolator load limit is reached. Machine data \$MN_IPO_MAX_LOAD is used to specify the gross interpolator operating time (in % of the interpolation cycle) at which variable \$AN_IPO_LOAD_LIMIT is set to TRUE. If the value falls below the limit again, the variable is reset to FALSE.											
Axes:						NCK Version:		54.00.00			
Unit:		-	min:		FALSE				max:		TRUE
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X				X	X		X		
write:											
Attributes:		Global Search run				Link					
		not classified				not classified					

DOUBLE	\$AN_IPO_ACT_LOAD				Current IPO runtime				Cross. R.:		
Description: \$AN_IPO_ACT_LOAD supplies the current interpolator runtime including the runtime of the synchronized actions in all channels.											
Axes:						NCK Version:		54.00.00			
Unit:		-	min:		DBL_MIN				max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X					X		X		
write:											
Attributes:		Global Search run				Link					
		not classified				not classified					

DOUBLE	\$AN_IPO_MAX_LOAD				Maximum IPO runtime				Cross. R.:	
Description: \$AN_IPO_MAX_LOAD supplies the longest interpolator runtime of one interpolation cycle (including the runtime of the synchronized actions).										
Axes:				NCK Version:				54.00.00		
Unit:		-	min:	DBL_MIN				max:	DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:	X	X				X	X		X	7
Attributes:		Global				Search run				Link
		not classified				not classified				

DOUBLE	\$AN_IPO_MIN_LOAD				Shortest IPO runtime				Cross. R.:	
Description: \$AN_IPO_MIN_LOAD supplies the shortest interpolator runtime including the runtime of the synchronized actions per interpolation cycle in all channels.										
Axes:				NCK Version:				54.00.00		
Unit:		-	min:	DBL_MIN				max:	DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:	X	X				X	X		X	7
Attributes:		Global				Search run				Link
		not classified				not classified				

DOUBLE	\$AN_IPO_LOAD_PERCENT				Ratio of current IPO runtime to IPO cycle				Cross. R.:	
Description: \$AN_IPO_LOAD_PERCENT supplies the current interpolator load percentage across all channels. Is calculated from the ratio of the interpolator runtime across all channels in the last interpolation cycle to the interpolation cycle.										
Axes:				NCK Version:				54.00.00		
Unit:		-	min:	DBL_MIN				max:	DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:										
Attributes:		Global				Search run				Link
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AN_SYNC_ACT_LOAD					Current runtime for synchronized actions					Cross. R.:
Description: \$AC_SYNC_ACT_LOAD supplies the current runtime for synchronized actions of the last interpolation cycle across all channels.											
Axes:					NCK Version:					54.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X					X		X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AN_SYNC_MAX_LOAD					Longest runtime for synchronized actions					Cross. R.:
Description: \$AC_SYNC_MAX_LOAD supplies the longest runtime for synchronized actions of one interpolation cycle across all channels.											
Axes:					NCK Version:					54.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X				X	X		X		
write:	X	X				X	X		X	7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AN_SYNC_TO_IPO					Synact / IPO computing time percentage					Cross. R.:
Description: \$AN_SYNC_TO_IPO supplies the percentage proportion of the synchronized action runtime measured against the overall interpolation runtime of the last interpolation cycle across all channels.											
Axes:					NCK Version:					54.00.00	
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X					X		X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AN_SERVO_ACT_LOAD				Current runtime of position controller				Cross. R.:	
Description:										
\$AN_SERVO_ACT_LOAD supplies the current runtime of the position controller.										
Axes:					NCK Version:	54.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AN_SERVO_MAX_LOAD				Longest runtime of position controller				Cross. R.:	
Description:										
\$AN_SERVO_MAX_LOAD supplies the longest runtime of the position controller.										
Axes:					NCK Version:	54.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:	X	X				X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AN_SERVO_MIN_LOAD				Shortest runtime of position controller				Cross. R.:	
Description:										
\$AN_SERVO_MIN_LOAD supplies the shortest runtime of the position controller.										
Axes:					NCK Version:	54.00.00				
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:	X	X				X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AN_REBOOT_DELAY_TIME				Time until reboot				Cross. R.:	
Description:										
A value higher than zero indicates that the NCK has received the "NCK Reset" signal from the HMI and displays the time period (in seconds) programmed on the NCK for rebooting (Power Off followed by Power ON).										
The user can thus identify a reboot operation in a synchronized action and prepare his application accordingly.										
\$AN_REBOOT_DELAY_TIME is 0.0 provided that no "NCK Reset" has been received.										
Example:										
A synchronized action reacts to the variable and switches the axes to "Safe standstill" in a Safety Integrated application.										
Comments:										
- See also: \$MN_REBOOT_DELAY_TIME										
- The "NCK Reset" is implemented on the OPI by means of PI "_N_IBN_SS".										
Axes:						NCK Version:		56.00.00		
Unit:		s	min:		0.0		max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X		X	
write:										
Attributes:		Global	Search run			Link				
	X	Independent			No restriction					

DOUBLE	\$AN_TIMER[n]				System variable for global NCK time measurement				Cross. R.:	
Description:										
\$AN_TIMER[n]										
Timer unit in seconds										
The time is counted in multiples of an interpolation cycle.										
The timers are started by \$AN_TIMER[n]=<start value>.										
The timers are stopped by \$AN_TIMER[n]=-1.										
When a timer is stopped, the last current time value is stored.										
Description of array limits:										
The dimension is defined in MD \$MN_MM_NUM_AN_TIMER.										
Axes:						NCK Version:		56.00.00		
Unit:		-	min:		DBL_MIN		max:		DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global	Search run			Link				
	X	not classified			not classified					

INT	\$A_PROBE[2]				Probe status				Cross. R.:	
Description: \$A_PROBE[1]: Status of first probe \$A_PROBE[2]: Status of second probe 0 => not deflected 1 => deflected										
Description of array limits: n: Number of probe										
Axes:				NCK Version:				13.00.00		
Unit:	-	min:	0				max:	1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1.25 Axis system Variables

DOUBLE	\$P_EP				Programmed end position				Cross. R.:	
Description: \$P_EP[X] System variable \$P_EP supplies the current WCS setpoint position in the interpreter. The numerical value is not necessarily identical to the value programmed in the part program. The two values differ in the following situations: - with incremental programming - when the WCS is changed by a frame or tool selection If an ASUB is started after a block search with calculation, the positions in the interpreter are synchronized with this operation. \$P_EP then supplies the actual standstill positions of the axes in the Asub. The collected search position can be interrogated via system variable \$AC_RETPOINT.										
Axes:				NCK Version:				06.00.00		
Geometry axis Channel axis Machine axis Spindle										
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$P_EPM				Programmed MCS target position				Cross. R.:	
Description: Axial variable \$P_EPM[ax] determines the current programmed MCS target position in the preprocessor for the specified axis (see also \$P_EP).										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		20.09.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$P_APR				Still to be defined				Cross. R.:	
Description: \$P_APR[X] Position of axis in workpiece coordinate system at starting point of approach movement on smooth approach to the contour										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$P_AEP				Still to be defined				Cross. R.:	
Description: \$P_AEP[X] Approach point: First contour point in workpiece coordinate system on smooth approach to contour										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$P_POLF				Programmed retraction position of the axis				Cross. R.:	
Description: \$P_POLF[X] supplies the programmed retraction position of the axis X: Axis										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		51.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$P_POLF_VALID				Status of the value of \$P_POLF				Cross. R.:	
Description: \$P_POLF_VALID[X] Supplies the status of \$P_POLF[X] X: Axis Return values: 0: No retraction programmed 1: Retraction programmed Position programmed 2: Retraction programmed as distance										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				51.00.00	
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_IW				Current WCS setpoint of an axis				Cross. R.:	
Description: Axial variable \$AA_IW[ax] determines the current setpoint in the workpiece coordinate system (WCS) for the specified axis. The setpoint is equivalent to the interpolator output value for the current interpolation cycle. The WCS value contains no axial offset components (DRF, AA_OFF, ext. work offset, etc.).										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$AA_REPOS_DELAY					Still to be defined			Cross. R.:	
Description: \$AA_REPOS_DELAY[X] TRUE: Repos suppression is currently active for this axis. FALSE: otherwise										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		51.00.00		
Unit:	-	min:	TRUE				max:	FALSE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X		X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				Not Lead Link axis				

DOUBLE	\$AA_IEN					Current SZS setpoint of an axis			Cross. R.:	
Description: Axial variable \$AA_IEN[ax] determines the current setpoint in the settable zero coordinate system (SZS) for the specified axis. See also \$AA_IW[ax]. The SZS value contains no axial offset components (DRF, AA_OFF, ext. work offset, etc.).										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		13.00.00		
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_IBN				Current BZS setpoint of an axis				Cross. R.:	
Description: Axial variable \$AA_IBN[ax] determines the current setpoint in the basic zero coordinate system (BZS) for the specified axis. See also \$AA_IW[ax]. The BZS value contains no axial offset components (DRF, \$AA_OFF, ext. work offset, etc.).										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_IB				Current BCS setpoint of an axis				Cross. R.:	
Description: Axial variable \$AA_IB[ax] determines the current setpoint in the basic coordinate system (BCS) for the specified axis. See also \$AA_IW[ax]. The BCS value contains no axial offset components (DRF, \$AA_OFF, ext. work offset, etc.).										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_ENC_AMPL[n]					Gain factor for closed-loop amplitude control			Cross. R.:	
Description: \$AA_ENC_AMPL[n,ax] supplies the gain factor of the closed-loop amplitude control for diagnostics and monitoring purposes. The standard encoder voltage is 1V = 100%, the gain can fluctuate between 0.5V and 1.3V schwanken. The meaning of the indices are as follows: n: Encoder number ax: Machine axes Description of array limits: n: Encoder number										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:		53.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$AA_IM					Current MCS setpoint of an axis			Cross. R.:	
Description: Axial variable \$AA_IM[ax] determines the current setpoint in the machine coordinate system (MCS) for the specified axis. See also \$AA_IW[ax]. The MCS value contains all axial offset components (DRF, \$AA_OFF, ext. work offset, etc.).										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		06.00.00		
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

1.1 List of system variables

INT	\$AA_ACT_INDEX_AX_POS_NO				Current indexing position				Cross. R.:	
Description: \$AA_ACT_INDEX_AX_POS_NO[X] 0: Not an indexing axis, no indexing position is thus available. > 0: Number of last reached or last crossed indexing position										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_PROG_INDEX_AX_POS_NO				Programmed indexing position				Cross. R.:	
Description: \$AA_PROG_INDEX_AX_POS_NO[X] 0: Not an indexing axis, no indexing position is thus available or the indexing axis is not currently approaching an indexing position > 0: Number of programmed indexing position										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$AA_ENC_ACTIVE				Measuring system is active				Cross. R.:	
Description: Axial variable \$AA_ENC_ACTIVE[ax] determines whether the active measuring system is operating below the encoder limit frequency.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$AA_ENC1_ACTIVE					1. Measuring system is active			Cross. R.:	
Description: Axial variable \$AA_ENC1_ACTIVE[ax] determines whether the first measuring system is operating below the encoder limit frequency.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		13.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$AA_ENC2_ACTIVE					2. Measuring system is active			Cross. R.:	
Description: Axial variable \$AA_ENC2_ACTIVE[ax] determines whether the second measuring system is operating below the encoder limit frequency.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		13.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$VA_IM					Current MCS actual value of an axis			Cross. R.:	
Description: Axial variable \$VA_IM[ax] determines the encoder actual value (measured by active measuring system) in the machine coordinate system (MCS). All actual value compensations are corrected (leadscrew error compensation, backlash compensation, quadrant error compensation). When a spindle or axis disable is active, this variable returns the current setpoint by definition. If it is preferred to return the actual value in this situation, BIT3 in \$MA_MISC_FUNCTION_MASK must be set.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		13.00.00		
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$VA_IM1					Current MCS actual value of an axis			Cross. R.:	
Description: Axial variable \$VA_IM1[ax] determines the encoder actual value (measured by encoder 1) in the machine coordinate system (MCS). All actual value compensations are corrected (leadscrew error compensation, backlash compensation, quadrant error compensation). When a spindle or axis disable is active, this variable returns the current setpoint by definition. If it is preferred to return the actual value in this situation, BIT3 in \$MA_MISC_FUNCTION_MASK must be set.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:			13.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$VA_IM2					Current MCS actual value of an axis			Cross. R.:	
Description: Axial variable \$VA_IM2[ax] determines the encoder actual value (measured by encoder 2) in the machine coordinate system (MCS). All actual value compensations are corrected (leadscrew error compensation, backlash compensation, quadrant error compensation). When a spindle or axis disable is active, this variable returns the current setpoint by definition. If it is preferred to return the actual value in this situation, BIT3 in \$MA_MISC_FUNCTION_MASK must be set.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:			13.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$VA_LAG_ERROR					Axis following error			Cross. R.:	
Description: Variable \$VA_LAG_ERROR[X] supplies the contour-related following error, i.e. position setpoint after fine interpolator actual position value.										
Axes:	Channel axis Machine axis					NCK Version:		53.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MW					Measured probe position (WCS)			Cross. R.:	
Description: \$AA_MW[X] Probe measured value in workpiece coordinate system										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		06.00.00		
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MM					Measured probe position (MCS)			Cross. R.:	
Description: \$AA_MM[X] Probe measured value in machine coordinate system										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		06.00.00		
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_MW1				Probe position trigger 1 (WCS)				Cross. R.:	
Description: \$AA_MW1[X] Measurement result axial measurement Trigger event 1 in WCS										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	Lin. - /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MW2				Probe position trigger 2 (WCS)				Cross. R.:	
Description: \$AA_MW2[X] Measurement result axial measurement Trigger event 2 in WCS										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	Lin. - /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MW3				Probe position trigger 3 (WCS)				Cross. R.:	
Description: \$AA_MW3[X] Measurement result axial measurement Trigger event 3 in WCS										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	Lin. - /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MW4				Probe position trigger 4 (WCS)				Cross. R.:	
Description: \$AA_MW4[X] Measurement result axial measurement Trigger event 4 in WCS										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	Lin. - /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_MM1				Probe position trigger 1 (MCS)				Cross. R.:	
Description: \$AA_MM1[X] Measurement result axial measurement Trigger event 1 in MCS										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	Lin. - /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MM2				Probe position trigger 2 (MCS)				Cross. R.:	
Description: \$AA_MM2[X] Measurement result axial measurement Trigger event 2 in MCS										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	Lin. - /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MM3				Probe position trigger 3 (MCS)				Cross. R.:	
Description: \$AA_MM3[X] Measurement result axial measurement Trigger event 3 in MCS										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MM4				Probe position trigger 4 (MCS)				Cross. R.:	
Description: \$AA_MM4[X] Measurement result axial measurement Trigger event 4 in MCS										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

BOOL	\$AA_MEA ACT				Axial measurement active				Cross. R.:	
Description: \$AA_MEA[ax] Value is TRUE when axial measurement is active for X Corresponds to PLC interface signal DB31...DBX62.3										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_DRF				Handwheel override of an axis				Cross. R.:	
Description: Axial variable \$AC_DRF[ax] determines the axial override value caused by the handwheel (DRF offset).										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AC_PRESET				PRESET value of an axis				Cross. R.:	
Description: Axial variable \$AC_PRESET[ax] determines the last defined PRESET value.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:								X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_ETRANS				External zero offset				Cross. R.:	
Description:										
Axial variable \$AA_ETRANS[ax] is used to enter an external work offset which can be activated by the PLC. After activation by the PLC, the offset value is traversed as an axial override in the next block.										
If Bit 1 is set in \$MC_MM_SYSTEM_FRAME_MASK, an active movement is stopped immediately, on activation by the PLC, the preprocessor is reorganized, and the system frame is initialized with the axis value of \$AA_ETRANS[ax] and is activated. The offset is traversed before resuming the interrupted movement. The external work offset has an absolute effect on the translation of the current system frame. Multiple activation is thus not additive; only the coarse component of the translation (not the fine offset) is overwritten with the value from \$AA_ETRANS[ax].										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00	
Unit:	Lin. - /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_MEAS_P1_VALID				Unlatch 1st measuring point of an axis				Cross. R.:	
Description:										
Variable for workpiece and tool measurement.										
Axial variable \$AA_MEAS_P1_VALID[ax] is used to unlatch the current axis position with reference to a selected coordinate system. Variable \$AC_MEAS_P1_COORD is used to select the coordinate system.										
Application:										
\$AA_MEAS_P1_VALID[ax] = 0 ; 1st measuring point of axis is invalid										
\$AA_MEAS_P1_VALID[ax] = 1 ; Determining 1st measuring point of axis										
The unlatched measuring point is stored in \$AA_MEAS_POINT1[ax].										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				43.00.00	
Unit:	-	min:					max:	1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AA_MEAS_P2_VALID				Unlatch 2nd measuring point of an axis				Cross. R.:		
Description: Variable for workpiece and tool measurement. Axial variable \$AA_MEAS_P2_VALID[ax] is used to unlatch the current axis position with reference to a selected coordinate system. Variable \$AC_MEAS_P2_COORD is used to select the coordinate system. Application: \$AA_MEAS_P2_VALID[ax] = 0 ; 2nd measuring point of axis is invalid \$AA_MEAS_P2_VALID[ax] = 1 ; Determining 2nd measuring point of axis The unlatched measuring point is stored in \$AA_MEAS_POINT2[ax].											
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		43.00.00			
Unit:		-		min:		max:		1			
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	X	
write:		X	X	X			X	X	X	X	7
Attributes:		Global				Search run		Link			
						not classified		not classified			

INT	\$AA_MEAS_P3_VALID				Unlatch 3rd measuring point of an axis				Cross. R.:		
Description: Variable for workpiece and tool measurement. Axial variable \$AA_MEAS_P3_VALID[ax] is used to unlatch the current axis position with reference to a selected coordinate system. Variable \$AC_MEAS_P3_COORD is used to select the coordinate system. Application: \$AA_MEAS_P3_VALID[ax] = 0 ; 3rd measuring point of axis is invalid \$AA_MEAS_P3_VALID[ax] = 1 ; Determining 3rd measuring point of axis The unlatched measuring point is stored in \$AA_MEAS_POINT3[ax].											
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		43.00.00			
Unit:		-		min:		max:		1			
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	X	
write:		X	X	X			X	X	X	X	7
Attributes:		Global				Search run		Link			
						not classified		not classified			

INT	\$AA_MEAS_P4_VALID				Unlatch 4th measuring point of an axis				Cross. R.:	
Description: Variable for workpiece and tool measurement. Axial variable \$AA_MEAS_P4_VALID[ax] is used to unlatch the current axis position with reference to a selected coordinate system. Variable \$AC_MEAS_P4_COORD is used to select the coordinate system. Application: \$AA_MEAS_P4_VALID[ax] = 0 ; 4th measuring point of axis is invalid \$AA_MEAS_P4_VALID[ax] = 1 ; Determining 4th measuring point of axis The unlatched measuring point is stored in \$AA_MEAS_POINT4[ax].										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				43.00.00	
Unit:	-	min:					max:	1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MEAS_POINT1				1. measuring point				Cross. R.:	
Description: Variable for workpiece and tool measurement. Axial variable \$AA_MEAS_POINT1[ax] is used to write the 1st measuring point for workpiece and tool measurement. The measuring point can be either written directly or unlatched with variables \$AC_MEAS_LATCH[0], \$AA_MEAS_P1_VALID[ax]. Application: \$AA_MEAS_POINT1[x] = \$AA_IW[x] \$AA_MEAS_POINT1[y] = \$AA_IW[y] \$AA_MEAS_POINT1[z] = \$AA_IW[z]										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				43.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_MEAS_POINT2				2. measuring point				Cross. R.:	
Description: Variable for workpiece and tool measurement. Axial variable \$AA_MEAS_POINT2[ax] is used to write the 2nd measuring point for workpiece and tool measurement. The measuring point can be either written directly or unlatched with variables \$AC_MEAS_LATCH[1], \$AA_MEAS_P2_VALID[ax]. Application: \$AA_MEAS_POINT2[x] = \$AA_IW[x] \$AA_MEAS_POINT2[y] = \$AA_IW[y] \$AA_MEAS_POINT2[z] = \$AA_IW[z]										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				43.00.00	
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MEAS_POINT3				3. measuring point				Cross. R.:	
Description: Variable for workpiece and tool measurement. Axial variable \$AA_MEAS_POINT3[ax] is used to write the 3rd measuring point for workpiece and tool measurement. The measuring point can be either written directly or unlatched with variables \$AC_MEAS_LATCH[2], \$AA_MEAS_P3_VALID[ax]. Application: \$AA_MEAS_POINT3[x] = \$AA_IW[x] \$AA_MEAS_POINT3[y] = \$AA_IW[y] \$AA_MEAS_POINT3[z] = \$AA_IW[z]										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				43.00.00	
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_MEAS_POINT4				4. measuring point				Cross. R.:	
Description: Variable for workpiece and tool measurement. Axial variable \$AA_MEAS_POINT4[ax] is used to write the 4th measuring point for workpiece and tool measurement. The measuring point can be either written directly or unlatched with variables \$AC_MEAS_LATCH[3], \$AA_MEAS_P4_VALID[ax]. Application: \$AA_MEAS_POINT4[x] = \$AA_IW[x] \$AA_MEAS_POINT4[y] = \$AA_IW[y] \$AA_MEAS_POINT4[z] = \$AA_IW[z]										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				43.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_MEAS_SP_VALID				Validity of position setpoint				Cross. R.:	
Description: Variable for workpiece and tool measurement. Axial variable \$AA_MEAS_SP_VALID[ax] is used to set the defined setpoint of an axis to valid or invalid. Application: \$AA_MEAS_SP_VALID[ax] = 0 ; Position setpoint of axis is invalid \$AA_MEAS_SP_VALID[ax] = 1 ; Position setpoint of axis is valid The position setpoint is stored in \$AA_MEAS_SETPOINT[ax]										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				43.00.00	
Unit:	-	min:				max:		1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X		
write:	X					X		X		7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_MEAS_SETPOINT					Position setpoint of an axis					Cross. R.:
Description:											
Variable for workpiece and tool measurement.											
Axial variable \$AA_MEAS_SETPOINT[ax] is used to define a position setpoint for an axis. This position setpoint is considered when calculating the workpiece position or the tool length.											
Application:											
\$AA_MEAS_SETPOINT[x] = 0.0											
\$AA_MEAS_SETPOINT[y] = 0.0											
\$AA_MEAS_SETPOINT[z] = 0.0											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	43.00.00				
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_MEAS_SETANGLE					Angle setpoint of an axis					Cross. R.:
Description:											
Variable for workpiece and tool measurement.											
Axial variable \$AA_MEAS_SETANGLE[ax] is used to define an angle setpoint for an axis. This angle setpoint is considered when calculating the workpiece position or the tool length.											
Application:											
\$AA_MEAS_SETANGLE[x] = 0.0											
\$AA_MEAS_SETANGLE[y] = 0.0											
\$AA_MEAS_SETANGLE[z] = 0.0											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	48.00.00				
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:	X					X		X		7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_OFF				Overlaid movement of an axis				Cross. R.:	
Description: Axial variable \$AA_OFF[ax] is used to overlay a movement for the programmed axis. The behavior of the overlaid movement can be configured with \$MA_AA_OFF_MODE.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:		X					X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_OFF_LIMIT				Limit value reached for axis offset				Cross. R.:	
Description: Axial variable \$AA_OFF_LIMIT[ax] is used to interrogate a limit value for the axis offset \$AA_OFF[ax]. The following values are possible: 0:Limit value not reached 1:Limit value reached in positive axis direction -1:Limit value reached in negative axis direction										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	-	min:	-1			max:	1			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_OFF_VAL				Integrated path of axis offset				Cross. R.:		
Description: Axial variable \$AA_OFF_VAL[ax] determines the integrated value of the overlaid movement for an axis. An overlaid movement can be canceled again by means of the negative value of this variable. e.g. \$AA_OFF[axis] = -\$AA_OFF_VAL[axis]											
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		20.00.00			
Unit:		-	min: DBL_MIN				max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:		Global Search run				Link					
		not classified				not classified					

DOUBLE	\$AC_RETPOINT				Repositioning point in Asub				Cross. R.:		
Description: \$AC_RETPOINT[X] \$AC_RETPOINT[] supplies the WCS position of an axis at which an ASUB has been started. The axis can then be repositioned at this point in the Asub. If an Asub is started immediately after a block search with calculation, \$AC_RETPOINT then supplies the collected search position. For a modulo axis \$AC_RETPOINT[] supplies the position as modulo converted. System variable \$AC_RPVALID[] can be used to check whether \$AC_RETPOINT[] is supplying a valid repositioning point within the current program context (see documentation for \$AC_RPVALID[]).											
Note about application in synchronized actions: The points generated by REPOS are supplied while the REPOS approach blocks are being processed. The current parameter settings for the REPOS operation (approach to interruption point, block start point, etc.) defined by G codes RMI, RMB, RME, RMN or VDI signal are also taken into account.											
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:		Lin.- /Angle pos.	min: DBL_MIN				max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:		Global Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_TOFF					Offset in tool direction			Cross. R.:	
Description:										
Variable \$AA_TOFF[geo axis] is used to overlay a movement in the corresponding tool direction. The behavior of the overlaid movement can be configured with \$MC_TOFF_MODE.										
Activation in the part program is performed using the TOFFON instruction.										
The TOFFOF instruction can be used to reset the offset values.										
The velocity for the offset can be defined with MD 21194 TOFF_VELO; the acceleration can be defined with MD21196 TOFF_ACCEL.										
The variable is only appropriate in conjunction with an active orientation transformation or an active toolholder.										
Axes:	Geometry axis					NCK Version:			50.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_TOFF_VAL					Integrated value of offset in TCS			Cross. R.:	
Description:										
Variable \$AA_TOFF_VAL[geo axis] determines the integrated value of the overlaid movement in the corresponding tool direction.										
The variable is only appropriate in conjunction with an active orientation transformation or an active toolholder.										
Axes:	Geometry axis					NCK Version:			50.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AA_TOFF_LIMIT				Limit value for offset in TCS reached				Cross. R.:	
Description: Axial variable \$AA_TOFF_LIMIT[ax] is used to interrogate a limit value for the offset in the tool direction (TCS) via \$AA_TOFF[geo axis]. The following values are possible: 0: Limit value not reached 1: Limit value reached in positive axis direction -1: Limit value reached in negative axis direction The limit values can be defined with SD 42970 TOFF_LIMIT. The variable is only appropriate in conjunction with an active orientation transformation or an active toolholder.										
Axes:	Geometry axis				NCK Version:				50.00.00	
Unit:	-	min:	-1			max:	1			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_TOFF_PREP_DIFF				Difference value of main run/preprocessing run in TCS				Cross. R.:	
Description: Variable \$AA_TOFF_PREP_DIFF[geo axis] determines the difference value of the overlaid movement in the corresponding tool direction between the main run and preprocessing run. The variable is only appropriate in conjunction with an active orientation transformation or an active toolholder.										
Axes:	Geometry axis				NCK Version:				50.00.00	
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_SOFTENDP				Software limit position, positive direction				Cross. R.:	
Description: \$AA_SOFTENDP[X] Current software limit position, positive direction										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_SOFTENDN				Software limit position, negative direction				Cross. R.:	
Description: \$AA_SOFTENDN[X] Software limit position, negative direction										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_DTBW				Distance from block start in WCS				Cross. R.:		
Description:											
Axial variable \$AA_DTBW[ax] determines the axial distance from the start of the block in the workpiece coordinate system for positioning and synchronized axes. The programmed position is the only factor used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00		
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X	X				X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_DTBB				Distance from block start in BCS				Cross. R.:		
Description:											
Axial variable \$AA_DTBB[ax] determines the axial distance from the start of the block in the basic coordinate system for positioning and synchronized axes. The programmed position is the only factor used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00		
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X	X				X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_DTEW				Distance from block end in WCS				Cross. R.:		
Description: Axial variable \$AA_DTEW[ax] determines the axial distance to the end of the block in the workpiece coordinate system for positioning and synchronized axes. The programmed position is the only factor used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00		
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X	X				X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_DTEB				Distance from block end in BCS				Cross. R.:		
Description: Axial variable \$AA_DTEB[ax] determines the axial distance to the end of the block in the basic coordinate system for positioning and synchronized axes. The programmed position is the only factor used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00		
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X	X				X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

DOUBLE	\$AA_DTEPW				Distance to go of a reciprocating axis in WCS				Cross. R.:	
Description: Axial variable \$AA_DTEPW[ax] determines the axial distance to go for the infeed reciprocation in the workpiece coordinate system.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_DTEPB				Distance to go of a reciprocating axis in BCS				Cross. R.:	
Description: Axial variable \$AA_DTEPB[ax] determines the axial distance to go for the infeed reciprocation in the basic coordinate system.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_OSCILL_REVERSE_POS1		Reciprocation reversal position 1				Cross. R.:			
Description:										
\$AA_OSCILL_REVERSE_POS1[X]										
Supplies current reversal position 1 for reciprocation.										
In synchronized actions, the value of setting data \$SA_OSCILL_REVERSE_POS1 is evaluated online.										
The variable can be accessed only from synchronized actions.										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:	06.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_OSCILL_REVERSE_POS2		Reciprocation reversal position 2				Cross. R.:			
Description:										
\$AA_OSCILL_REVERSE_POS2[X]										
Supplies current reversal position 2 for reciprocation.										
In synchronized actions, the value of setting data \$SA_OSCILL_REVERSE_POS2 is evaluated online.										
The variable can be accessed only from synchronized actions.										
Axes:	Geometry axis Channel axis Machine axis					NCK Version:	06.00.00			
Unit:	Lin. - /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_DELT				Stored axial distance to go after DDTG				Cross. R.:	
Description: \$AA_DELT[X] Stored axial distance to go in workpiece coordinate system after axial delete distance to go by a motion-synchronous action.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$P_FA				Programmed axial feedrate				Cross. R.:	
Description: \$P_FA[X] Last programmed axial feedrate										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_OVR					Axial override					Cross. R.:
Description:											
\$AA_OVR[<axis>]											
Axial override for motion-synchronous actions.											
Multiplicative override component, applied in addition to operator override, programmed override and transformational override.											
The value is limited to max. 200%. If a value of < 0.0 is entered, it is assumed to be 0 and alarm 14756 is output.											
\$AA_OVR[<axis>] must be rewritten in every Ipo cycle or else a value of 100% is applied.											
Variable \$AA_OVR[<spindle>] alters the spindle override.											
The variable can be accessed only from motion-synchronous actions.											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	06.00.00				
Unit:	-	min:				max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X					X	X	X		
write:		X					X		X	7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_PLC_OVR					Axial override from PLC					Cross. R.:
Description:											
\$AA_PLC_OVR[ax] supplies the axial override defined by the PLC.											
Axes:	Channel axis					NCK Version:	54.00.00				
Unit:	-	min:				max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X					X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_TOTAL_OVR					Overall axial override					Cross. R.:
Description:											
\$AA_TOTAL_OVR[ax] supplies the overall axial override (PLC_OVR*NC_OVR).											
Axes:	Channel axis					NCK Version:	54.00.00				
Unit:	-	min:				max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:		X					X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

DOUBLE	\$AA_VC				Additive axial feedrate override				Cross. R.:	
Description:										
\$AA_VC[X]										
Additive axial feedrate override for motion-synchronous actions.										
The override value must be rewritten in every lpo cycle or else a value of 0 is applied.										
A setting of 0 makes the override inoperative and is not applied to the override value.										
The total feedrate cannot be made negative by an override value.										
An upper limit is applied to ensure that the maximum axis velocities and acceleration rates cannot be exceeded.										
The calculation of other feed components is not affected by \$AA_VC.										
The override values defined by machine data: \$MN_OVR_FACTOR_LIMIT_BIN,										
\$MN_OVR_FACTOR_FEEDRATE[30],										
\$MN_OVR_FACTOR_AX_SPEED[30] and \$MN_OVR_FACTOR_SPIND_SPEED cannot										
be exceeded. The additive feedrate override is limited such that the resultant feedrate does not exceed the										
maximum override										
value of the programmed feedrate.										
The variable can be accessed only from synchronized actions.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:		X					X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_VACTB				Axis velocity in the BCS				Cross. R.:	
Description:										
Axial variable \$AA_VACTB[ax] determines the axis velocity in the basic coordinate system.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_VACTW				Axis velocity in the WCS				Cross. R.:	
Description: Axial variable \$AA_VACTW[ax] determines the axis velocity in the workpiece coordinate system.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_VACTM				Axis velocity in the MCS				Cross. R.:	
Description: Axial variable \$AA_VACTM[ax] determines the axis velocity on the setpoint side in the machine coordinate system. The variable also returns valid values for replacement and PLC axes.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$VA_VACTM				Axis velocity actual value in the MCS				Cross. R.:	
Description: Axial variable \$VA_VACTM[ax] determines the axis velocity actual value in the machine coordinate system. The variable supplies an undefined value if the encoder limit frequency is exceeded. When a spindle/axis disable is active, this variable returns the current velocity setpoint. If it is preferred to return the actual velocity in this situation, BIT3 in \$MA_MISC_FUNCTION_MASK must be set.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				13.00.00	
Unit:	Lin.- /angle speed.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_LOAD				Drive load				Cross. R.:	
Description: \$AA_LOAD[X] Drive load in % Only available for 611D and Profibus drives. On the Profibus, the value must be prepared explicitly by the drive and transported across the bus by variable telegram programming.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00	
Unit:	-	min:	-100				max:	100		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

DOUBLE	\$VA_LOAD					Drive load		Cross. R.:		
Description: \$VA_LOAD[X] Drive load in % Only available for 611D and Profibus drives. On the Profibus, the value must be prepared explicitly by the drive and transported across the bus by variable telegram programming.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		17.00.00		
Unit:	-	min:	-100				max:	100		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X			
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

DOUBLE	\$AA_TORQUE					Drive torque setpoint		Cross. R.:		
Description: \$AA_TORQUE[X] Drive torque setpoint in Nm or actual force in N (for 611D HLA only) Only available for 611D and Profibus drives. On the Profibus, the value must be prepared explicitly by the drive and transported across the bus by variable telegram programming.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		06.00.00		
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

1.1 List of system variables

DOUBLE	\$VA_TORQUE				Drive torque setpoint				Cross. R.:	
Description: \$VA_TORQUE[X] Drive torque setpoint in Nm or actual force in N (for 611D HLA only) Only available for 611D and Profibus drives. On the Profibus, the value must be prepared explicitly by the drive and transported across the bus by variable telegram programming.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				17.00.00	
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X			
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

DOUBLE	\$AA_POWER				Drive active power				Cross. R.:	
Description: \$AA_POWER[x] Drive active power in W Only available for 611D and Profibus drives. On the Profibus, the value must be prepared explicitly by the drive and transported across the bus by variable telegram programming.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				06.00.00	
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

DOUBLE	\$VA_POWER					Drive active power					Cross. R.:
Description: \$VA_POWER[x] Drive active power in W Only available for 611D and Profibus drives. On the Profibus, the value must be prepared explicitly by the drive and transported across the bus by variable telegram programming.											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		17.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X				
write:											
Attributes:	Global	Search run				Link					
		State				not classified					

DOUBLE	\$AA_CURR					Drive actual current					Cross. R.:
Description: \$AA_CURR[X] Actual current of axis or spindle in A Only available for 611D and Profibus drives. On the Profibus, the value must be prepared explicitly by the drive and transported across the bus by variable telegram programming.											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		06.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		State				not classified					

DOUBLE	\$VA_CURR					Drive actual current					Cross. R.:
Description: \$VA_CURR[X] Actual current of axis or spindle in A Only available for 611D and Profibus drives. On the Profibus, the value must be prepared explicitly by the drive and transported across the bus by variable telegram programming.											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		17.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X				
write:											
Attributes:	Global	Search run				Link					
		State				not classified					

1.1 List of system variables

DOUBLE	\$VA_DIST_TORQUE					Disturbing torque			Cross. R.:	
Description: \$VA_DIST_TORQUE[X] Normalized disturbing torque (disturbing torque/max. motor torque) = output signal of disturbance monitor on drive - only available on Profibus with Telegram 203										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		45.00.00		
Unit:	-	min:	-100			max:	100			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

DOUBLE	\$VA_VALVELIFT					Still to be defined			Cross. R.:	
Description: \$VA_VALVELIFT[X] Actual valve lift in mm (for 611D hydraulic module only)										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		17.00.00		
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

DOUBLE	\$VA_PRESSURE_A					Still to be defined			Cross. R.:	
Description: \$VA_PRESSURE_A[X] Pressure at A end of cylinder in bar (for 611D hydraulic module only)										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		17.00.00		
Unit:	-	min:				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

DOUBLE	\$VA_PRESSURE_B					Still to be defined	Cross. R.:			
Description: \$VA_PRESSURE_B[X] Pressure at B end of cylinder in bar (for 611D hydraulic module only)										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	17.00.00			
Unit:	-	min:				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		State				not classified				

INT	\$VA_DP_ACT_TEL[20]					Profibus actual telegram from drive to NC	Cross. R.:			
Description: \$VA_DP_ACT_TEL[b,a] b: Word index (16-bit access) in Profibus telegram a: Machine axes Actual value telegram contents - only available for Profibus. For details, please see telegram configuration in PROFIdrive or drive documentation										
Description of array limits: b: Word index in Profibus actual value telegram										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	50.00.00			
Unit:	-	min:				max:	65535			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AA_STAT					Axis status					Cross. R.:
Description: \$AA_STAT[<axis>] Axis status: 0: No axis status available 1: Traversing movement in progress 2: Axis has reached lpo end 3: Axis in position (exact stop coarse) 4: Axis in position (exact stop fine)											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	06.00.00				
Unit:	-	min:	0			max:	4				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
	X	not classified				not classified					

INT	\$AA_SINGLAX_STAT					Status of single axis					Cross. R.:
Description: \$AA_SINGLAX_STAT[X] Axis status: 0: Axis is not a single axis 1: Single axis in Reset 2: Single axis has ended 3: Single axis is interrupted 4: Single axis is active 5: Single axis alarm is active											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:	48.00.00				
Unit:	-	min:				max:	4				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

INI	\$AA_REF				Axis is homed				Cross. R.:		
Description: \$AA_REF[X] Axis status: 0: Axis is not homed 1: Axis is homed											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00				
Unit:	-	min:					max:	1			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X		X		
write:											
Attributes:	Global	Search run				Link					
	X	not classified				not classified					

INI	\$AA_TYP				Axis type				Cross. R.:		
Description: \$AA_TYP[<axis>] Axis type: 0: Axis in another channel 1: Program axis of own channel 2: Neutral axis 3: PLC axis 4: Oscillating axis 5: Neutral axis which is currently executing a JOG or homing motion 6: Following axis coupled via master value 7: Coupled motion following axis 8: Command axis 9: CompileCycles axis 10: Coupled slave axis (master-slave function) 11: Program axis which is currently executing a JOG or homing motion											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00				
Unit:	-	min:	0				max:	11			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

INT	\$AA_MASL_STAT				Master-slave coupling status				Cross. R.:		
Description:											
The current status of a master-slave coupling.											
Val. 0: Axis is not a slave axis or no coupling is active.											
Value > 0: Coupling is active, the relevant machine axis number of the master axis is supplied.											
\$AA_MASL_STAT[X]											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		42.00.00				
Unit:	-	min:					max:	MACHAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$P_SEARCH_MASLC				Master-slave coupling status changed				Cross. R.:		
Description:											
\$P_SEARCH_MASLC[axis identifier]											
The current status of a master-slave coupling has been changed during a block search.											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		43.00.00				
Unit:	-	min:					max:	1			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X					
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$P_SEARCH_MASLD				Master-slave position offset				Cross. R.:	
Description: \$P_SEARCH_MASLD[axis identifier] Positional offset between master and slave axes calculated during block search as coupling was closed.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		43.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_FXS				Still to be defined				Cross. R.:	
Description: \$AA_FXS[X] Status desired state "Travel to fixed stop" 0: Axis not at limit stop 1: Fixed stop has been successfully approached 2: Approach to fixed stop has failed 3: Selection of travel to fixed stop active 4: Fixed stop has been detected 5: Deselection of travel to fixed stop active										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	-	min:				max:	5			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X	X	X	7
Attributes:	Global	Search run				Link				
		According to part program				not classified				

1.1 List of system variables

INT	\$VA_FXS				Still to be defined				Cross. R.:	
Description: \$VA_FXS[X] Status actual state "Travel to fixed stop" 0: Axis not at limit stop 1: Fixed stop has been successfully approached 2: Approach to fixed stop has failed 3: Selection of travel to fixed stop active 4: Fixed stop has been detected 5: Deselection of travel to fixed stop active										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		44.00.00		
Unit:		-	min:			max:		5		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global Search run				Link				
		State				not classified				

INT	\$VA_FXS_INFO				Still to be defined				Cross. R.:	
Description: \$VA_FXS_INFO[X] Additional information with "Travel to fixed stop" if \$VA_FXS[]=2 0: No additional information available 1: No approach movement programmed 2: Programmed end position reached, motion completed 3: Abort by NC RESET (key reset) 4: Axis has exited fixed stop window 5: Torque reduction rejected by drive 6: PLC has cancelled enables										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		45.00.00		
Unit:		-	min:			max:		6		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X		
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

INT	\$VA_TORQUE_AT_LIMIT				Still to be defined				Cross. R.:		
Description: \$VA_TORQUE_AT_LIMIT[X] "Torque limit reached" status 0: Torque limit not yet reached 1: Torque limit reached In digital 611D systems, the drive returns a status signal indicating whether the programmed torque limit has been reached.											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		20.00.00				
Unit:	-	min:					max:	1			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$AA_FOC				Still to be defined				Cross. R.:		
Description: \$AA_FOC[X] Status desired state "ForceControl" 0: ForceControl not active 1: ForceControl active modally 2: ForceControl active non-modally											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		20.00.00				
Unit:	-	min:					max:	2			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X	X			X	X	X	X	7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

INT	\$VA_FOC				Still to be defined				Cross. R.:	
Description: \$VA_FOC[X] Status actual state "ForceControl" 0: ForceControl not active 1: ForceControl active modally 2: ForceControl active non-modally										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		44.00.00		
Unit:	-	min:				max:		2		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_COUP_ACT				Coupling type of a following axis/spindle				Cross. R.:	
Description: \$AA_COUP_ACT[C] C: following axis C or S2: following spindle 2 It is possible to determine whether an axis/spindle is being used by a coupling. The coupling type is returned when the coupling is active. The system variable must be read out for the following axis/spindle. Values: 0: Axis/spindle is not coupled with a leading spindle/leading axis 1,2,3: Axis is made to follow tangentially (TANG) 4: Synchronous spindle coupling (COUP) 8: Axis is made to follow (TRAIL) 16: Following axis in master value coupling (LEAD) 32: Following axis for electronic gear (ELG) 64: Axis is active in a gantry grouping 128,256,384: Axis is made to follow tangentially (TANG with optimization) If the axis/spindle is a following axis/spindle in several couplings, the total is returned as the value.										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00		
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
	X	not classified				not classified				

DOUBLE	\$AA_EG_SYNFA				Still to be defined				Cross. R.:	
Description: \$AA_EG_SYNFA[a] a: Following axis Synchronous position of following axis										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		16.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

STRING	\$P_EG_BC				Still to be defined				Cross. R.:	
Description: \$P_EG_BC[a] Block change criterion for EGONSYN, EGON, WAITC.										
Axes:	Geometry axis Channel axis Spindle				NCK Version:		16.00.00			
Unit:	-	min:				max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_EG_NUM_LA				Still to be defined				Cross. R.:	
Description: \$AA_EG_NUM_LA[a] a: Following axis Number of leading axes specified with EGDEF										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		16.00.00			
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$VA_EG_SYNCDIFF					Still to be defined					Cross. R.:
Description: \$VA_EG_SYNCDIFF[a] a: Following axis Synchronism deviation											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$VA_EG_SYNCDIFF_S					Still to be defined					Cross. R.:
Description: \$VA_EG_SYNCDIFF_S[a] a: Following axis Signed synchronism deviation											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		50.00.00			
Unit:	Lin.- /Angle pos.	min:	-DBL_MAX			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

AXIS	\$AA_EG_AX[20]				Still to be defined				Cross. R.:		
Description: \$AA_EG_AX[n,a] n: Index for leading axis a: Following axis Identifier for the nth leading axis											
Description of array limits: n: Index for leading axis (nth leading axis)											
Axes:	Geometry axis Channel axis Spindle				NCK Version:		18.00.00				
Unit:	-	min:					max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X					X		X			
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_LEAD_SP				Still to be defined				Cross. R.:		
Description: \$AA_LEAD_SP[LW] Simulated master value position											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00				
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X	X			X	X		X	7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

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DOUBLE	\$AA_LEAD_SV				Still to be defined				Cross. R.:	
Description: \$AA_LEAD_SV[LW] Simulated master value velocity										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00			
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_LEAD_P_TURN				Still to be defined				Cross. R.:	
Description: \$AA_LEAD_P_TURN[LW] Current master value positional component lost as a result of modulo reduction. The actual master value position (used internally by the control) is \$AA_LEAD_P[LW] + \$AA_LEAD_P_TURN[LW] If LW is a modulo axis, \$AA_LEAD_P_TURN is an integral multiple of \$MA_MODULO_RANGE. If LW is not a modulo axis, \$AA_LEAD_P_TURN is always 0. Example_1: \$MA_MODULO_RANGE[LW]=360 \$AA_LEAD_P[LW] =290 \$AA_LEAD_P_TURN[LW] =720 The actual master value position (used internally by the control) is 1010. Example_2: \$MA_MODULO_RANGE[LW]=360 \$AA_LEAD_P[LW] =290 \$AA_LEAD_P_TURN[LW] =-360 The actual master value position (used internally by the control) is -70.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_LEAD_P				Still to be defined				Cross. R.:	
Description: \$AA_LEAD_P[LW] Current master value position (modulo-reduced) If LW is a modulo axis, the following always applies: 0 <= \$AA_LEAD_P[LW] <= \$MA_MODULO_RANGE[LW]										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_LEAD_V				Still to be defined				Cross. R.:	
Description: \$AA_LEAD_V[LW] Current master value velocity										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00			
Unit:	Lin.- /angle speed.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AA_SYNC				Still to be defined				Cross. R.:	
Description: \$AA_SYNC[FA] Coupling status of following axis with master value coupling 0 => No synchronism 1 => Coarse synchronism 2 => Fine synchronism 3 => Coarse and fine synchronism										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		13.00.00		
Unit:		-		min:		max:		3		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

INT	\$AA_IN_SYNC				Still to be defined				Cross. R.:	
Description: \$AA_IN_SYNC[FA] Synchronization status of following axis with master value coupling and ELG 1 => Synchronization in progress, i.e. following axis is being synchronized with leading axis										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		48.00.00		
Unit:		-		min:		max:		1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X			
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

DOUBLE	\$P_COUP_OFFS				Programmed position offset				Cross. R.:	
Description: \$P_COUP_OFFS[S2] S2: spindle 2 or C: axis C Programmed position offset from synchronous spindle (following spindle) to leading spindle										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		46.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X				
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_COUP_OFFS				Position offset on setpoint side				Cross. R.:	
Description: \$AA_COUP_OFFS[S2] S2: spindle 2 or C: axis C Position offset from synchronous spindle (following spindle) to leading spindle on setpoint side										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$VA_COUP_OFFS				Position offset on actual value side				Cross. R.:	
Description: \$VA_COUP_OFFS[S2] S2: spindle 2 or C: axis C Position offset from synchronous spindle (following spindle) to leading spindle on actual value side										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:			06.00.00		
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$AA_SCTRACE				Still to be defined				Cross. R.:	
Description: \$AA_SCTRACE[X] = 1 Write: Activate IPO trigger for servo trace 0: No action !0: Activate trigger Read: Always 0 because trigger cannot be read back										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:			13.00.00		
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$VA_DPE					Power enable for machine axis			Cross. R.:	
Description: \$VA_DPE[X1] Status of power enable for a machine axis										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00		
Unit:	-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_ACC					Current axial acceleration value			Cross. R.:	
Description: \$AA_ACC Current acceleration value of axis with single-axis interpolation. \$AA_ACC = \$MA_MAX_AX_ACCEL * progr. acceleration override.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00		
Unit:	Lin.- /angle acc.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_ACC_PERCENT					Current acceleration value percentage			Cross. R.:	
Description: Variable \$AA_ACC_PERCENT supplies the current acceleration value of the axis for single-axis interpolation in percent.										
Axes:						NCK Version:		53.00.00		
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$PA_ACCLIMA					Still to be defined			Cross. R.:	
Description: \$PA_ACCLIMA Acceleration override set with ACCLIMA in preprocessing run										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		50.00.00		
Unit:	-	min:	1			max:	200			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$PA_VELOLIMA					Still to be defined			Cross. R.:	
Description: \$PA_VELOLIMA Velocity override set with VELOLIMA in preprocessing run										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		50.00.00		
Unit:	-	min:	1			max:	200			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$PA_JERKLIMA					Still to be defined			Cross. R.:	
Description: \$PA_JERKLIMA Jerk override set with JERKLIMA in preprocessing run										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		50.00.00		
Unit:	-	min:	1			max:	200			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_ACCLIMA					Still to be defined			Cross. R.:	
Description: \$AA_ACCLIMA Acceleration override set with ACCLIMA in main run										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		50.00.00		
Unit:	-	min:	1			max:	200			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_VELOLIMA					Still to be defined			Cross. R.:	
Description: \$AA_VELOLIMA Velocity override set with VELOLIMA in main run										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		50.00.00		
Unit:	-	min:	1			max:	200			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_JERKLIMA					Still to be defined			Cross. R.:	
Description: \$AA_JERKLIMA Jerk override set with JERKLIMA in main run										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		50.00.00		
Unit:	-	min:	1			max:	200			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$AA_MOTEND				Current axial end of motion criterion				Cross. R.:	
Description: \$AA_MOTEND Current end of motion criterion with single-axis interpolation 1 = End of motion with exact stop FINE 2 = End of motion with exact stop COARSE 3 = End of motion at end of interpolation 4 = Block change in braking ramp of axis motion 5 = Block change in braking ramp of axis motion with tolerance window for setpoint 6 = Block change in braking ramp of axis motion with tolerance window for actual value										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				16.00.00	
Unit:	-	min:	1				max:	6		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_SCPAR				Setpoint parameter set				Cross. R.:	
Description: \$AA_SCPAR Current setpoint parameter set										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				16.00.00	
Unit:	-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_ESR_STAT				ESR status of an axis				Cross. R.:	
Description: \$AA_ESR_STAT[X] Status of "Extended stop and retract", bit-coded: BIT0: Generator mode is activated BIT1: Retraction is activated BIT2: Extended stop is activated BIT3: DC-link undervoltage BIT4: Generator minimum speed										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		16.00.00		
Unit:		-	min:			max:		15		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

BOOL	\$AA_ESR_ENABLE				ESR enable				Cross. R.:	
Description: \$AA_ESR_ENABLE[X] = 1 Enabling of "Extended stop and retract"										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		16.00.00		
Unit:		-	min:			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global Search run				Link				
		not classified				not classified				

BOOL	\$AA_ESR_TRIGGER				Triggers a single-axis ESR				Cross. R.:	
Description: \$AA_ESR_TRIGGER[X] = 1 Activation of "NC-controlled ESR" for PLC-controlled axis (= single axis) X: PLC-controlled axis										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		48.00.00		
Unit:		-	min:			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:		X					X		X	7
Attributes:		Global Search run				Link				
		not classified				not classified				

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DOUBLE	\$AA_POLFA				Programmed retraction position for single axis				Cross. R.:	
Description: \$AA_POLFA[X] X: PLC-controlled axis (= single axis) Supplies the programmed retraction position of the PLC-controlled axis										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		51.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_POLFA_VALID				Status of the value of \$AA_POLFA				Cross. R.:	
Description: \$AA_POLFA_VALID[X] Supplies the current status of \$AA_POLFA[X] X: PLC-controlled axis (= single axis) Return values: 0: Retraction not programmed 1: Retraction programmed as position 2: Retraction programmed as distance										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		51.00.00			
Unit:	-	min:				max:	2			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_ALARM_STAT					Still to be defined			Cross. R.:	
Description: \$AA_ALARM_STAT (Selected) alarm reactions for synchronous actions (SYNFCT)										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		48.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$AN_AXCTSWA					Axis container rotation			Cross. R.:	
Description: Is axis container rotation active ? Example: EVERY \$AN_AXCTSWA[n] == TRUE DO M99 Read: TRUE: An axis container rotation is currently being executed on the axis container with axis container name n FALSE: Axis container rotation is not active.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00		
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AN_AXCTAS					Axis container current rotation			Cross. R.:	
Description: Axis container current rotation: The number of slots by which the axis container is currently being rotated is specified for the axis container with axis container name n. The value ranges from 0 to the maximum number of occupied slots in the axis container -1.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

BOOL	\$AC_AXCTSWA					Channel enable for axis container rotation				Cross. R.:	
Description:											
Enables the axis container rotation in the channel. TRUE: The channel has enabled rotation for the axis container with axis container name n and this rotation is not yet finished. FALSE: The axis container rotation is finished.											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		16.00.00			
Unit:	-	min:	FALSE				max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$VA_POSCTRL_MODE					Position controller mode				Cross. R.:	
Description:											
\$VA_POSCTRL_MODE[X] Position controller mode: 0 = Closed-loop position control 1 = Closed-loop speed control 2 = Stop 3 = Park 4 = Follow-up											
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		55.00.00			
Unit:	-	min:	0				max:	4			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		State				not classified					

BOOL	\$VA_SCE					Status of speed controller enable			Cross. R.:	
Description: \$VA_SCE[X] Status of speed controller enable										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		55.00.00		
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_TRAVEL_DIST					Total traverse path			Cross. R.:	
Description: Total traversing distance of axis in MCS in mm or degrees. The total traversing distance of the axis since the SRAM contents were last erased is added.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		56.00.00		
Unit:	Lin.- /Angle pos.	min:	0.0			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

DOUBLE	\$AA_TRAVEL_TIME					Total traversing time of axis			Cross. R.:	
Description: Total traversing time of axis in MCS in seconds. The total traversing time of the axis since the SRAM contents were last erased is added.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		56.00.00		
Unit:	s	min:	0.0			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

1.1 List of system variables

DOUBLE	\$AA_TRAVEL_COUNT		Number of traversing operations				Cross. R.:			
Description: Number of traversing operations of axis in MCS. The total number of traversing operations since the SRAM contents were last erased is stored.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00			
Unit:	-	min:	0.0				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

DOUBLE	\$AA_TRAVEL_DIST_HS		Total traversing distance at high velocity				Cross. R.:			
Description: Total traversing distance of axis in MCS in mm or degrees at high velocity, i.e. at a velocity of $\geq 80\%$ of the maximum axis velocity. This value is stored in the SRAM.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00			
Unit:	Lin.- /Angle pos.	min:	0.0				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

DOUBLE	\$AA_TRAVEL_TIME_HS		Total traversing time of axis at high velocity				Cross. R.:			
Description: Total traversing time of axis in seconds at high velocity in MCS, i.e. at a velocity of $\geq 80\%$ of the maximum axis velocity. This value is stored in the SRAM.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00			
Unit:	s	min:	0.0				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

DOUBLE	\$AA_TRAVEL_COUNT_HS				No. of traversing operations at high velocity				Cross. R.:	
Description: Number of traversing operations of axis in MCS at high velocity, i.e. at a velocity of >= 80% of the maximum axis velocity. This value is stored in the SRAM.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00			
Unit:	-	min:	0.0			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

DOUBLE	\$AA_JERK_TOT				Total axial jerk				Cross. R.:	
Description: Total axial jerk in m/s^3. The total jerk applied to the axis is added up and stored in the SRAM.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00			
Unit:	Lin.- /angle jerk	min:	0.0			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

DOUBLE	\$AA_JERK_TIME				Total traversing time of axis with jerk				Cross. R.:	
Description: Total traversing time of axis in seconds in MCS with jerk. The total time period for which the axis traverses with jerk is added up and stored in the SRAM.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00			
Unit:	s	min:	0.0			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

1.1 List of system variables

DOUBLE	\$AA_JERK_COUNT					Number of traversing operations with jerk			Cross. R.:	
Description: Number of traversing operations executed by axis in MCS with jerk. This value is stored in the SRAM.										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		56.00.00		
Unit:	-	min:	0.0			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		According to part program				not classified				

BOOL	\$AC_RPVALID					Repos position valid			Cross. R.:	
Description: \$AC_RPVALID[X] \$AC_RPVALID[axis identifier] returns TRUE if a valid Repos position, which can be interrogated with \$AC_RETPOINT[axis identifier], is available for this axis. Valid Repos positions are generally available while system and user Asubs are being processed. However, this is not the case in the following situations: - The Asub activates a modified radius when tool radius compensation is active. \$AC_RPVALID then returns FALSE for geometry axes while the Asub is running. The newly calculated Repos positions only become available with the approach blocks generated by the REPOS command. - The end position of the axis was last specified by the main run (FC18, synchronized actions, reciprocation, transfer from another channel after axis replacement).										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:		51.06.00		
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$VA_SYNCDIFF				Synchronism deviation between actual values				Cross. R.:		
Description: \$VA_SYNCDIFF[FA] FA: Following axis/following spindle Deviation in synchronism between actual values for LEAD, TRAIL, ELG and COUP. The deviation in synchronism between actual values is the deviation in distance between the servo actual position of the following axis/following spindle and a point calculated (according to the coupling rule) from the servo actual position of the leading axis/leading spindle. $\$VA_SYNCDIFF[FA] = \$VA_IM[FA] - K(\$VA_IM[LA])$ K: Coupling rule LA: Leading axis/leading spindle											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00				
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

DOUBLE	\$AA_SYNCDIFF				Synchronism deviation between setpoints				Cross. R.:		
Description: \$AA_SYNCDIFF[FA] FA: Following axis/following spindle Deviation in synchronism between setpoints for LEAD, TRAIL, ELG and COUP. The deviation in synchronism between setpoints is the deviation in distance between the setpoint position of the following axis/following spindle and a point calculated (according to the coupling rule) from the setpoint position of the leading axis/leading spindle. $\$AA_SYNCDIFF[FA] = \$AA_IM[FA] - K(\$AA_IM[LA])$ K: Coupling rule LA: Leading axis/leading spindle											
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00				
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

1.1 List of system variables

INT	\$VA_SYNCDIFF_STAT					Status of synchronism deviation between actual values			Cross. R.:	
Description: VA_SYNCDIFF_STAT[FA] FA: Following axis/following spindle Status of synchronism deviation between actual values: -4: Reserved -3: No valid value in \$VA_SYNCDIFF, tangential control (not TANG(... "P")) -2: No valid value in \$VA_SYNCDIFF, master value coupling and simulated MV -1: No valid value in \$VA_SYNCDIFF 0: No valid value in \$VA_SYNCDIFF, coupling not active 1: Valid value in \$VA_SYNCDIFF										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00		
Unit:		-	min: -4			max:		1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

INT	\$AA_SYNCDIFF_STAT					Status synchron. dev. between setpoints			Cross. R.:	
Description: \$AA_SYNCDIFF_STAT[FA] FA: Following axis/following spindle Status of synchronism deviation between setpoints: -4: No valid value in \$AA_SYNCDIFF, coupled motion from part program -3: Reserved -2: Reserved -1: No valid value in \$AA_SYNCDIFF 0: No valid value in \$AA_SYNCDIFF, coupling not active 1: Valid value in \$AA_SYNCDIFF										
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		56.00.00		
Unit:		-	min: -4			max:		1		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_OSCILL_BREAK_POS1				Reciprocation interruption position 1				Cross. R.:	
Description: \$AA_OSCILL_BREAK_POS1[<axis>] The current approach to reversal position 1 is finished at this position or the last approach to reversal position 1 was finished at this position (reversal position 2 currently being approached). \$AA_OSCILL_BREAK_POS1[<axis>] is not equal to \$AA_OSCILL_REVERSE_POS1[<axis>] if the reciprocation motion was interrupted by an external signal (PLC). The variable can be accessed only from synchronized actions.										
Axes:	Geometry axis Channel axis Machine axis				NCK Version:				57.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_OSCILL_BREAK_POS2				Reciprocation interruption position 2				Cross. R.:	
Description: \$AA_OSCILL_BREAK_POS2[<axis>] The current approach to reversal position 2 is finished at this position or the last approach to reversal position 2 was finished at this position (reversal position 1 currently being approached). \$AA_OSCILL_BREAK_POS2[<axis>] is not equal to \$AA_OSCILL_REVERSE_POS2[<axis>] if the reciprocation motion was interrupted by an external signal (PLC). The variable can be accessed only from synchronized actions.										
Axes:	Geometry axis Channel axis Machine axis				NCK Version:				57.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X					X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_BCS_OFFSET				Total axis offsets				Cross. R.:	
Description: Axial variable \$AA_BCS_OFFSET[ax] is used to determine the total axis offsets for an axis. The total consists of the handwheel (DRF) offset, the overlaid movement (\$AA_OFF[ax]) and the external work offset. This offset is included in the BCS. The MCS is displaced in relation to the BCS according to the offset.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				58.00.00	
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_CHANNO				Axis in the channel				Cross. R.:	
Description: This variable returns the number of the channel in which the axis is being interpolated. If value 0 is output, the axis could not be assigned to a channel.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				59.00.00	
Unit:	-	min:	0				max:	10		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
	X	not classified				not classified				

DOUBLE	\$AA_IW_CORR				Actual PCS-Position of one axis incl. overlay rates				Cross. R.:	
Description: The axial variable \$AA_IW_CORR[ax] calculates the actual interpolator position of the part coordinate system (PCS) for the specified axis. The position corresponds to the value of the interpolator for the actual interpolation cycle. The PCS-Value contains any axial overlay rate (DRF, \$AA_OFF, external Frame, etc.).										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				59.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_IEN_CORR				Actual FCS-Position of one axis incl. overlay rates				Cross. R.:	
Description: The axial variable \$AA_IEN_CORR[ax] calculates the actual interpolator position of the adjustable coordinate system (ACS) for the specified axis. See also \$AA_IW_CORR[ax]. The ACS-Value contains any axial overlay rate (DRF, \$AA_OFF, external Frame, etc.).										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				59.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_IBN_CORR				Actual FCS-Position of one axis incl. overlay rates				Cross. R.:	
Description: The axial variable \$AA_IBN_CORR[ax] calculates the actual interpolator position of the foot coordinate system (FCS) for the specified axis. See also \$AA_IW_CORR[ax]. The FCS-Value contains any axial overlay rate (DRF, \$AA_OFF, external Frame, etc.).										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				59.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_IB_CORR				Actual BCS-Position of one axis incl. overlay rates				Cross. R.:	
Description: The axial variable \$AA_IB_CORR[ax] calculates the actual interpolator position of the base coordinate system (BCS) for the specified axis. See also \$AA_IW_CORR[ax]. The BCS-Value contains any axial overlay rate (DRF, \$AA_OFF, external Frame, etc.).										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:			59.00.00		
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$AA_TYPE				Axis type				Cross. R.:	
Description: \$AA_TYPE[<axis>] Axis type: 0: Type is not ascertainable 1: NC-Program axis 2: Neutral axis 3: PLC axis 4: Oscillating axis 5: Neutral axis which is currently executing a JOG or homing motion 6: Following axis coupled via master value 7: Coupled motion following axis 8: Command axis 9: CompileCycles axis 10: Coupled slave axis (master-slave function) 11: Program axis which is currently executing a JOG or homing motion										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:			59.00.00		
Unit:	-	min:	0			max:	11			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
	X	not classified				not classified				

DOUBLE	\$AA_DTSW				Distance from start of motion in PCS				Cross. R.:	
Description:										
Axial variable \$AA_DTSW[ax] determines the axial distance (with algebraic sign) from the start of motion in the workpiece coordinate system for positioning and synchronized axes. The programmed position is the only factor used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				59.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_DTSB				Distance from start of motion in BCS				Cross. R.:	
Description:										
Axial variable \$AA_DTSB[ax] determines the axial distance (with algebraic sign) from the start of motion in the basic coordinate system for positioning and synchronized axes. The programmed position is the only factor used to calculate the distance. If the axis is a coupled axis, the position component derived from the axis coupling is not considered.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				59.00.00	
Unit:	Lin.- /Angle pos.	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X	X				X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_COUP_CORR				Following spindle: Compensation value f. synch. spindle coupling				Cross. R.:	
Description:										
<p>\$AA_COUP_CORR[Sn] with spindle Sn (n: spindle number), example S2: spindle 2 or C: axis C The variable serves to execute the functionality "Correcting deviation of synchronism" and provides the compensation value for the position offset of the synchronized spindle coupling. For the duration (MD 30455 MISC_FUNCTION_MASK, bit 7) of the activation of the VDI interface signal DB31...,DBX31.6 'Correct synchronism' for the following spindle with active coupling, the actual values of this spindle are compared with the setpoint values. The difference is the compensation value which can be read with system variable \$AA_COUP_CORR. If the compensation value is known, this value can be written directly into the system variable, too. The VDI interface signal DB31...,DBX31.6 must not be activated in this case! In the coupling module, the variable \$AA_COUP_CORR is considered and results in a correction of the setpoint values. The compensation value is deleted when switching on the synchronized spindle coupling for the relevant following spindle with COUPON(..) or COUPONC(..) as well as in the case of NC RESET, reference point approach or zero mark synchronization. The system variable returns the value 'zero'. Depending on the application, the compensation value can also be deleted at an earlier point in time by describing the the variables with the value '0'.</p>										
Axes:	Channel axis Machine axis Spindle				NCK Version:		60.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

INT	\$AA_AXCHANGE_TYP		exchange axistype				Cross. R.:				
Description:											
\$AA_AXCHANGE_TYP[<Axis>] Type of axis regarding axis interchange 0: Axis assigned to NC program 1: Axis assigned to PLC, or active as command or reciprocating axis 2: Other channel has right to interpolate 3: Neutral axis 4: Neutral axis controlled by PLC 5: Other channel has right to interpolate, axis requested for NC program 6: Other channel has right to interpolate, axis requested as neutral axis 7: Axis is PLC axis or active as command or reciprocating axis, axis requested for NC program 8: Axis is PLC axis or active as command or reciprocating axis, axis requested as neutral axis.											
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		61.00.00			
Unit:		-		min: 0		max:		8			
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X						X		X	
write:											
Attributes:		Global				Search run		Link			
						not classified		not classified			

INT	\$AA_AXCHANGE_STAT		exchange axis state				Cross. R.:				
Description:											
\$AA_AXCHANGE_STAT[<Axis>] Axis status regarding axis interchange: 0: Axis can be interchanged 1: Axis is assigned to the channel, but can become the PLC, command or reciprocating axis 2: Axis cannot be interchanged											
Axes:		Geometry axis Channel axis Machine axis Spindle				NCK Version:		61.00.00			
Unit:		-		min: 0		max:		2			
		Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:		X						X		X	
write:											
Attributes:		Global				Search run		Link			
						not classified		not classified			

1.1 List of system variables

INT	\$AA_INPOS_STAT					State of the programmed position			Cross. R.:	
Description: \$AA_INPOS_STAT[<Axis>] determines the status for a programmed position (see also VDI interface 'Spindle in position', 'Indexing axis in position'). The following values are possible: 0: No status available (axis / spindle outside the programmed position) 1: Awaiting traversing movement 2: Position reached via setpoint 3: Position reached via 'Exact stop coarse' 4: Position reached via 'Exact stop fine'										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:			61.00.00	
Unit:	-	min:	0			max:	4			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
	X	not classified				not classified				

INT	\$AA_EG_TYPE					Still to be defined			Cross. R.:	
Description: \$AA_EG_TYPE[a,b] a: Following axis b: Leading axis Type of coupling for leading axis b 0: Actual value coupling 1: Setpoint value coupling										
Axes:	Geometry axis Channel axis Machine axis Spindle					NCK Version:			18.00.00	
Unit:	-	min:				max:	1			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_EG_NUMERA				Still to be defined				Cross. R.:	
Description: \$AA_EG_NUMERA[a,b] a: Following axis b: Leading axis Numerator of coupling factor for leading axis b										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		18.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$AA_EG_DENOM				Still to be defined				Cross. R.:	
Description: \$AA_EG_DENOM[a,b] a: Following axis b: Leading axis Denominator of coupling factor for leading axis b										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		18.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

DOUBLE	\$AA_EG_SYN				Still to be defined				Cross. R.:	
Description: \$AA_EG_SYN[a,b] a: Following axis b: Leading axis Synchronous position of leading axis b										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		18.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$AA_EG_ACTIVE				Still to be defined				Cross. R.:	
Description: \$AA_EG_ACTIVE[a,b] a: Following axis b: Leading axis Coupling for leading axis b is active, i.e. switched on										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		18.00.00			
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1.26 Safety Integrated

INT	\$A_STOPESI					Stop E active			Cross. R.:	
Description: \$A_STOPESI Current Safety Integrated Stop E for any axis: Val. 0: No Stop E Value not 0: For one of the axes, a Stop E is currently active										
Axes:					NCK Version:			48.00.00		
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$A_INSE[SF_MAXNUM_DIG_EXT_I NBITS]					External NCK SPL input signal			Cross. R.:	
Description: \$A_INSE[n] n = bit number (1...64) External NCK SPL input signal NCK SPL interface for SPL control signal I/O interface logic										
Description of array limits: n: Number of input 1 - ...										
Axes:					NCK Version:			10.00.00		
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$A_INSED[SF_MAXNUM_DIG_EXT_INWORDS]					External NCK SPL input signals (32-bit)		Cross. R.:		
Description: \$A_INSED[n] n = doubleword number (1,2) External NCK SPL input signals (32-bit) NCK SPL interface for SPL control signal I/O interface logic										
Description of array limits: n: Number of input word 1 - ...										
Axes:					NCK Version:		10.00.00			
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$A_INSEP[SF_MAXNUM_DIG_EXT_INBITS]					External PLC SPL input signal		Cross. R.:		
Description: \$A_INSEP[n] n = bit number (1...64) Image of an external PLC SPL input signal PLC SPL interface for SPL control signal I/O interface logic										
Readable only during the SPL start-up phase										
Description of array limits: n: Number of input 1 - ...										
Axes:					NCK Version:		10.00.00			
Unit:		-	min:	FALSE			max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$A_INSEPD[SF_MAXNUM_DIG_EXT_INWORDS]					External PLC SPL input signals (32-bit)					Cross. R.:	
Description: \$A_INSEPD[n] n = doubleword number (1,2) Image of external PLC SPL input signals (32-bit) PLC SPL interface for SPL control signal I/O interface logic Readable only during the SPL start-up phase												
Description of array limits: n: Number of input word 0 - ...												
Axes:					NCK Version:					10.00.00		
Unit:		-		min: INT_MIN			max:		INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X	X			X	X	X	X			
write:												
Attributes:	Global	Search run				Link						
		not classified				not classified						

BOOL	\$A_OUTSE[SF_MAXNUM_DIG_EXT_OUTBITS]					External NCK SPL output signal					Cross. R.:	
Description: \$A_OUTSE[n] n = bit number (1..64) External NCK SPL output signal NCK SPL interface for SPL status signal I/O interface logic Can be written only from SPL (SAFE.SPF program)												
Description of array limits: n: Number of output 1 - ...												
Axes:					NCK Version:					10.00.00		
Unit:		-		min: FALSE			max:		TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X	X			X	X	X	X			
write:	X	X	X			X	X		X	7		
Attributes:	Global	Search run				Link						
		not classified				not classified						

1.1 List of system variables

INT	\$A_OUTSED[SF_MAXNUM_DIG_EX T_OUTWORDS]					External NCK SPL output signals (32-bit)					Cross. R.:	
Description: \$A_OUTSED[n] n = doubleword number (1,2) External NCK SPL output signals (32-bit) NCK SPL interface for SPL status signal I/O interface logic Can be written only from SPL (SAFE.SPF program)												
Description of array limits: n: Number of output word 1 - ...												
Axes:					NCK Version:					10.00.00		
Unit:		-		min: INT_MIN			max:		INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X	X			X	X	X	X			
write:	X	X	X			X	X		X	7		
Attributes:	Global	Search run				Link						
		not classified				not classified						

BOOL	\$A_OUTSEP[SF_MAXNUM_DIG_EX T_OUTBITS]					External PLC SPL output signal					Cross. R.:	
Description: \$A_OUTSEP[n] n = bit number (1...64) Image of an external PLC SPL output signal PLC SPL interface for SPL status signal I/O interface logic Readable only during the SPL start-up phase												
Description of array limits: n: Number of output 1 - ...												
Axes:					NCK Version:					10.00.00		
Unit:		-		min: FALSE			max:		TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X	X			X	X	X	X			
write:												
Attributes:	Global	Search run				Link						
		not classified				not classified						

INT	\$A_OUTSEPD[SF_MAXNUM_DIG_EXT_OUTWORDS]					External PLC SPL output signals (32-bit)	Cross. R.:			
Description: \$A_OUTSEPD[n] n = doubleword number (1,2) Image of external PLC SPL output signals (32-bit) PLC SPL interface for SPL status signal I/O interface logic Readable only during the SPL start-up phase										
Description of array limits: n: Number of output word 0 - ...										
Axes:					NCK Version:		10.00.00			
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$A_INSI[SF_MAXNUM_DIG_INT_IN_BITS]					Internal NCK SPL input signal	Cross. R.:			
Description: \$A_INSI[n] n = bit number (1..64) Internal NCK SPL input signal Interface to the status signals of the axial NCK monitoring channels										
Description of array limits: n: Number of input 1 - ...										
Axes:					NCK Version:		10.00.00			
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$A_INSID[SF_MAXNUM_DIG_INT_I NWORDS]					Internal NCK SPL input signals (32-bit)		Cross. R.:			
Description: \$A_INSID[n] n = doubleword number (1,2) Internal NCK SPL input signals (32-bit) Interface to the status signals of the axial NCK monitoring channels											
Description of array limits: n: Number of input word 1 - ...											
Axes:					NCK Version:		10.00.00				
Unit:		-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

BOOL	\$A_INSIP[SF_MAXNUM_DIG_INT_I NBITS]					Internal PLC SPL input signal		Cross. R.:			
Description: \$A_INSIP[n] n = bit number (1...64) Image of an internal PLC SPL input signal Interface to the status signals of the axial 611D monitoring channels											
Readable only during the SPL start-up phase											
Description of array limits: n: Number of input 1 - ...											
Axes:					NCK Version:		10.00.00				
Unit:		-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$A_INSIPD[SF_MAXNUM_DIG_INT_INWORDS]					Internal PLC SPL input signals (32-bit)	Cross. R.:			
Description: \$A_INSIPD[n] n = doubleword number (1,2) Image of internal PLC SPL input signals (32-bit) Interface to the status signals of the axial 611D monitoring channels Readable only during the SPL start-up phase										
Description of array limits: n: Number of input word 1 - ...										
Axes:						NCK Version:	10.00.00			
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$A_OUTSI[SF_MAXNUM_DIG_INT_OUTBITS]					Internal NCK SPL output signal	Cross. R.:			
Description: \$A_OUTSI[n] n = bit number (1..64) Internal NCK SPL output signal Interface to the control signals of the axial NCK monitoring channels Can be written only from SPL (SAFE.SPF program)										
Description of array limits: n: Number of output 1 - ...										
Axes:						NCK Version:	10.00.00			
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$A_OUTSID[SF_MAXNUM_DIG_INT_OUTWORDS]					Internal NCK SPL output signals (32-bit)	Cross. R.:			
Description: \$A_OUTSID[n] n = doubleword number (1,2) Internal NCK SPL output signals (32-bit) Interface to the control signals of the axial NCK monitoring channels Can be written only from SPL (SAFE.SPF program)										
Description of array limits: n: Number of output word 1 - ...										
Axes:						NCK Version:	10.00.00			
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$A_OUTSIP[SF_MAXNUM_DIG_INT_OUTBITS]					Internal PLC SPL output signal	Cross. R.:			
Description: \$A_OUTSIP[n] n = bit number (1..64) Image of an internal PLC SPL output signal Interface to the control signals of the 611D monitoring channels Readable only during the SPL start-up phase										
Description of array limits: n: Number of output 1 - ...										
Axes:						NCK Version:	10.00.00			
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$A_OUTSIPD[SF_MAXNUM_DIG_INT_OUTWORDS]					Internal PLC SPL output signals (32-bit)	Cross. R.:			
Description: \$A_OUTSIPD[n] n = doubleword number (1,2) Image of internal PLC SPL output signals (32-bit) Interface to the control signals of the 611D monitoring channels Readable only during the SPL start-up phase										
Description of array limits: n: Number of output word 1 - ...										
Axes:						NCK Version:	10.00.00			
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

BOOL	\$A_MARKERSI[SF_MAXNUM_MARKER]					NCK SPL flags	Cross. R.:			
Description: \$A_MARKERSI[n] n = bit number (1..64) NCK SPL flags Can be written only from SPL (SAFE.SPF program)										
Description of array limits: n: Number of flag 1 - ...										
Axes:						NCK Version:	10.00.00			
Unit:	-	min:	FALSE			max:	TRUE			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$A_MARKERSID[SF_MAXNUM_MARKER_WORDS]					NCK SPL flag word					Cross. R.:
Description: \$A_MARKERSID[n] n = doubleword number (1,2) NCK SPL flag word (32-bit) Can be written only from SPL (SAFE.SPF program)											
Description of array limits: n: Number of flag word 1 - ...											
Axes:					NCK Version:					13.09.00	
Unit:	-	min:	INT_MIN			max:	INT_MAX				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X	X			X	X		X	7	
Attributes:	Global	Search run				Link					
		not classified				not classified					

BOOL	\$A_MARKERSIP[SF_MAXNUM_MARKER]					PLC SPL flags					Cross. R.:
Description: \$A_MARKERSIP[n] n = bit number (1...64) Image of a PLC SPL flag Readable only during the SPL start-up phase											
Description of array limits: n: Number of flag 1 - ...											
Axes:					NCK Version:					10.00.00	
Unit:	-	min:	FALSE			max:	TRUE				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:	Global	Search run				Link					
		not classified				not classified					

INT	\$A_MARKERSIPD[SF_MAXNUM_MARKER_WORDS]					PLC SPL flag word	Cross. R.:			
Description: \$A_MARKERSIPD[n] n = doubleword number (1,2) Image of a PLC SPL flag word (32-bit) Readable only during the SPL start-up phase										
Description of array limits: n: Number of flag word 1 - ...										
Axes:					NCK Version:		13.09.00			
Unit:	-	min:	INT_MIN			max:	INT_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

DOUBLE	\$A_TIMERSI[SF_MAXNUM_TIMER]					SPL timers	Cross. R.:			
Description: \$A_TIMERSI[n] n=timer number (1...16) SPL timers Unit in seconds The time is counted internally in multiples of the interpolation cycle. Incrementation of the time variable is started by value assignment \$A_TIMERSI[n]=<start value> Incrementation of a time variable is stopped through assignment of a negative value \$A_TIMERSI[n]=-1 The current timer count can be read while the time variable is running or stopped. When the time variable is stopped by assigning -1, the last count value remains stored in the variable and can continue to be read. The timers are not stopped by a channel/mode group reset.										
Description of array limits: n: Number of timer 1 - ...										
Axes:					NCK Version:		10.00.00			
Unit:	-	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$A_STATSID				SPL status signals				Cross. R.:	
Description: \$A_STATSID										
Status of data cross-check between NCK and PLC (SPL DCC) if the value does not equal zero, an error has occurred in the SPL DCC.										
Meaning										
Bit 0 ... 27: DCC error in input/output signals or flags										
Bit 28:DCC error "SPL protection status" (\$MN_PREVENT_SYNACT_LOCK status not equal to DB18.DBX36.0)										
Bit 29:Time error during communication between NCK and PLC (all ext. NCK SPL outputs are set to zero in 5 sec. and the PLC switches to Stop)										
Bit 30: Stop signaled from PLC to NCK										
Axes:						NCK Version:		13.03.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:		Global				Search run		Link		
		not classified				not classified				

BOOL	\$A_CMDSI[SF_MAXNUM_CMD_MARKER]				SPL DCC control signals				Cross. R.:	
Description: \$A_CMDSI[n] n = bit number (1..0.16)										
Control word for data cross-check between NCK and PLC (SPL DCC). n = 1: Increase time for signal change monitoring to 10 s.										
Can be written only from SPL (SAFE.SPF program)										
Description of array limits: n: Number of control signal for SPL data cross-check										
Axes:						NCK Version:		13.03.00		
Unit:		-	min:		FALSE			max:		TRUE
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:	X	X	X			X	X		X	7
Attributes:		Global				Search run		Link		
		not classified				not classified				

INT	\$A_LEVELSID					SPL DCC level		Cross. R.:			
Description: \$A_LEVELSID											
Displays the fill level for signal change monitoring during data cross-check between NCK and PLC SPL (SPL DCC). Specifies the number of signals currently tagged for cross-checking. The value is already zero if an SPL signal has different levels on the NCK and PLC but the allowed discrepancy time for the signals (2 sec) has not yet expired.											
Axes:							NCK Version:		13.03.00		
Unit:		-	min:		INT_MIN			max:		INT_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:		Global Search run					Link				
		not classified					not classified				

INT	\$A_XFAULTSI					DCC status		Cross. R.:			
Description: \$A_XFAULTSI											
Information on Stop F for a Safety axis: Bit 0 = 1: An actual value error has been detected by the data cross-check between NCK and 611D for any Safety axis. Bit 1 = 1: Any error on any axis has been detected by the data cross-check between NCK and 611D and the waiting time before triggering of Stop B on that axis is running or has expired (\$MA_SAFE_STOP_SWITCH_TIME_F).											
Axes:							NCK Version:		45.00.00		
Unit:		-	min:		0			max:		3	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X		X		
write:											
Attributes:		Global Search run					Link				
		not classified					not classified				

1.1 List of system variables

BOOL	\$A_PLCSIIN[SF_MAXNUM_PLCIN_ MARKER]					SPL signal from PLC to NCK		Cross. R.:			
Description: \$A_PLCSIIN[n] n = bit number (1..0.32) Single-channel signals from PLC SPL (DB18) to NCK SPL. Application: \$A_MARKERSI[1] = \$A_PLCSIIN[1] ; Signal from PLC-SPL											
Description of array limits: n: Number of signal 1 - ... from PLC to NCK											
Axes:							NCK Version:		45.00.00		
Unit:		-	min:		FALSE			max:		TRUE	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:											
Attributes:		Global		Search run			Link				
		not classified			not classified						

BOOL	\$A_PLCSIOUT[SF_MAXNUM_PLCOUT_MARKER]					SPL signal from NCK to PLC		Cross. R.:			
Description: \$A_PLCSIOUT[n] n = bit number (1..0.32) Single-channel signals from NCK SPL to PLC SPL (DB18). Application: \$A_PLCSIOUT[1] = \$A_MARKERSI[1] ; Signal to PLC-SPL Can be written only from SPL (SAFE.SPF program)											
Description of array limits: n: Number of signal 1 - ... from NCK to PLC											
Axes:							NCK Version:		45.00.00		
Unit:		-	min:		FALSE			max:		TRUE	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X	X			X	X	X	X		
write:	X	X	X			X	X		X	7	
Attributes:		Global		Search run			Link				
		not classified			not classified						

DOUBLE	\$VA_IS				Safe actual position NCK				Cross. R.:	
Description: \$VA_IS[X] X = axis identifier Safe actual position for NCK monitoring channel										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:		06.00.00			
Unit:	Lin.- /Angle pos.	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

INT	\$VA_STOPSI				Stop by Safety Integrated				Cross. R.:	
Description: \$VA_STOPSI[X] X = axis identifier Current Safety Integrated Stop for the relevant axis Value Meaning -1No Stop 0Stop A 1Stop B 2Stop C 3Stop D 4Stop E 5Stop F 10Test Stop NC 11Test ext. pulse suppression										
Axes:	Geometry axis Channel axis Machine axis				NCK Version:		48.00.00			
Unit:	-	min:				max:	7			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X	X			X	X	X	X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1 List of system variables

INT	\$VA_XFAULTSI				Stop F by data cross-check error active				Cross. R.:	
Description: \$VA_XFAULTSI[X] X = axis identifier										
Information about Safety Integrated Stop F for this axis: Bit 0 set: An actual value error has been detected by the data cross-check between NCK and 611D. Bit 1 set: Any error has been detected by the data cross-check between NCK and 611D and the waiting time before triggering of Stop B (\$MA_SAFE_STOP_SWITCH_TIME_F) is running or has expired.										
Axes:	Geometry axis Channel axis Machine axis Spindle				NCK Version:				45.00.00	
Unit:	-	min:	0				max:	3		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X		X	
write:										
Attributes:	Global	Search run				Link				
		not classified				not classified				

1.1.27 User specific system variables

DOUBLE	SYG_RM[n]				Synact Real parameters for GUD2 block				Cross. R.:	
Description: SYG_RM[n] Synact Real parameters in GUD2 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Real is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_REAL[1])										
Axes:					NCK Version:				57.00.00	
Unit:	-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:	Global	Search run				Link				
		According to part program				No restriction				

INT	SYG_IM[n]					Synact Integer parameters for GUD2 block			Cross. R.:	
Description: SYG_IM[n] Synact Integer parameters in GUD2 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_INT[1])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

BOOL	SYG_BM[n]					Synact Boolean parameters for GUD2 block			Cross. R.:	
Description: SYG_BM[n] Synact Boolean parameters in GUD2 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Boolean parameters is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_BOOL[1])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: FALSE			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

1.1 List of system variables

AXIS	SYG_AM[n]				Synact Axis parameters for GUD2 block				Cross. R.:	
Description: SYG_AM[n] Synact axis parameters in GUD2 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD axis is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_AXIS[1])										
Axes:						NCK Version:		61.00.00		
Unit:		-		min:		max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

CHAR	SYG_CM[n]				Synact char parameters for GUD2 block				Cross. R.:	
Description: SYG_CM[n] Synact char parameters in GUD2 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD char is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_CHAR[1])										
Axes:						NCK Version:		61.00.00		
Unit:		-		min:		max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

STRING	SYG_SM[n,MD_MAXNUM_STRLEN _SYNACT]					Synact string parameters for GUD2 block					Cross. R.:	
Description: SYG_SM[n] Synact string parameters in GUD2 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.												
Description of array limits: The maximum number of SynactGUD string is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_STRING[1]) to be defined												
Axes:							NCK Version:		61.00.00			
Unit:		-	min:					max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:		Global					Search run					Link
		According to part program					No restriction					

DOUBLE	SYG_RU[n]					Synact Real parameters for UGUD block					Cross. R.:	
Description: SYG_RU[n] Synact Real parameters in UGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least three GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.												
Description of array limits: The maximum number of SynactGUD Real is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_REAL[2])												
Axes:							NCK Version:		57.00.00			
Unit:		-	min:		DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:		Global					Search run					Link
		According to part program					No restriction					

1.1 List of system variables

INT	SYG_IU[n]					Synact Integer parameters for UGUD block			Cross. R.:	
Description: SYG_IU[n] Synact Integer parameters in UGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least three GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_INT[2])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

BOOL	SYG_BU[n]					Synact Boolean parameters for UGUD block			Cross. R.:	
Description: SYG_BU[n] Synact Boolean parameters in UGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least three GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Boolean parameters is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_BOOL[2])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: FALSE			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

AXIS	SYG_AU[n]				Synact Axis parameters for UGUD block				Cross. R.:	
Description: SYG_AU[n] Synact Axis parameters in UGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least three GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Real is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_AXIS[2])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

CHAR	SYG_CU[n]				Synact char parameters for UGUD block				Cross. R.:	
Description: SYG_CU[n] Synact char parameters in UGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least three GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Char is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_CHAR[2])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

1.1 List of system variables

STRING	SYG_SU[n,MD_MAXNUM_STRLEN _SYNACT]					Synact string parameters for UGUD block					Cross. R.:	
Description:												
SYG_SU[n] Synact string parameters in UGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least three GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.												
Description of array limits:												
The maximum number of SynactGUD String is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_STRING[2]) to be defined												
Axes:							NCK Version:		61.00.00			
Unit:		-	min:					max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:		Global					Search run					Link
		According to part program					No restriction					

DOUBLE	SYG_R4[n]					Synact Real parameters for GUD4 block					Cross. R.:	
Description:												
SYG_R4[n] Synact Real parameters in GUD4 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.												
Description of array limits:												
The maximum number of SynactGUD Real is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_REAL[3])												
Axes:							NCK Version:		57.00.00			
Unit:		-	min:		DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:		Global					Search run					Link
		According to part program					No restriction					

INT	SYG_I4[n]					Synact Integer parameters for GUD4 block			Cross. R.:	
Description: SYG_I4[n] Synact Integer parameters in GUD4 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_INT[3])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

BOOL	SYG_B4[n]					Synact Boolean parameters for GUD4 block			Cross. R.:	
Description: SYG_B4[n] Synact Boolean parameters in GUD4 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Boolean parameters is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_BOOL[3])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: FALSE			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

1.1 List of system variables

AXIS	SYG_A4[n]				Synact Axis parameters for GUD4 block				Cross. R.:	
Description: SYG_A4[n] Synact Real parameters in GUD4 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Axis is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_AXIS[3])										
Axes:						NCK Version:		61.00.00		
Unit:		-		min:				max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

CHAR	SYG_C4[n]				Synact Char parameters for GUD4 block				Cross. R.:	
Description: SYG_C4[n] Synact Char parameters in GUD4 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Char is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_CHAR[3])										
Axes:						NCK Version:		61.00.00		
Unit:		-		min:				max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

STRING	SYG_S4[n,MD_MAXNUM_STRLEN_				Synact String parameters for GUD4 block				Cross. R.:	
SYNACT] Description: SYG_S4[n] Synact String parameters in GUD4 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least four GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES. Description of array limits: The maximum number of SynactGUD String is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_STRING[3]) to be defined										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
		According to part program				No restriction				

DOUBLE	SYG_R5[n]				Synact Real parameters for GUD5 block				Cross. R.:	
Description: SYG_R5[n] Synact Real parameters in GUD5 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least five GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES. Description of array limits: The maximum number of SynactGUD Real is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_REAL[4])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min:		DBL_MIN			max:		DBL_MAX
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
		According to part program				No restriction				

1.1 List of system variables

INT	SYG_I5[n]					Synact Integer parameters for GUD5 block			Cross. R.:	
Description: SYG_I5[n] Synact Integer parameters in GUD5 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least five GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_REAL[4])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

BOOL	SYG_B5[n]					Synact Boolean parameters for GUD5 block			Cross. R.:	
Description: SYG_B5[n] Synact Boolean parameters in GUD5 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least five GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Boolean parameters is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_BOOL[4])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: FALSE			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

AXIS	SYG_A5[n]				Synact Axis parameters for GUD5 block				Cross. R.:	
Description: SYG_A5[n] Synact Axis parameters in GUD5 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least five GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Axis is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_AXIS[4])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

CHAR	SYG_C5[n]				Synact Char parameters for GUD5 block				Cross. R.:	
Description: SYG_C5[n] Synact Char parameters in GUD5 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least five GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Char is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_CHAR[4])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

1.1 List of system variables

STRING	SYG_S5[n,MD_MAXNUM_STRLEN_					Synact String parameters for GUD5					Cross. R.:	
	SYNACT]					block						
Description:												
SYG_S5[n] Synact String parameters in GUD5 block.												
A protection level can be assigned to the parameters with REDEF.												
In order to create the parameters, at least five												
GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.												
Description of array limits:												
The maximum number of SynactGUD String is defined in machine data												
(\$MN_MM_NUM_SYNACT_GUD_STRING[4])												
to be defined												
Axes:						NCK Version:	61.00.00					
Unit:	-	min:				max:						
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:	Global	Search run				Link						
		According to part program				No restriction						

DOUBLE	SYG_R6[n]					Synact Real parameters for GUD6					Cross. R.:	
						block						
Description:												
SYG_R6[n] Synact Real parameters in GUD6 block.												
A protection level can be assigned to the parameters with REDEF.												
In order to create the parameters, at least six												
GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.												
Description of array limits:												
The maximum number of SynactGUD Real is defined in machine data												
(\$MN_MM_NUM_SYNACT_GUD_REAL[5])												
Axes:						NCK Version:	57.00.00					
Unit:	-	min:	DBL_MIN			max:	DBL_MAX					
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:	Global	Search run				Link						
		According to part program				No restriction						

INT	SYG_I6[n]					Synact Integer parameters for GUD6 block			Cross. R.:	
Description: SYG_I6[n] Synact Integer parameters in GUD6 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least six GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_REAL[5])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

BOOL	SYG_B6[n]					Synact Boolean parameters for GUD6 block			Cross. R.:	
Description: SYG_B6[n] Synact Boolean parameters in GUD6 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least six GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Boolean parameters is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_BOOL[5])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: FALSE			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

1.1 List of system variables

AXIS	SYG_A6[n]				Synact Axis parameters for GUD6 block				Cross. R.:	
Description: SYG_A6[n] Synact Axis parameters in GUD6 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least six GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Axis is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_AXIS[5])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
		According to part program				No restriction				

CHAR	SYG_C6[n]				Synact Char parameters for GUD6 block				Cross. R.:	
Description: SYG_C6[n] Synact Char parameters in GUD6 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least six GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Char is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_CHAR[5])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
		According to part program				No restriction				

STRING	SYG_S6[n,MD_MAXNUM_STRLEN_					Synact String parameters for GUD6 block		Cross. R.:			
SYNACT]											
Description: SYG_S6[n] Synact String parameters in GUD6 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least six GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.											
Description of array limits: The maximum number of SynactGUD String is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_STRING[5]) to be defined											
Axes:						NCK Version:		61.00.00			
Unit:		-	min:					max:			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X				X	X	X	X		
write:	X	X				X	X	X	X	7	
Attributes:		Global				Search run		Link			
						According to part program		No restriction			

DOUBLE	SYG_R7[n]					Synact Real parameters for GUD7 block		Cross. R.:			
Description: SYG_R7[n] Synact Real parameters in GUD6 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least seven GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.											
Description of array limits: The maximum number of SynactGUD Real is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_REAL[6])											
Axes:						NCK Version:		57.00.00			
Unit:		-	min:	DBL_MIN				max:	DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X				X	X	X	X		
write:	X	X				X	X	X	X	7	
Attributes:		Global				Search run		Link			
						According to part program		No restriction			

1.1 List of system variables

INT	SYG_I7[n]					Synact Integer parameters for GUD7 block			Cross. R.:	
Description: SYG_I7[n] Synact Integer parameters in GUD6 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least seven GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_INT[6])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min:	INT_MIN			max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

BOOL	SYG_B7[n]					Synact Boolean parameters for GUD7 block			Cross. R.:	
Description: SYG_B7[n] Synact Boolean parameters in GUD7 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least seven GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Boolean parameters is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_BOOL[6])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min:	FALSE			max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

AXIS	SYG_A7[n]				Synact Axis parameters for GUD7 block				Cross. R.:	
Description: SYG_A7[n] Synact Axis parameters in GUD6 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least seven GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Axis is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_AXIS[6])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

CHAR	SYG_C7[n]				Synact Char parameters for GUD7 block				Cross. R.:	
Description: SYG_C7[n] Synact Char parameters in GUD6 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least seven GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Char is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_CHAR[6])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

1.1 List of system variables

STRING	SYG_S7[n,MD_MAXNUM_STRLEN_					Synact String parameters for GUD7					Cross. R.:	
	SYNACT]					block						
Description:												
SYG_S7[n] Synact String parameters in GUD6 block.												
A protection level can be assigned to the parameters with REDEF.												
In order to create the parameters, at least seven												
GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.												
Description of array limits:												
The maximum number of SynactGUD String is defined in machine data												
(\$MN_MM_NUM_SYNACT_GUD_STRING[6])												
to be defined												
Axes:							NCK Version:		61.00.00			
Unit:		-	min:			max:						
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:		Global					Search run					Link
		According to part program					No restriction					

DOUBLE	SYG_R8[n]					Synact Real parameters for GUD8					Cross. R.:	
						block						
Description:												
SYG_R8[n] Synact Real parameters in GUD8 block.												
A protection level can be assigned to the parameters with REDEF.												
In order to create the parameters, at least eight												
GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.												
Description of array limits:												
The maximum number of SynactGUD Real is defined in machine data												
(\$MN_MM_NUM_SYNACT_GUD_REAL[7])												
Axes:							NCK Version:		57.00.00			
Unit:		-	min:			max:						
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:		Global					Search run					Link
		According to part program					No restriction					

INT	SYG_I8[n]					Synact Integer parameters for GUD8 block			Cross. R.:	
Description: SYG_I8[n] Synact Integer parameters in GUD8 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least eight GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_INT[7])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

BOOL	SYG_B8[n]					Synact Boolean parameters for GUD8 block			Cross. R.:	
Description: SYG_B8[n] Synact Boolean parameters in GUD8 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least eight GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_BOOL[7])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: FALSE			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

1.1 List of system variables

AXIS	SYG_A8[n]				Synact Axis parameters for GUD8 block				Cross. R.:	
Description: SYG_A8[n] Synact Axis parameters in GUD8 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least eight GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Axis is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_AXIS[7])										
Axes:						NCK Version:		61.00.00		
Unit:		-		min:				max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

CHAR	SYG_C8[n]				Synact Char parameters for GUD8 block				Cross. R.:	
Description: SYG_C8[n] Synact Char parameters in GUD8 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least eight GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Char is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_CHAR[7])										
Axes:						NCK Version:		61.00.00		
Unit:		-		min:				max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

STRING	SYG_S8[n,MD_MAXNUM_STRLEN_				Synact String parameters for GUD8 block				Cross. R.:	
SYNACT]										
Description: SYG_S8[n] Synact String parameters in GUD8 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least eight GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD String is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_STRING[7]) to be defined										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:	Global	Search run				Link				
		According to part program				No restriction				

DOUBLE	SYG_R9[n]				Synact Real parameters for GUD9 block				Cross. R.:	
Description: SYG_R9[n] Synact Real parameters in GUD9 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least nine GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Real is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_REAL[8])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min:	DBL_MIN				max:	DBL_MAX	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:	Global	Search run				Link				
		According to part program				No restriction				

1.1 List of system variables

INT	SYG_I9[n]					Synact Integer parameters for GUD9 block			Cross. R.:	
Description: SYG_I9[n] Synact Integer parameters in GUD9 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least nine GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_INT[8])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: INT_MIN			max:		INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

BOOL	SYG_B9[n]					Synact Boolean parameters for GUD9 block			Cross. R.:	
Description: SYG_B9[n] Synact Boolean parameters in GUD9 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least nine GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Boolean parameters is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_BOOL[8])										
Axes:						NCK Version:		57.00.00		
Unit:		-	min: FALSE			max:		TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes: Global		Search run				Link				
		According to part program				No restriction				

AXIS	SYG_A9[n]				Synact Axis parameters for GUD9 block				Cross. R.:	
Description: SYG_A9[n] Synact Axis parameters in GUD9 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least nine GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Axis is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_AXIS[8])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

CHAR	SYG_C9[n]				Synact Char parameters for GUD9 block				Cross. R.:	
Description: SYG_C9[n] Synact Char parameters in GUD9 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least nine GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Char is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_CHAR[8])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

1.1 List of system variables

STRING	SYG_S9[n,MD_MAXNUM_STRLEN_					Synact String parameters for GUD9 block					Cross. R.:	
SYNACT] Description: SYG_S9[n] Synact String parameters in GUD9 block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least nine GUD blocks must be activated with MD \$MN_MM_NUM_GUD_MODULES. Description of array limits: The maximum number of SynactGUD String is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_STRING[8]) to be defined												
Axes:							NCK Version:		61.00.00			
Unit:		-	min:			max:						
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:		Global					Search run					Link
		According to part program					No restriction					

DOUBLE	SYG_RS[n]					Synact Real parameters for SGUD block					Cross. R.:	
Description: SYG_RS[n] Synchronization Real parameters in SGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least one GUD block must be activated with MD \$MN_MM_NUM_GUD_MODULES. Description of array limits: The maximum number of SynactGUD Real is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_REAL[0])												
Axes:							NCK Version:		57.00.00			
Unit:		-	min:			max:			DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.		
read:	X	X				X	X	X	X			
write:	X	X				X	X	X	X	7		
Attributes:		Global					Search run					Link
		According to part program					No restriction					

INT	SYG_IS[n]				Synact Integer parameters for SGUD block				Cross. R.:		
Description: SYG_IS[n] Synact Integer parameters in SGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least one GUD block must be activated with MD \$MN_MM_NUM_GUD_MODULES.											
Description of array limits: The maximum number of SynactGUD Integers is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_INT[0])											
Axes:						NCK Version:		57.00.00			
Unit:		-	min:	INT_MIN				max:	INT_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X				X	X	X	X		
write:	X	X				X	X	X	X	7	
Attributes:		Global				Search run		Link			
						According to part program		No restriction			

BOOL	SYG_BS[n]				Synact Boolean parameters for SGUD block				Cross. R.:		
Description: SYG_BS[n] Synact Boolean parameters in SGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least one GUD block must be activated with MD \$MN_MM_NUM_GUD_MODULES.											
Description of array limits: The maximum number of SynactGUD Boolean parameters is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_BOOL[0])											
Axes:						NCK Version:		57.00.00			
Unit:		-	min:	FALSE				max:	TRUE		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.	
read:	X	X				X	X	X	X		
write:	X	X				X	X	X	X	7	
Attributes:		Global				Search run		Link			
						According to part program		No restriction			

1.1 List of system variables

AXIS	SYG_AS[n]					Synact axis parameters for SGUD block			Cross. R.:	
Description: SYG_AS[n] Synchronization axis parameters in SGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least one GUD block must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD Axis is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_AXIS[0])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
		According to part program				No restriction				

CHAR	SYG_CS[n]					Synact char parameters for SGUD block			Cross. R.:	
Description: SYG_CS[n] Synchronization Char parameters in SGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least one GUD block must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD char is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_CHAR[0])										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:			max:				
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
		According to part program				No restriction				

STRING	SYG_SS[n,MD_MAXNUM_STRLEN_SYNACT]					Synact string parameters for SGUD block		Cross. R.:		
Description: SYG_SS[n] Synchronization string parameters in SGUD block. A protection level can be assigned to the parameters with REDEF. In order to create the parameters, at least one GUD block must be activated with MD \$MN_MM_NUM_GUD_MODULES.										
Description of array limits: The maximum number of SynactGUD String is defined in machine data (\$MN_MM_NUM_SYNACT_GUD_STRING[0]) to be defined										
Axes:						NCK Version:		61.00.00		
Unit:		-	min:					max:		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X	X				X	X	X	X	
write:	X	X				X	X	X	X	7
Attributes:		Global				Search run		Link		
						According to part program		No restriction		

1.1.28 Kinematic chain

STRING	\$NK_NAME[n,MAX_STRINGLENGT H]					Name of chain element		Cross. R.:		
Description: \$NK_NAME[n] Name of the nth element of a kinematic chain. The maximum possible number of chain elements is set in MD \$MN_MM_MAX_NUM_KIN_CHAIN_ELEMENTS.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM. max. string length										
Axes:						NCK Version:		58.00.00		
Unit:		-	min:	-				max:	-	
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global				Search run		Link		
						not classified		No restriction		

1.1 List of system variables

STRING	\$NK_NEXT[n,MAX_STRINGLENGT H]				Name of next chain element			Cross. R.:		
Description: \$NK_NEXT[n] Name of next chain element. An empty string "" means the end of the chain.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM. max. string length										
Axes:						NCK Version:		58.00.00		
Unit:		-		min:		-		max:		-
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global				Search run		Link		
		not classified				No restriction				

STRING	\$NK_NEXTP[n,MAX_STRINGLENG TH]				Name of a further next chain element			Cross. R.:		
Description: \$NK_NAMEP[n] Name of a further next chain element. This is needed for chain branches which occur in the case of parallel kinematic sequences. An empty string "" means that no further chain element exists.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM. max. string length										
Axes:						NCK Version:		58.00.00		
Unit:		-		min:		-		max:		-
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global				Search run		Link		
		not classified				No restriction				

STRING	\$NK_INSERT[n,MAX_STRINGLENGTH]					Name of a chain to be inserted		Cross. R.:		
Description: \$NK_INSERT[n] Name of a chain to be inserted. A chain or chain element inserted with \$NK_INSERT[n] takes effect at the start of the element which contains it. Work offsets and rotations defined in an inserted chain element apply to the current element and all subsequent elements of the chain.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM. max. string length										
Axes:						NCK Version:		58.00.00		
Unit:	-	min:	-			max:	-			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$NK_OFF[n,3]					Offset component		Cross. R.:		
Description: \$NK_OFF[n, i] Offset component i (0<=i<=2) of the nth element of a kinematic chain.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM. Index of the 3 components (0 <= i <= 2).										
Axes:						NCK Version:		58.00.00		
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$NK_RPY[n,3]					RPY angle		Cross. R.:		
Description: \$NK_RPY[n, i] RPY angle i (0<=i<=2) of the nth element of a kinematic chain.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM. Index of the 3 components (0 <= i <= 2).										
Axes:						NCK Version:		58.00.00		
Unit:	Degrees	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

1.1 List of system variables

STRING	\$NK_AXIS[n,MAX_STRINGLENGTH]					Axis name, frame name			Cross. R.:	
Description: \$NK_AXIS[n,i] Axis or frame name. the axis is described in detail in \$NK_AXINDEX. The null string is allowed for this variable. In this case, the entire data block describes a constant chain element.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM. max. string length										
Axes:							NCK Version:		58.00.00	
Unit:		-		min:		-		max:		-
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global					Search run		Link	
							not classified		No restriction	

INT	\$NK_AXINDEX[n]					Axis name, frame name			Cross. R.:	
Description: \$NK_AXIS[n] Defines how the string in the variable \$NK_AXIS is to be interpreted. If this index is 0, the string defines a frame which describes the change in the chain element. If the index is greater than 0, the string designates an axis name and the index itself designates the number of the channel in which the axis is defined. If the axis name is a machine axis name, the index can contain any value greater than zero. For example, \$NK_AXIS[1, 1] = "X" defines that the 1st chain element is moved by the 1st channel axis X. \$NK_AXIS[1] = "FRAME1" and \$NK_INDEX = 0 defines that the 1st element of the chain is moved by frame "FRAME1". Frame "FRAME1" has to be provided by the active transformation.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM.										
Axes:							NCK Version:		58.00.00	
Unit:		-		min:		-		max:		-
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global					Search run		Link	
							not classified		No restriction	

DOUBLE	\$NK_DIR[n,3]					Axis direction			Cross. R.:	
Description: \$NK_DIR[n, i] Component i of the axis direction vector (0<=i<=2) of the nth element of a kinematic chain.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM. Index of the 3 components (0 <= i <= 2).										
Axes:					NCK Version:			58.00.00		
Unit:		-	min: DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global Search run				Link				
		not classified				No restriction				

DOUBLE	\$NK_A_OFF[n]					Axis offset			Cross. R.:	
Description: \$NK_A_OFF[n] Specifies the position of the axis at the point defined by \$NK_OFF. This value is redundant because a kinematic chain can always be defined such that the offset is zero with suitable settings in \$NK_OFF and \$NK_RPY.										
Description of array limits: The maximum number of elements of kinematic chains is set in MD \$MN_MM_MAXNUM_KIN_CHAIN_ELEM.										
Axes:					NCK Version:			58.00.00		
Unit:		inch	min: DBL_MIN			max:		DBL_MAX		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global Search run				Link				
		not classified				No restriction				

1.1 List of system variables

1.1.29 Protection area elements

STRING	\$NP_NAME[n,MAX_STRINGLENGT H]					Name of protection zone element			Cross. R.:	
Description: \$NP_NAME[n] Name of protection zone element n.										
Description of array limits: The maximum number of elements in protection zones is defined by MD \$MN_MM_MAXNUM_AREA_ELEM. max. string length										
Axes:					NCK Version:			58.00.00		
Unit:		min:		-		max:		-		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global			Search run			Link		
		not classified			No restriction					

STRING	\$NP_NEXT[n,MAX_STRINGLENGT H]					Name of next protection zone element			Cross. R.:	
Description: \$NP_NEXT[n] Name of next protection zone element.										
Description of array limits: The maximum number of elements in protection zones is defined by MD \$MN_MM_MAXNUM_PROT_AREA_ELEM. max. string length										
Axes:					NCK Version:			58.00.00		
Unit:		min:		-		max:		-		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global			Search run			Link		
		not classified			No restriction					

STRING	\$NP_ADD[n,MAX_STRINGLENGTH]					Name of protection zone element			Cross. R.:	
Description: \$NP_ADD[n] Name of protection element to be added to the current protection zone.										
Description of array limits: The maximum number of elements in protection zones is defined by MD \$MN_MM_MAXNUM_PROT_AREA_ELEM. max. string length										
Axes:					NCK Version:			58.00.00		
Unit:		min:		-		max:		-		
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:		Global			Search run			Link		
		not classified			No restriction					

STRING	\$NP_CHAIN[n,MAX_STRINGLENGT H]					Assignment to a kin. chain		Cross. R.:		
Description: \$NP_CHAIN[n] Assignment to a kinematic chain. \$NP_CHAIN[n] can contain the name of a point in a kinematic chain at which the protection zone is fixed. In a complete protection zone definition, only one element of \$NP_CHAIN[n] may contain an entry not equal to the null string.										
Description of array limits: The maximum number of elements in protection zones is defined by MD \$MN_MM_MAXNUM_PROT_AREA_ELEM. max. string length										
Axes:						NCK Version:		58.00.00		
Unit:		-		min:		-		max:		-
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes: Global		Search run				Link				
		not classified				No restriction				

STRING	\$NP_TYPE[n,MAX_STRINGLENGT H]					Type of elementary body		Cross. R.:		
Description: \$NP_TYPE[n] Type of elementary body. The following elementary bodies are available: 1. BOX (L, B, H): box parallel to the axis with a corner at the zero point and a further corner at X=L, Y=B, Z=H. 2. SPHERE (R): sphere at the zero point with radius R. 3. CYLINDER (H, R): cylinder with radius R and height H, longitudinal axis parallel to the Z axis and center point of the base circle at the zero point. 4. CONE (H, R): straight cone with base circle radius R and height H, longitudinal axis parallel to the Z axis, cone tip at Z=H and center point of the base circle at the zero point. 5. CONE_TR (H, R, r): straight cone trunk with base circle radius R, height H and top circle radius r, longitudinal axis parallel to the Z axis and center point of the base circle at the zero point.										
Description of array limits: The maximum number of elements in protection zones is defined by MD \$MN_MM_MAXNUM_AREA_ELEM. max. string length										
Axes:						NCK Version:		58.00.00		
Unit:		-		min:		-		max:		-
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes: Global		Search run				Link				
		not classified				No restriction				

1.1 List of system variables

DOUBLE	\$NP_PARA[n,3]					Parameters for describing the type				Cross. R.:
Description: \$NP_PARA[n, i] Parameters for describing the type of an elementary body. A maximum of 3 parameters are required for the types of elementary body described under \$NP_TYP.										
Description of array limits: The maximum number of elements in protection zones is defined by MD \$MN_MM_MAXNUM_AREA_ELEM. The maximum number of parameters is 3.										
Axes:						NCK Version:	58.00.00			
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$NP_OFF[n,3]					Offset component				Cross. R.:
Description: \$NP_OFF[n, i] Component i (0<=i<=2) of the offset vector of protection zone element n.										
Description of array limits: The maximum number of elements in protection zones is defined by MD \$MN_MM_MAXNUM_AREA_ELEM. The 2nd index i designates the coordinate axis (0 <= i <= 2).										
Axes:						NCK Version:	58.00.00			
Unit:	inch	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

DOUBLE	\$NP_RPY[n,3]					RPY angle				Cross. R.:
Description: \$NP_RPY[n, i] RPY angle i (0 <= i <= 2) of protection zone element n.										
Description of array limits: The maximum number of elements in protection zones is defined by MD \$MN_MM_MAXNUM_AREA_ELEM. The 2nd index i designates the RPY angle (0 <= i <= 2).										
Axes:						NCK Version:	58.00.00			
Unit:	Degrees	min:	DBL_MIN			max:	DBL_MAX			
	Prep	Main run	PR-Stop	MR-Sync		PP	SA	OPI	OEM	Acc. R.
read:	X					X		X	X	
write:	X					X		X	X	7
Attributes:	Global	Search run				Link				
		not classified				No restriction				

References

A

An overview of publications which is updated each month and shows the languages available is provided on the Internet at:
<http://www.siemens.com/motioncontrol>
via „Support“, „Technical documentation“, „Overview of publications“.



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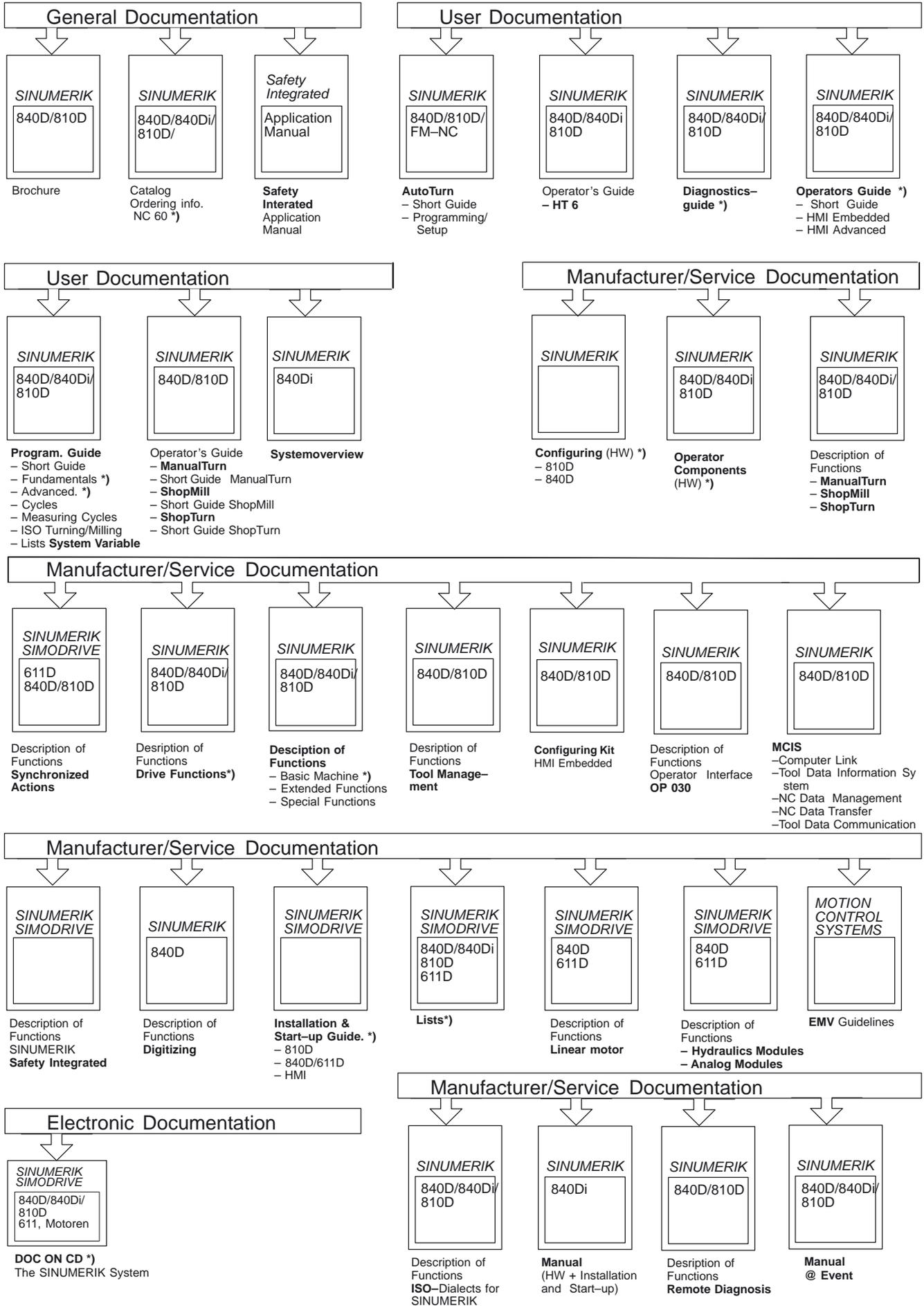
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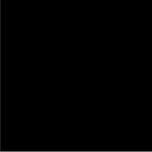
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